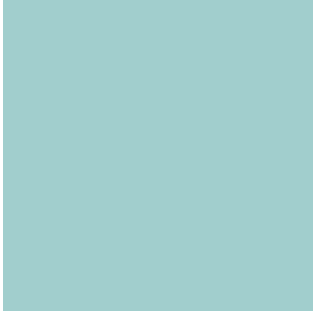




LS-DYNA in Ansys Workbench

- Case study of ROPS and FOPS simulation

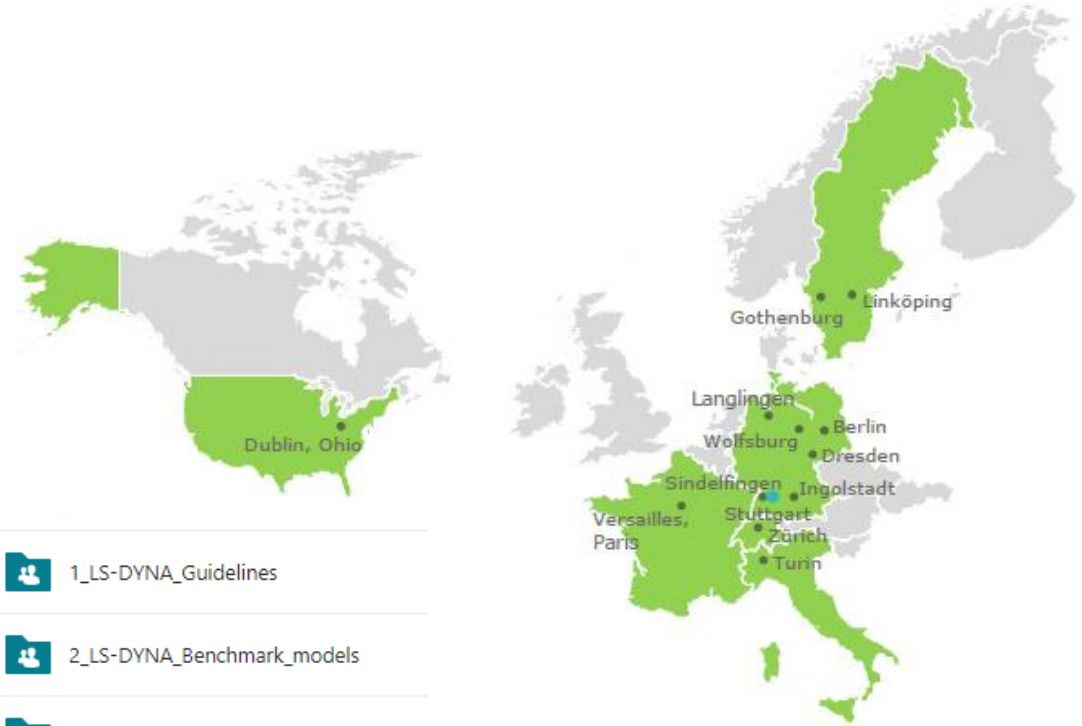
Anders Bernhardsson, DYNAmore Nordic AB
anders.bernhardsson@dynamore.se

Content

- DYNAmore Nordic
- Background
- What is LS-DYNA
- What is Ansys Workbench
- LS-DYNA Workbench integration
- Case study: ROPS and FOPS
- Additional input to LS-DYNA model
- Conclusion and Future

DYNAmore Group

- Totally ~100 employees
- Developers of ANSYS/LST: 14
- HQ: Stuttgart, Germany
- Nordic offices: Linköping & Göteborg
- Webinars: 1 per week
- Guidelines for DYNAmore customers
- Information
 - www.dynamore.se
 - www.dynasupport.com
 - www.dynalook.com



☐	1_LS-DYNA_Guidelines
☐	2_LS-DYNA_Benchmark_models
☐	3_LS-DYNA_Examples
☐	4_LS-DYNA_LS-PrePost_Tutorials
☐	5_LS-DYNA_Computer_Guide
☐	6_LS-DYNA_RP-C208
☐	7_Webinars
☐	8_Breakfast_Meetings_2019

Cooperation between DYNAmore Nordic, EDRMEDESO and ANSYS

■ ANSYS/LS-DYNA

- EDRMEDESO customers can purchase ANSYS/LS-DYNA licenses from EDRMEDESO and get support from DYNAmore Nordic if this is agreed before the purchase
- DYNAmore Nordic customers can purchase ANSYS/LS-DYNA or LSTC/LS-DYNA licenses from DYNAmore Nordic

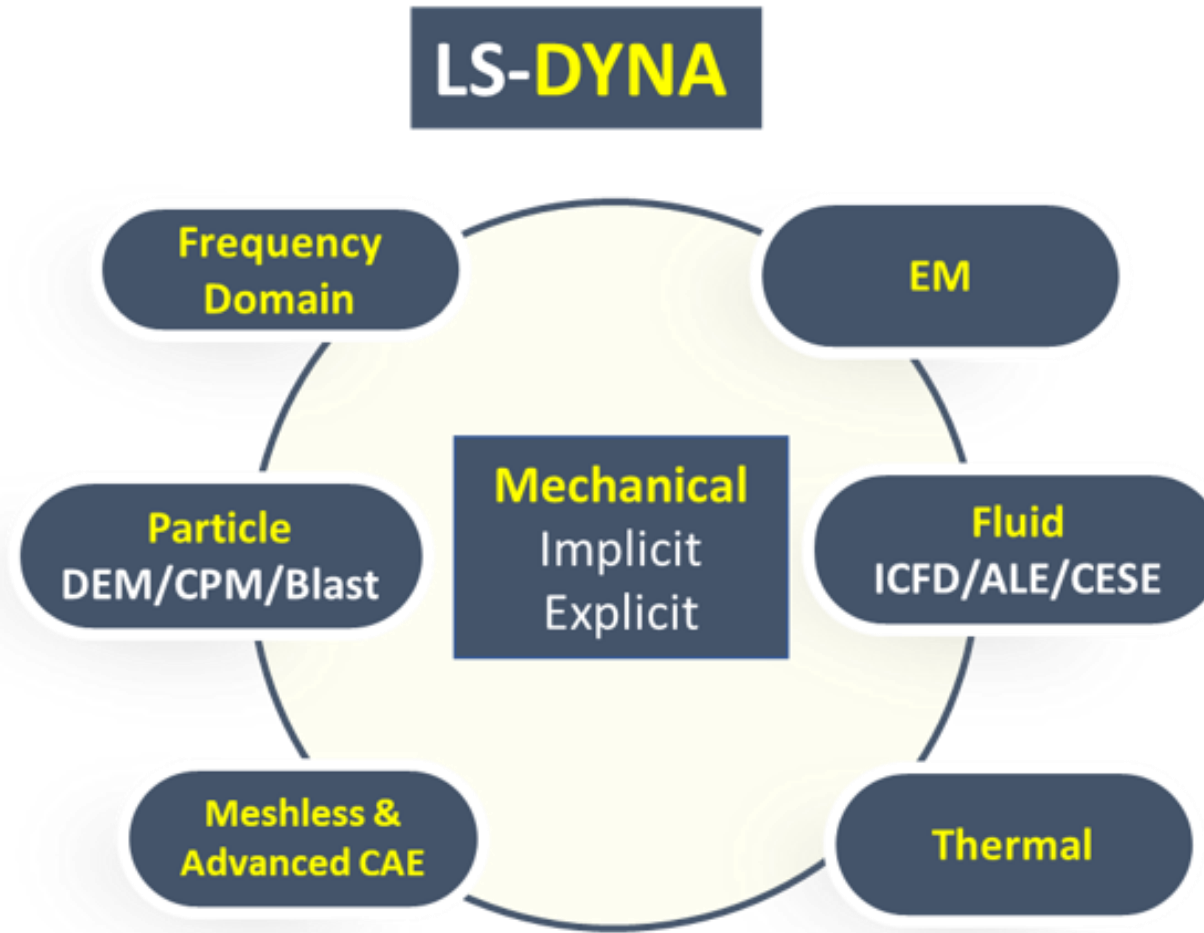


LS-DYNA

Background

- Even before Ansys acquisition of LSTC it was possible to use the LS-DYNA solver through Ansys products
- The LS-DYNA integration into Ansys Mechanical have existed many years by the Workbench LS-DYNA module
- The module allows the user to set up an LS-DYNA keyword model and postprocess the results in Ansys Mechanical

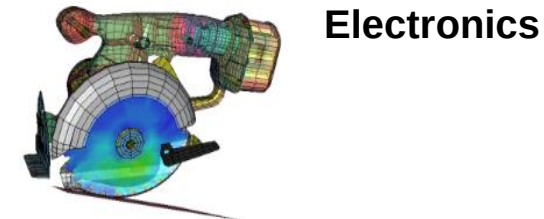
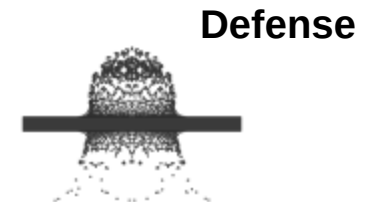
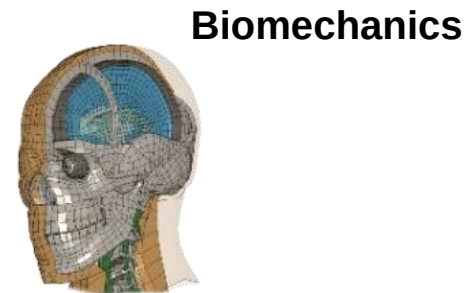
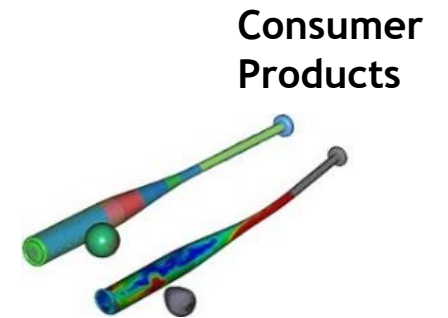
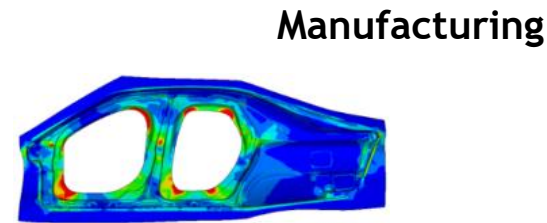
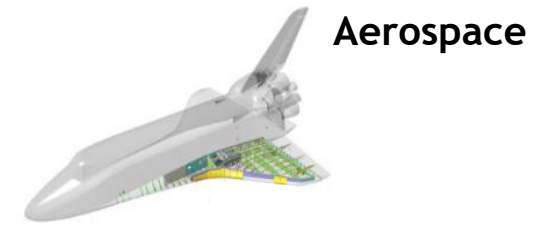
What is LS-DYNA - One Code for multi-physics solutions



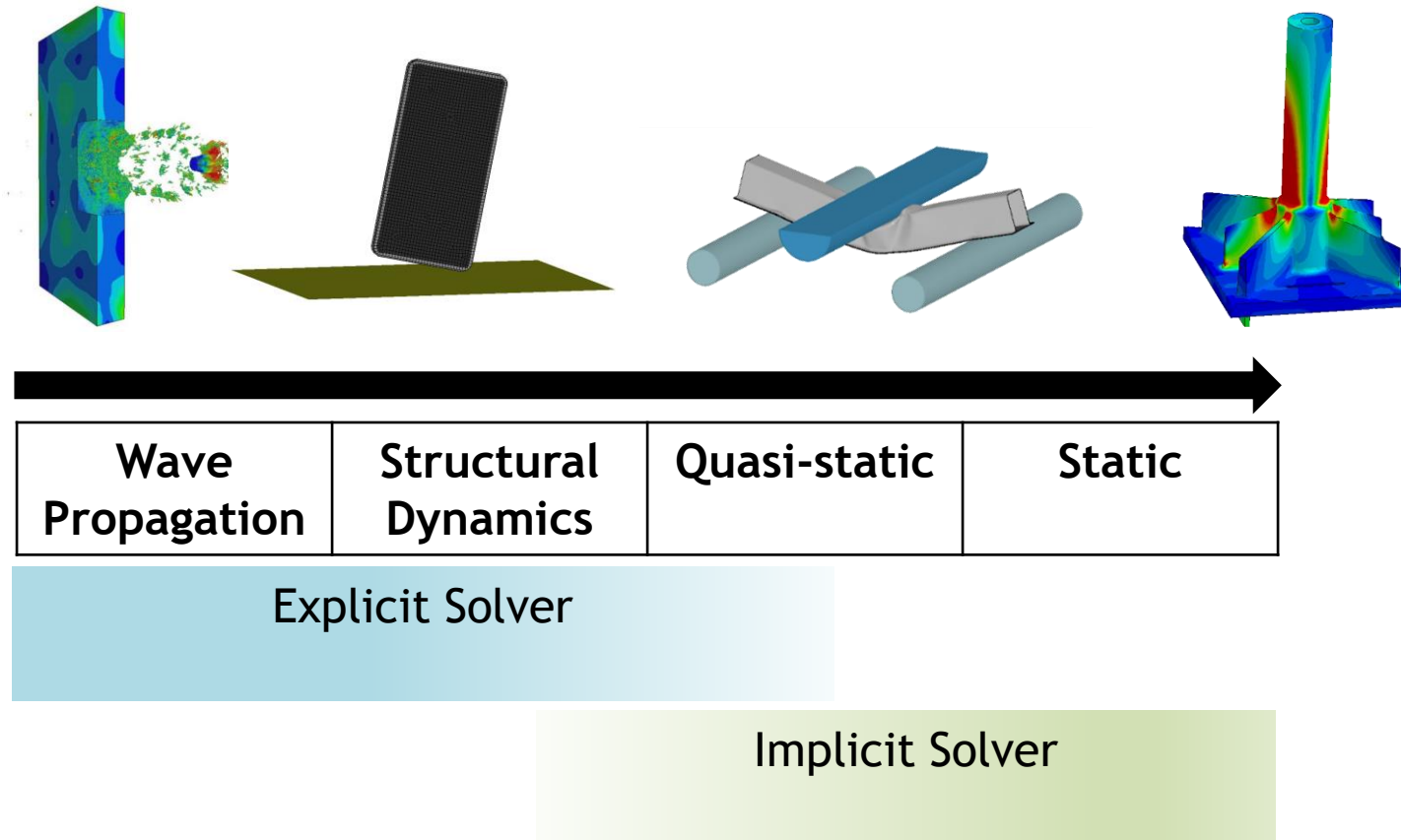
Note: All solvers are included in the license

What is LS-DYNA - Applications

- Crash and impact
- Manufacturing processes
- Overload
- Misuse
- Drop tests
- Advanced material models, failure etc.
- Large models
- Contacts
- Fatigue incremental or dynamic
- FSI
- Explosions

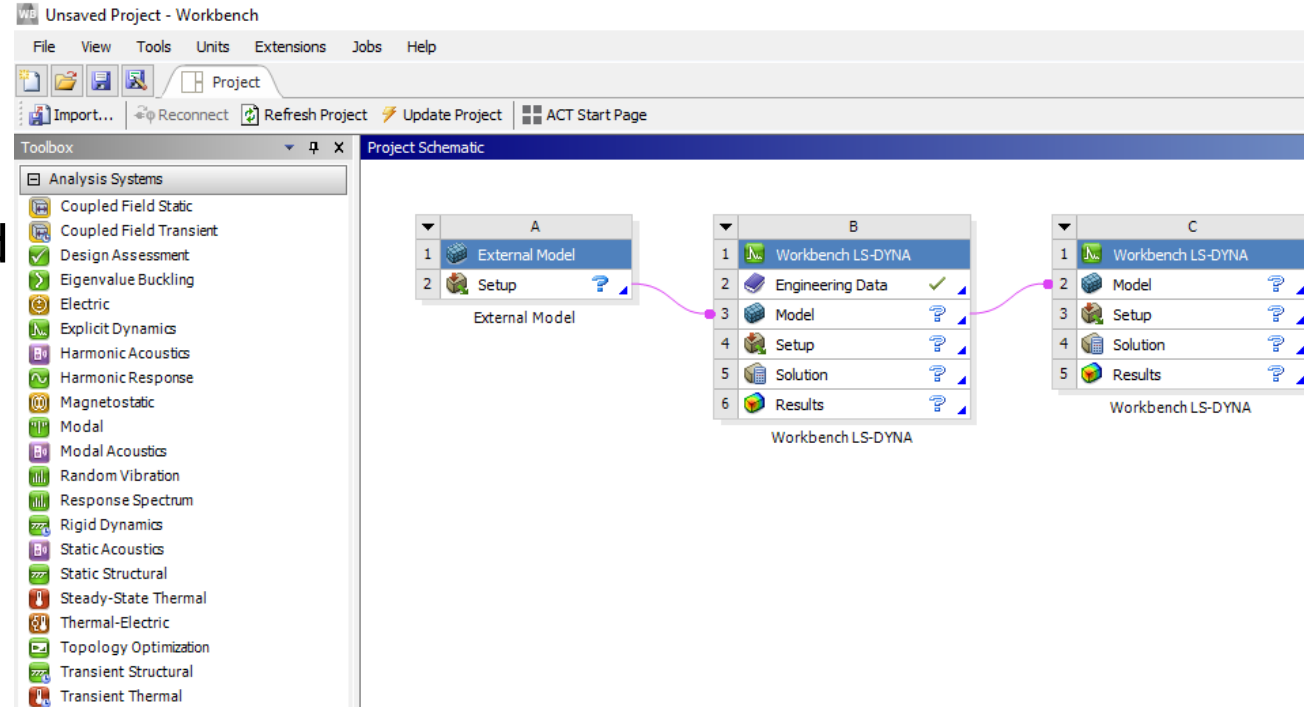


What is LS-DYNA - Explicit vs. Implicit solver



What is Ansys Workbench

- The Ansys Workbench interface gives the user an easy overview of the project
- By using different Analysis Systems in the project it is possible to transfer models and results between the systems
- The Analysis Systems are made up from different components called Cells. These Cells can either be opened inside Workbench interface or launch a separate application.

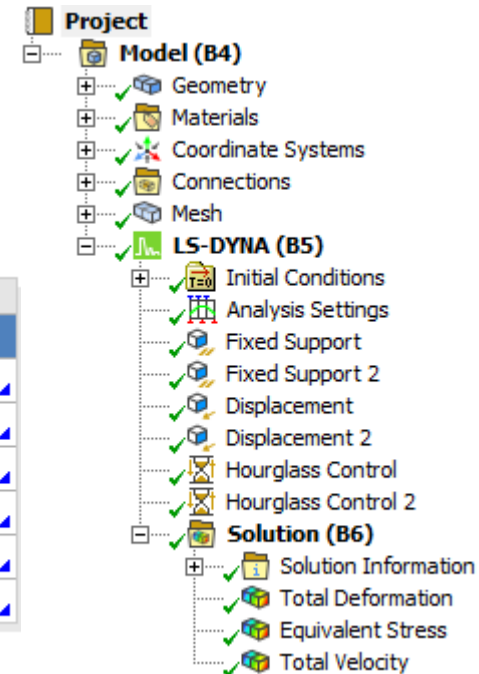
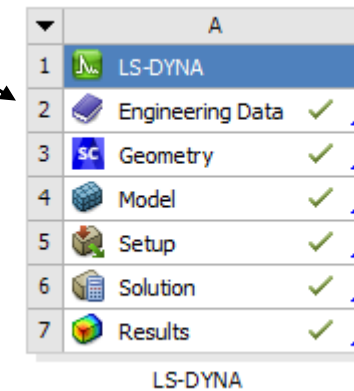
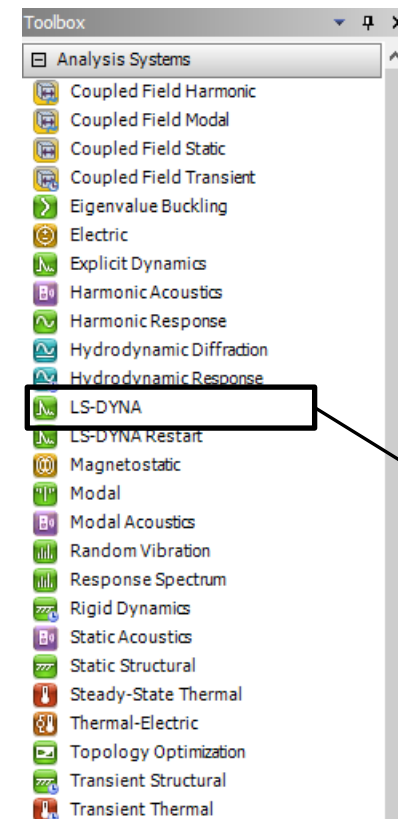


LS-DYNA Workbench integration

- Previously the LS-DYNA system was included as an extension or ACT (Ansys Customization Toolkit), but from Ansys 2020 R2 it is included as a regular Analysis System

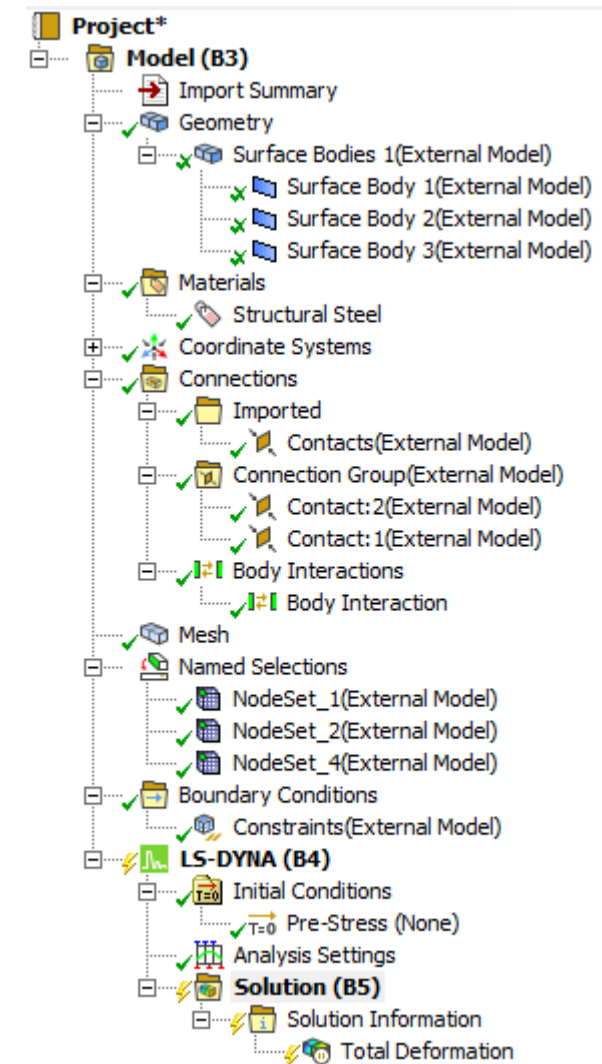
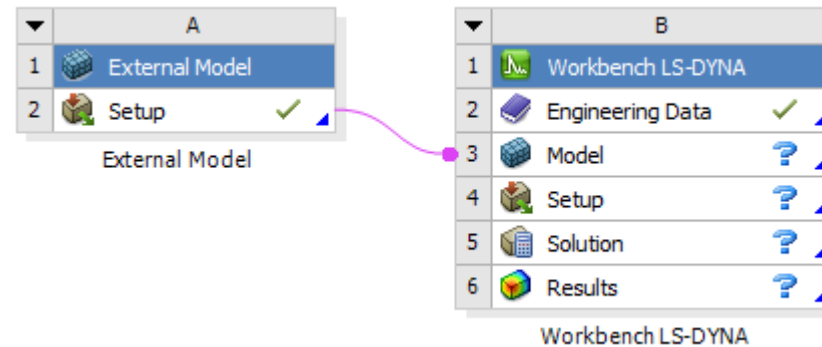
- The system consists of the following cells:

- Engineering Data: Material database for the analysis
- Geometry: Create or modify CAD model in DesignModeler or SpaceClaim
- Model: } FE setup; meshing, analysis
- Setup: } settings, post-processing. All
- Solution: } these steps are performed in
- Results: } Ansys Mechanical



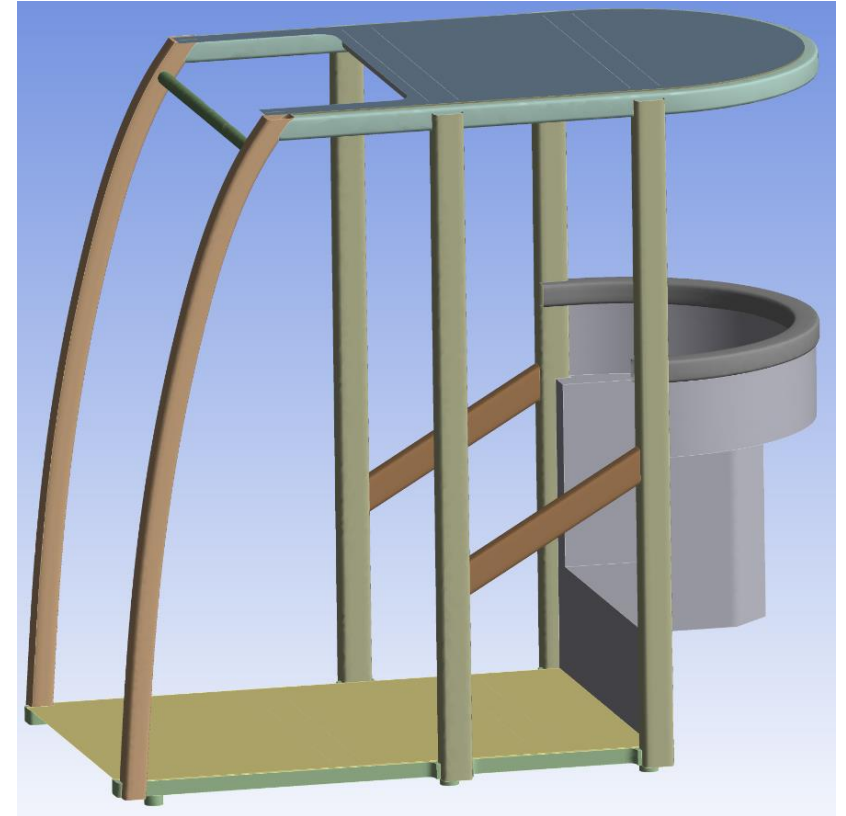
LS-DYNA Workbench integration

- Import a keyword file into Workbench
- Supported keywords to import
 - Nodes and elements
 - Parts
 - Node sets
 - SPCs
 - Contact regions
 - Initial thickness and stresses (from dynain)



Case study: ROPS and FOPS

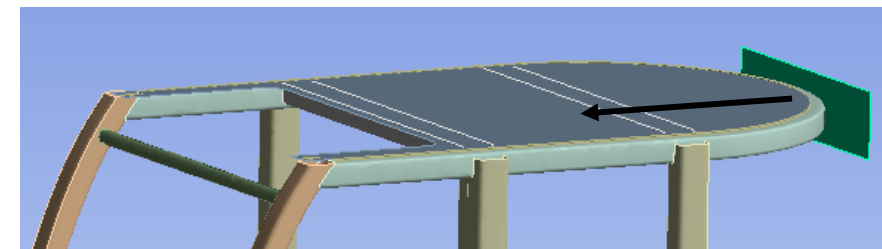
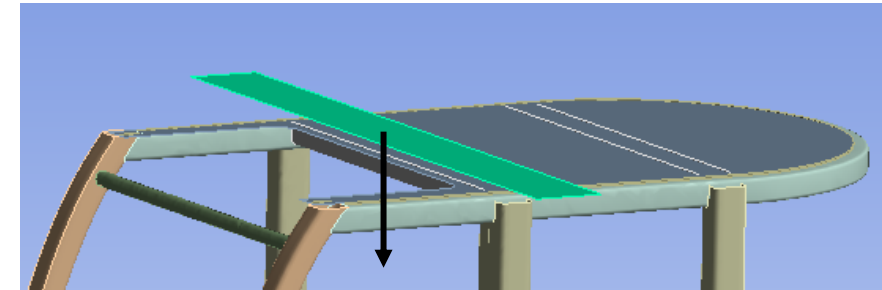
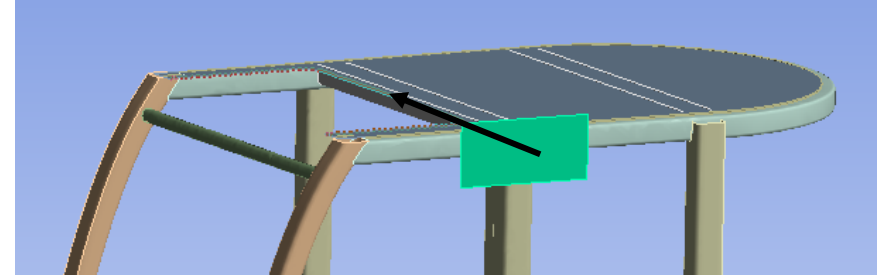
- ROPS : Roll Over Protective Structure
- FOPS : Falling Object Protective Structure
- Used in agricultural, forestry, earth-moving and mining machinery
- The testing procedures for these are harmonized in different standard documents



ROPS

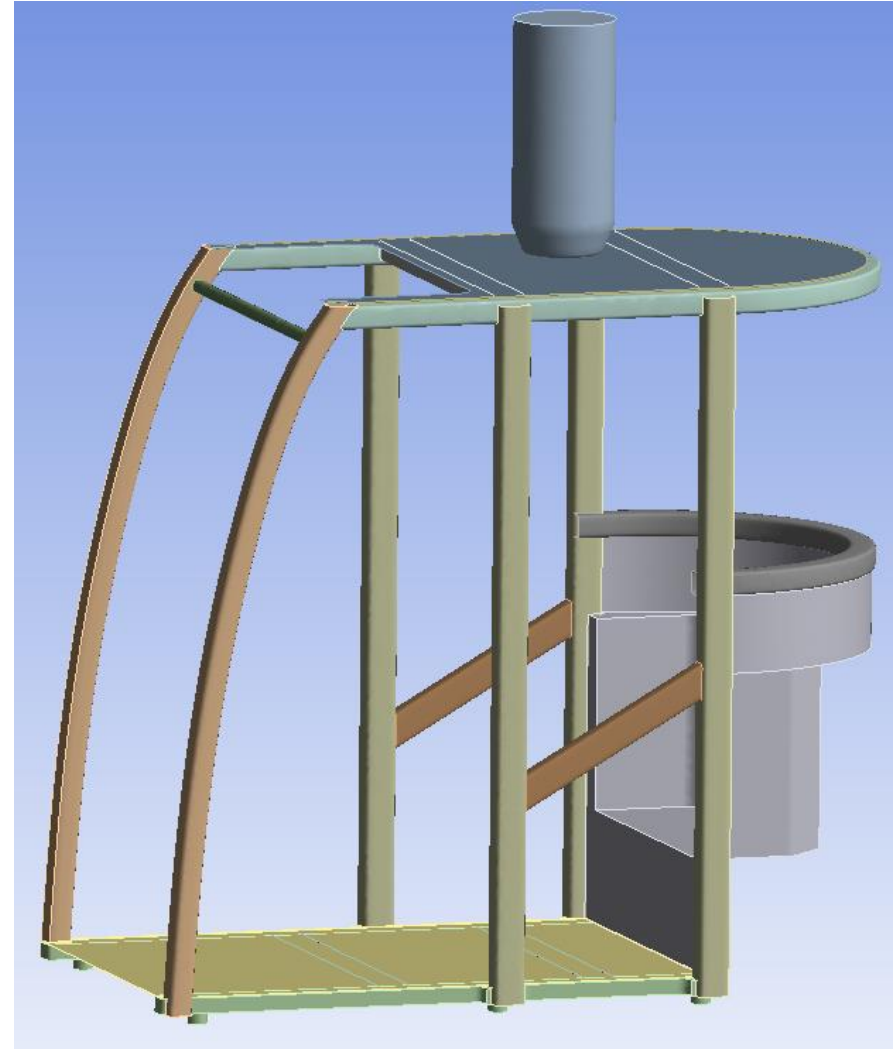
■ ROPS test procedure

- Load cases are to be performed in a sequence
- In this example:
 - Lateral
 - Vertical
 - Longitudinal
- The loading requirement depends on the machine type and weight
- For some load cases, both a force and energy requirement must be fulfilled
- The ROPS structure must not be deformed so it enters the area occupied by the driver



FOPS

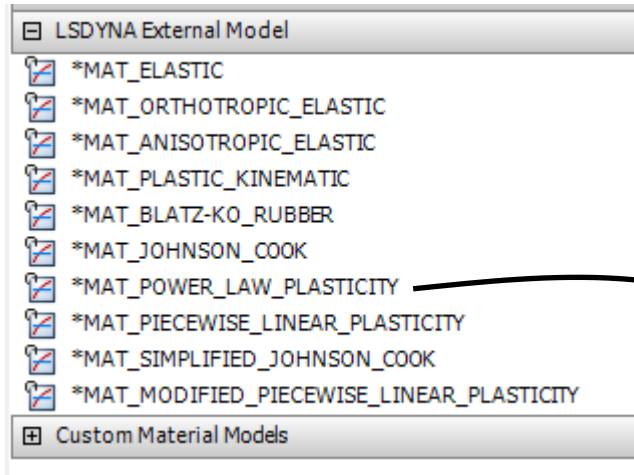
- FOPS test procedure
 - A test object is impacting the top of the FOPS
 - The mass and initial velocity of the test object determines the impact energy
 - The FOPS structure must not be deformed so it enters the area occupied by the driver



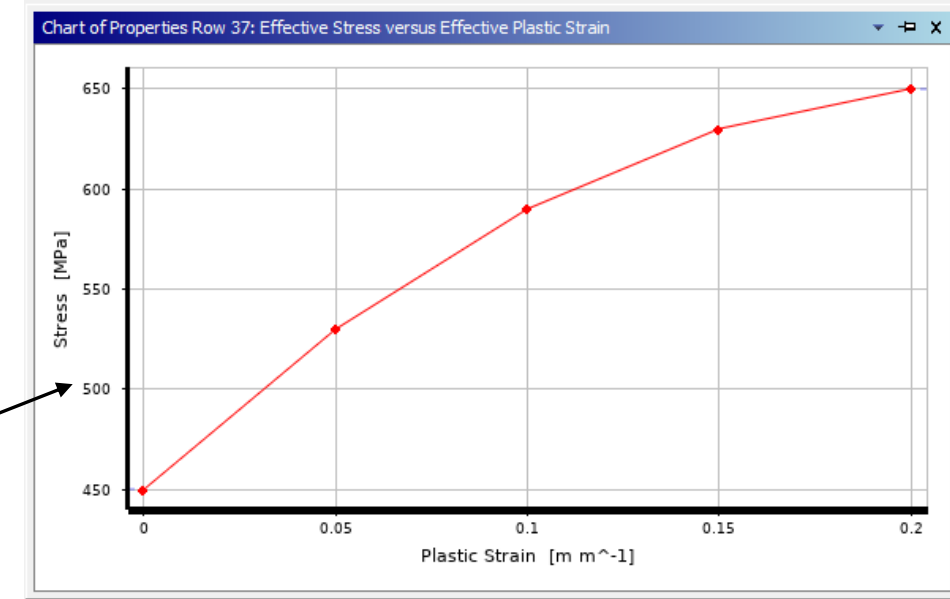
Material database

- From version 2021 R1 it's now possible to select LS-DYNA material models directly in Engineering Data
- Other LS-DYNA material models are available from the database, but is not visible directly in Engineering Data

	Plastic Strain (m m ⁻¹)	Stress (MPa)
1		
2	0	450
3	0.05	530
4	0.1	590
5	0.15	630
6	0.2	650

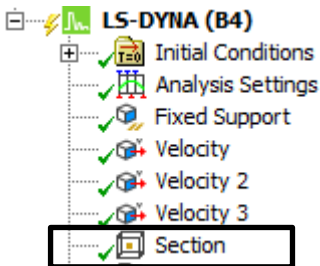


	A	B	C	D	E
1	Property	Value	Unit		
2	Material Field Variables	Table			
3	Density	7850	kg m ⁻³		
4	Isotropic Elasticity				
5	Derive from	Young's ...			
6	Young's Modulus	2E+11	Pa		
7	Poisson's Ratio	0.3			
8	Bulk Modulus	1.6667E+11	Pa		
9	Shear Modulus	7.6923E+10	Pa		
10	Isotropic Thermal Conductivity	60.5	W m ⁻¹ ...		
11	Specific Heat Constant Pressure, C _p	434	J kg ⁻¹ ...		
12	*MAT_PIECEWISE_LINEAR_PLASTICITY				
13	Definition				
37	Effective Stress versus Effective Plastic Strain	Tabular			
38	Scale	1			
39	Offset	0	MPa		

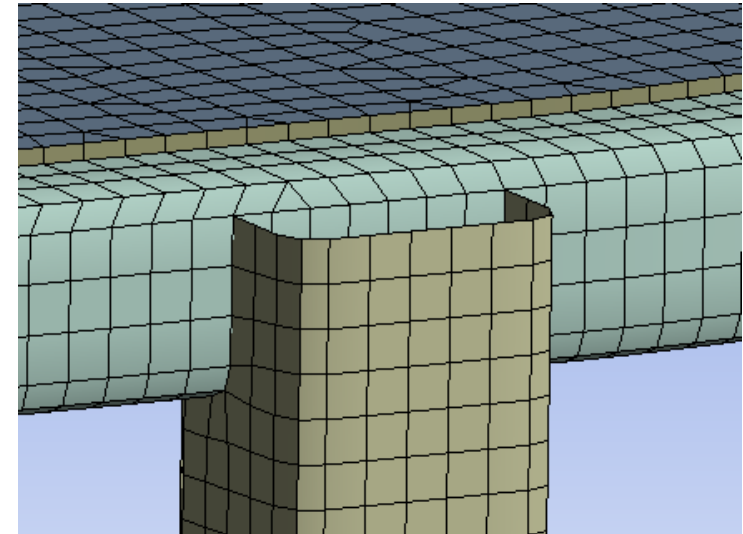


Elements

- As the explicit solver will be used for the simulations, aim for a uniform mesh in the model
- By default, under integrated elements are used for both shell and solid elements
- Possible to change the element formulation and the number of integration points through thickness
- Hourglass controls can be modified in Analysis Settings



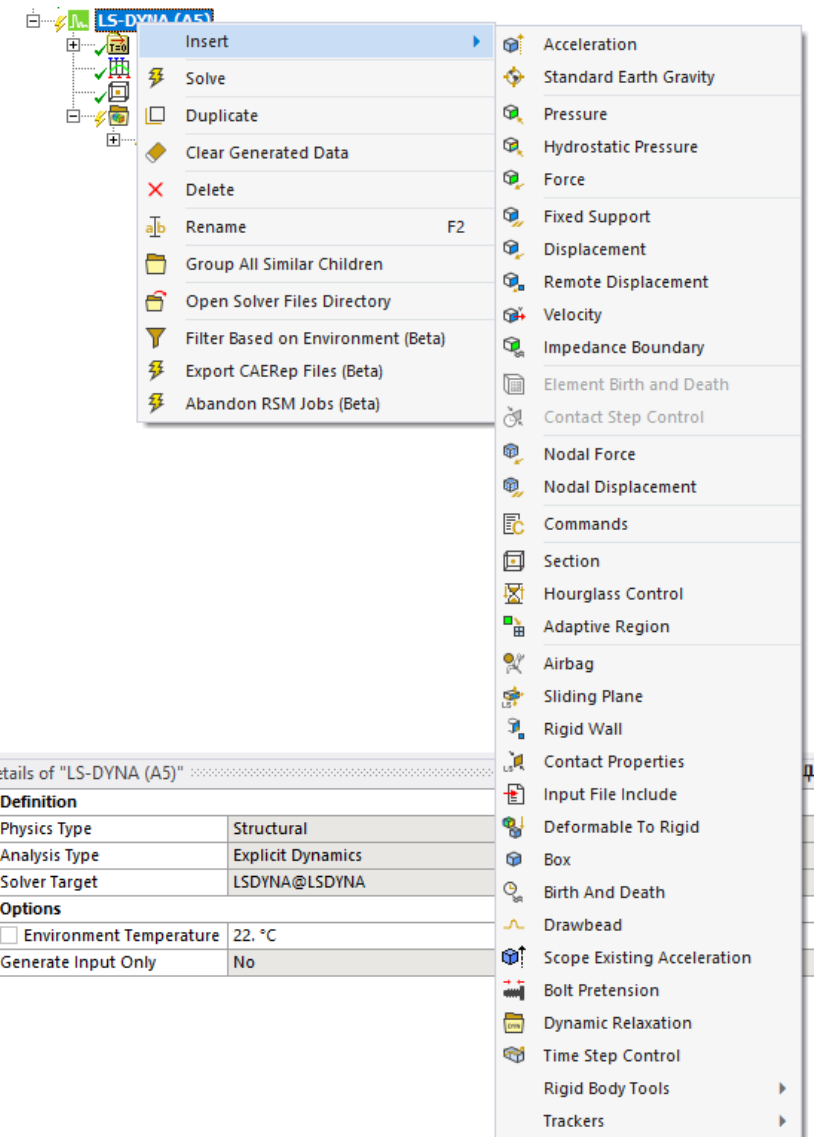
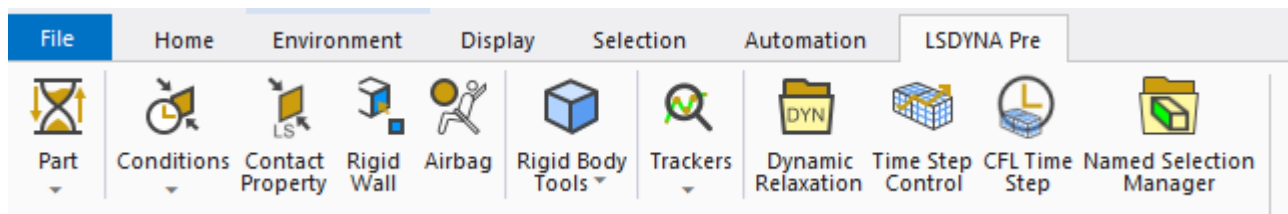
Details of "Section"	
Geometry	
Scoping Method	Geometry Selection
Geometry	1 Body
General	
ALE	No
Formulation	Belytschko-Tsay
LS-DYNA ID	2
Type	Section Shell
Through Thickness Integration Points	5 Point



Hourglass Controls	
Hourglass Type	Flanagan-Belytschko Stiffness Form
LS-DYNA ID	4
Default Hourglass Coefficient	0.1

Boundary Conditions

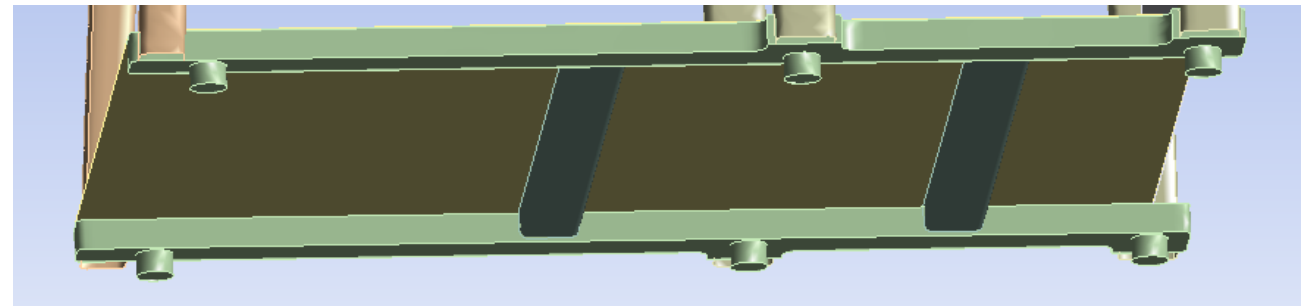
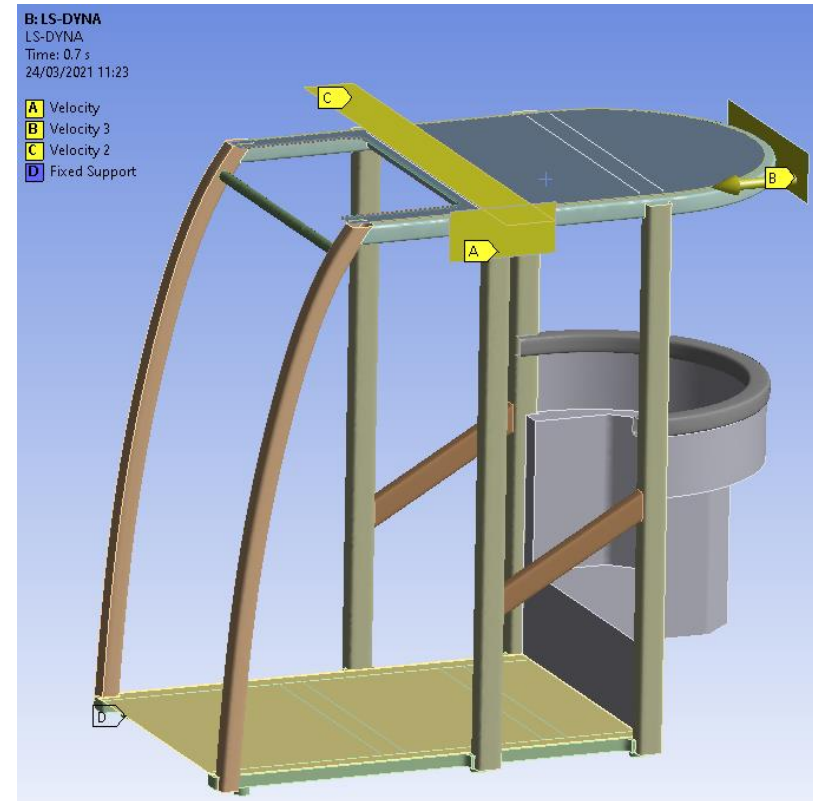
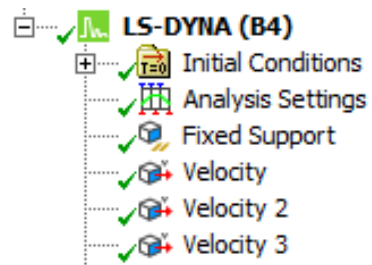
- The typical boundary and initial conditions used in a structural analysis can be selected
- The specific keywords are not seen when choosing the boundary conditions, but the naming of the inputs shows quite easily which LS-DYNA keyword that will be used



Boundary Conditions

■ ROPS

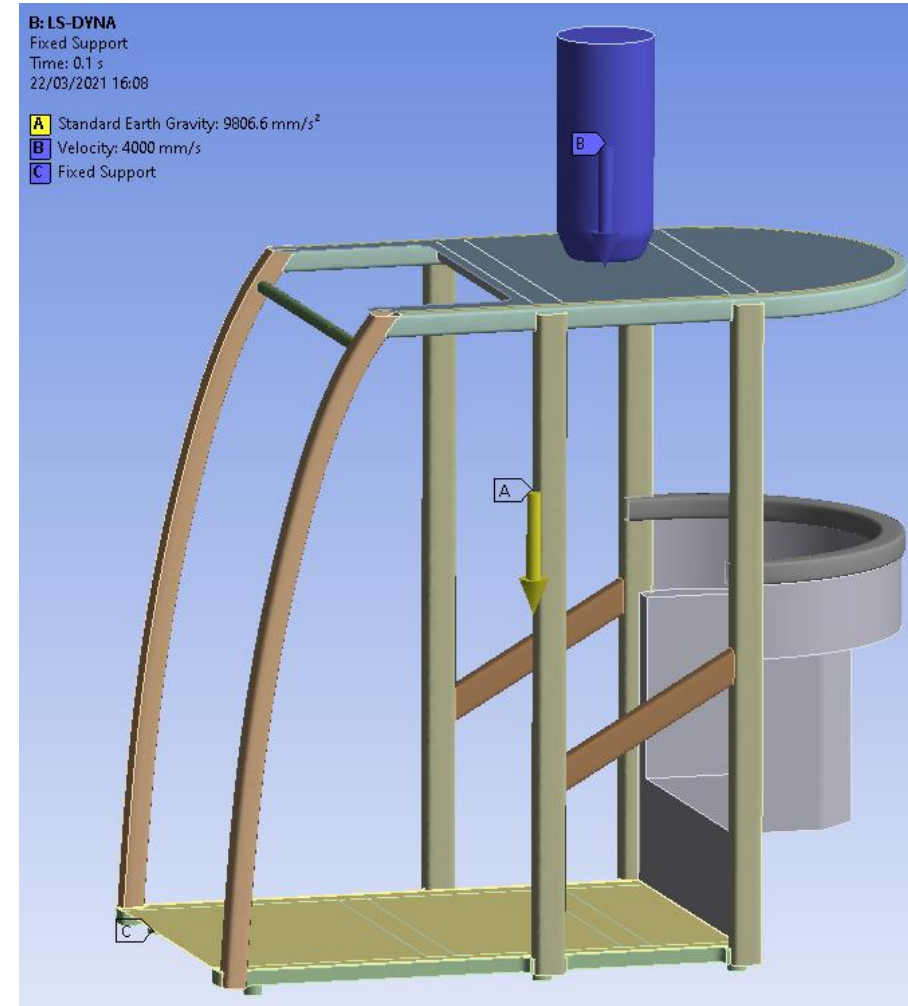
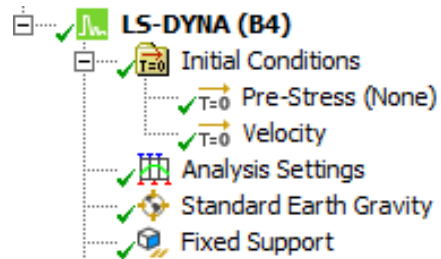
- Fixed supports on bottom plate
- Prescribed velocities on impactors



Boundary Conditions

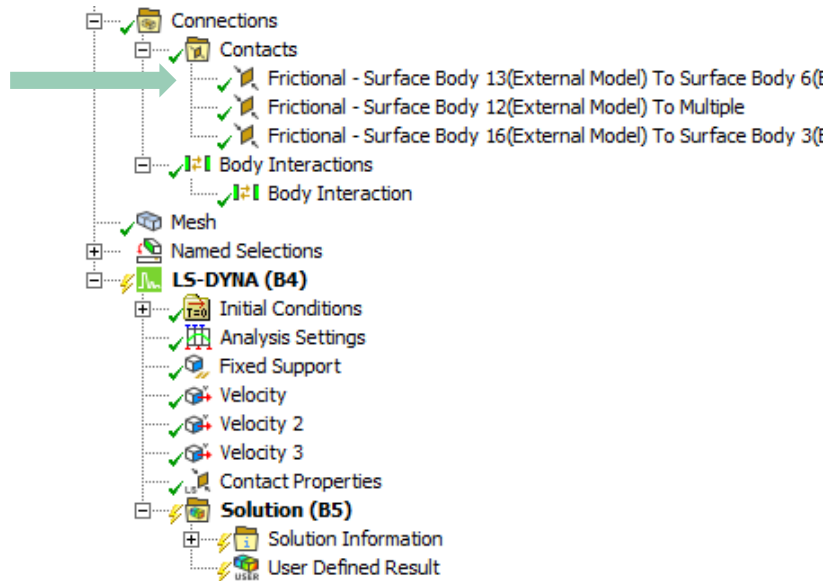
■ FOPS

- Fixed supports on bottom plate
- Initial velocity on impactor
- Gravity included

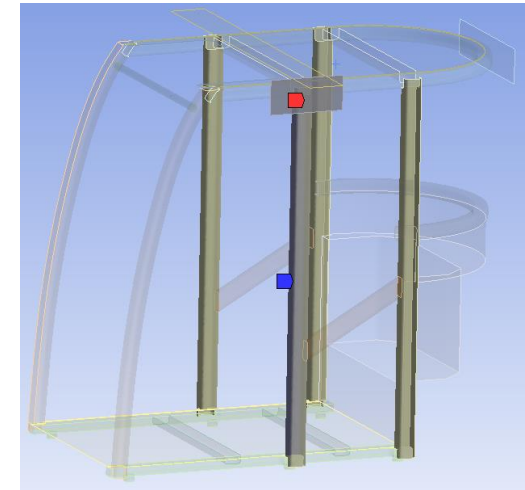


Contacts

- In the Contact Regions the user select the part/face/edge for the Contact and Target side (slave and master)
- Some general settings for the contact are also made
 - Type: Bonded/frictional
 - Friction coefficients
 - Behavior: Symmetric/Asymmetric

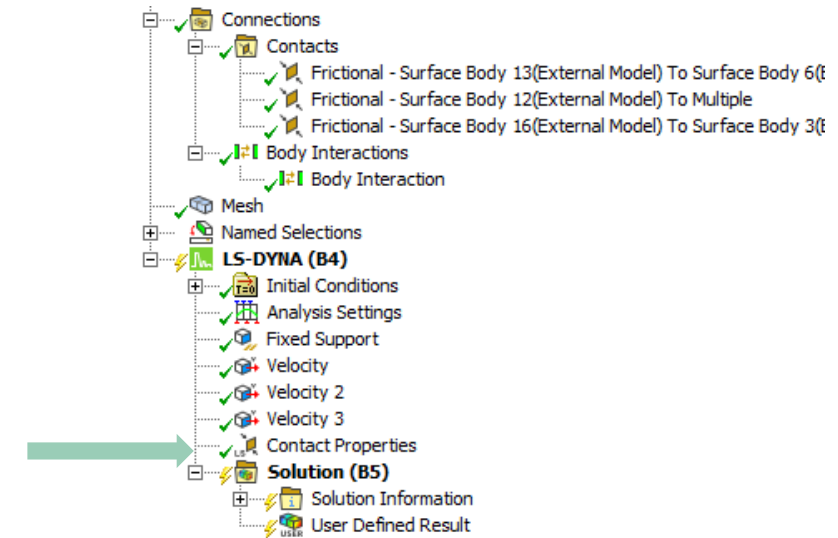


Details of "Frictional - Surface Body 13(External Model) To Surface Body 6(External Model)"	
Scope	
Scoping Method	Geometry Selection
Contact	1 Face
Target	1 Face
Contact Bodies	Surface Body 13(External Model)
Target Bodies	Surface Body 6(External Model)
Contact Shell Face	Top
Target Shell Face	Top
Protected	No
Definition	
Type	Frictional
☐ Friction Coefficient	0.3
☐ Dynamic Coefficient	0.
☐ Decay Constant	0.



Contacts

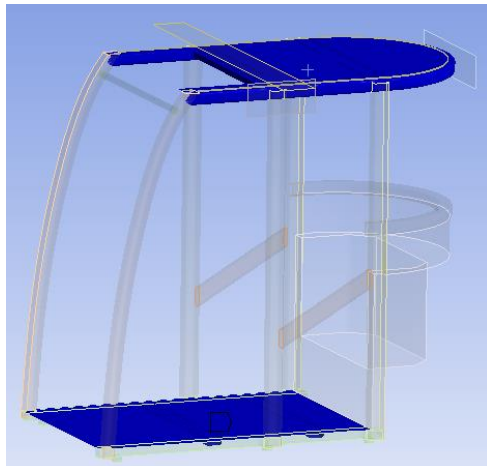
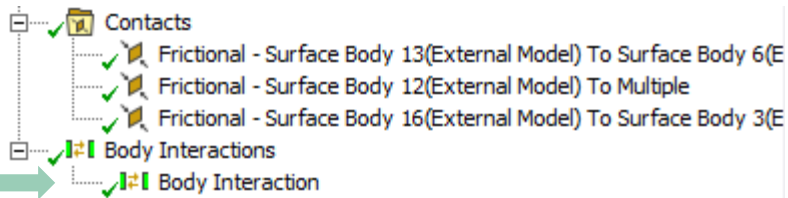
- In the Contact Properties section the user define the LS-DYNA contact settings for each contact region
- Depending on the type and behavior in the contact region (bonded/frictional and symmetric/asymmetric) and the Type selection we can set the specific formulation used in LS-DYNA
- Some other familiar options for the contact keyword are also available in these section
- Note that this is not mandatory. If not added the default settings will be used and is sufficient for most cases



Details of "Contact Properties"	
General	
Contact	Frictional - Surface Body 13(External M...
Type	Program Controlled
Formulation	AUTOMATIC_SURFACE_TO_SURFACE
Common Controls	
☐ Birth Time	0 s
☐ Death Time	0 s
☐ Viscous damping coefficient	10
☐ Slave Penalty Scale Factor	0
☐ Master Penalty Scale Factor	0
Advanced Controls	
☐ Optional Thickness for Slave Surface	0 mm
☐ Optional Thickness for Master Surface	0 mm
☐ Optional Solid Element Thickness	0 mm
Soft Constraint Formulation	Program Controlled
☐ Soft Constraint Scale Factor	0.1
Depth	5

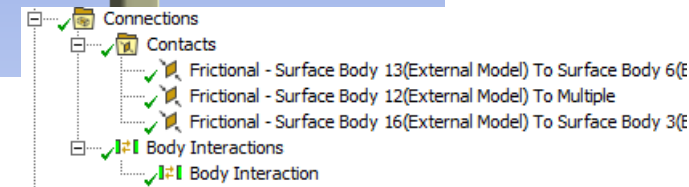
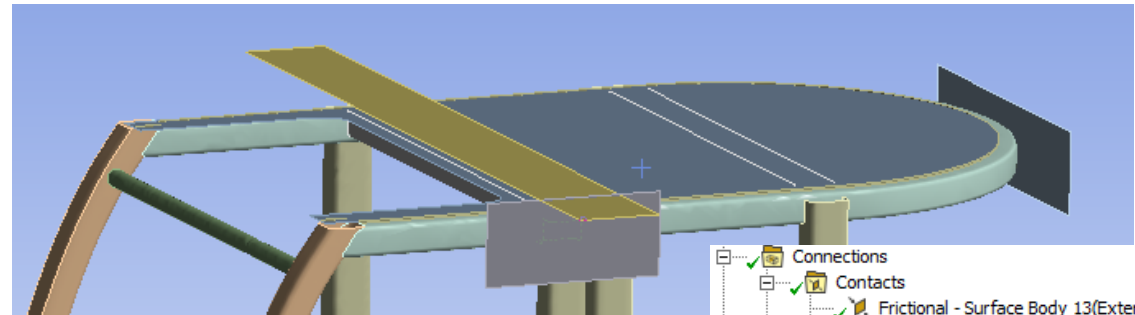
Contacts

- Body interaction to handle the internal contact between specific parts
 - *CONTACT_AUTOMATIC_SINGLE_SURFACE
- Use frictional contact for the rest of the contacts



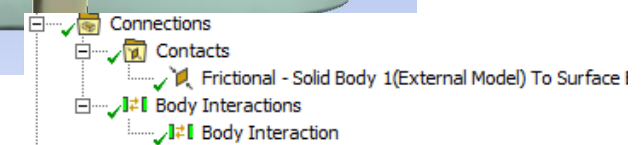
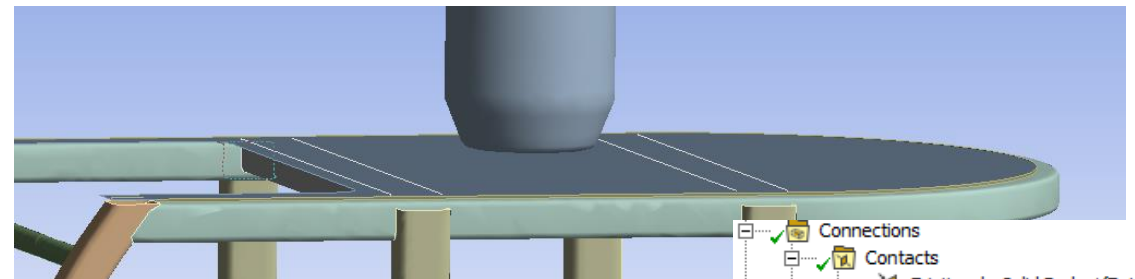
ROPS

- Contact between impactors and frame



FOPS

- Contact between test object and roof



Analysis settings

- The explicit solver will be used in both simulations
- The only needed input is the simulation end time
- ROPS
 - The ROPS test is a quasi-static test. In the simulation it will be a balance between not introducing dynamic effects in the loading and reducing the computational time.
 - Mass-scaling can be used to increase the explicit time step
- FOPS
 - The simulation time is set so it covers the impact
 - Mass-scaling can be used here as well but always check location and amount of added mass in the model

Step Controls	
End Time	0.7 s
Time Step Safety Factor	0.9
Maximum Number Of Cycles	10000000
Automatic Mass Scaling	Yes
Time Step Size	1.8E-06 s

From message file

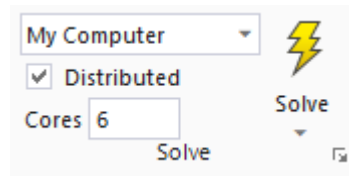
```
calculation with mass scaling for minimum dt
added mass      = 2.6363E-02
physical mass= 4.2625E-01
ratio           = 6.1850E-02
```


Run LS-DYNA

- In the Analysis Settings there are some general simulation settings together with the solver settings

- SMP/MPP
- NCPU
- Memory
- Single/double precision
- Solver version

CPU and Memory Management	
Memory Allocation	Program Controlled
Number Of CPUs	6
Processing Type	SMP
Solver Controls	
Solver Type	Program Controlled
Solver Precision	single
Unit System	mmm
Invariant Node Numbering	Off
Second Order Stress Update	No
Solver Version	11.2



Livermore Software Technology, LLC

7374 Las Positas Road
Livermore, CA 94551
Tel: (925) 449-2500 Fax: (925) 449-2507
www.lstc.com

LS-DYNA, A Program for Nonlinear Dynamic
Analysis of Structures in Three Dimensions
Date : 10/15/2020 Time: 07:56:29
Version : smp s R11.2.0
Revision: R11.2-66-g4cdf4c9c50

Features enabled in this version:
Shared Memory Parallel
FFTW (multi-dimensional FFTW Library)
Interactive Graphics
ANSYS License (ANSYS211)
MADYMO indirect coupling (7.2 or higher)

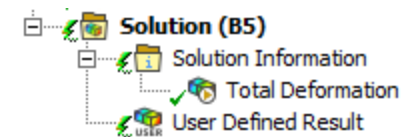
Licensed to:
Issued by : ANSYS

Platform : WINDOWS X64 (SSE2)
OS Level : Windows 8/10 & Srv 2012/2016 R2 ua
Compiler : Intel Fortran XE 2017 MSVC++ 2017
Hostname : canary
Precision : Single precision (I4R4)

Unauthorized use infringes LSTC copyrights

Run LS-DYNA

- The LS-DYNA message file can be viewed during the simulation in Solution Information
- The results and animation can be viewed “live” as the result files are created

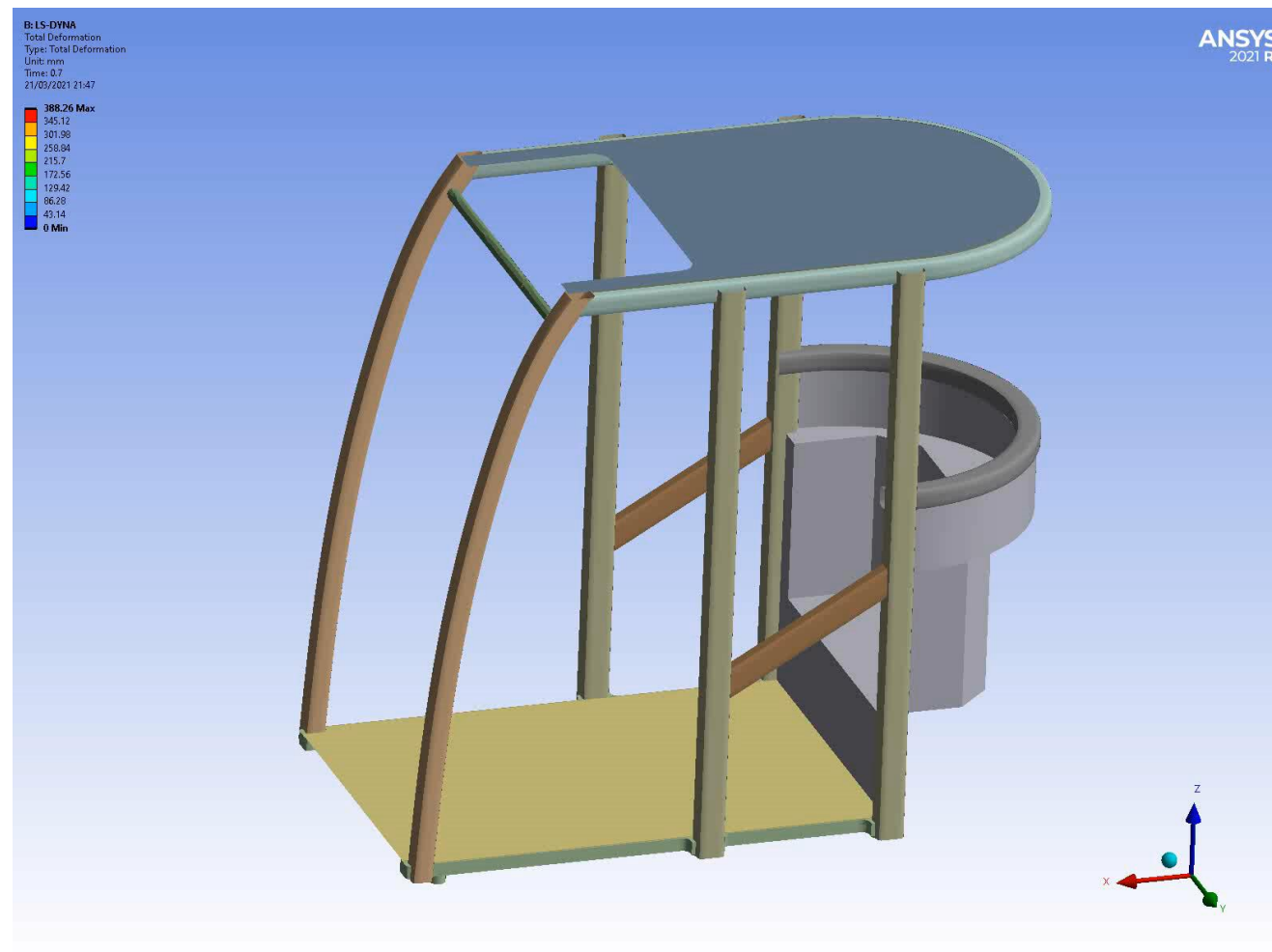


```
calculation with mass scaling for minimum dt
added mass = 8.7199E-02
physical mass= 1.6174E+00
ratio = 5.3914E-02
1 t 0.0000E+00 dt 1.62E-06 flush i/o buffers 03/21/21 21:12:03
1 t 0.0000E+00 dt 1.62E-06 write d3plot file 03/21/21 21:12:03
1 t 0.0000E+00 dt 1.62E-06 write intfor file 03/21/21 21:12:03
cpu time per zone cycle..... 0 nanoseconds
average cpu time per zone cycle.... 1133 nanoseconds
average clock time per zone cycle.. 504 nanoseconds
estimated total cpu time = 5618 sec ( 1 hrs 33 mins)
estimated cpu time to complete = 5610 sec ( 1 hrs 33 mins)
estimated total clock time = 2504 sec ( 0 hrs 41 mins)
estimated clock time to complete = 2496 sec ( 0 hrs 41 mins)
added mass = 8.7198E-02
percentage increase = 5.3913E+00
termination time = 1.000E-01
termination cycle = 10000000
618 t 9.9954E-04 dt 1.62E-06 write d3plot file 03/21/21 21:12:12
619 t 1.0012E-03 dt 1.62E-06 write intfor file 03/21/21 21:12:12
1235 t 1.9991E-03 dt 1.62E-06 write d3plot file 03/21/21 21:12:19
1236 t 2.0007E-03 dt 1.62E-06 write intfor file 03/21/21 21:12:19
1852 t 2.9986E-03 dt 1.62E-06 write d3plot file 03/21/21 21:12:25
1853 t 3.0002E-03 dt 1.62E-06 write intfor file 03/21/21 21:12:26
2470 t 3.9998E-03 dt 1.62E-06 write d3plot file 03/21/21 21:12:33
2471 t 4.0014E-03 dt 1.62E-06 write intfor file 03/21/21 21:12:33
3087 t 4.9993E-03 dt 1.62E-06 write d3plot file 03/21/21 21:12:39
3088 t 5.0009E-03 dt 1.62E-06 write intfor file 03/21/21 21:12:39
3704 t 5.9989E-03 dt 1.62E-06 write d3plot file 03/21/21 21:12:46
3705 t 6.0005E-03 dt 1.62E-06 write intfor file 03/21/21 21:12:46
4321 t 6.9984E-03 dt 1.62E-06 write d3plot file 03/21/21 21:12:54
4322 t 7.0000E-03 dt 1.62E-06 write intfor file 03/21/21 21:12:54
4939 t 7.9996E-03 dt 1.62E-06 write d3plot file 03/21/21 21:13:01
4940 t 8.0012E-03 dt 1.62E-06 write intfor file 03/21/21 21:13:01
5000 t 8.0984E-03 dt 1.62E-06 flush i/o buffers 03/21/21 21:13:02
5556 t 8.9991E-03 dt 1.62E-06 write d3plot file 03/21/21 21:13:09
5557 t 9.0007E-03 dt 1.62E-06 write intfor file 03/21/21 21:13:09
6173 t 9.9986E-03 dt 1.62E-06 write d3plot file 03/21/21 21:13:16
6174 t 1.0000E-02 dt 1.62E-06 write intfor file 03/21/21 21:13:16
6701 t 1.0000E-02 dt 1.62E-06 write d3plot file 03/21/21 21:13:23
```

Postprocessing

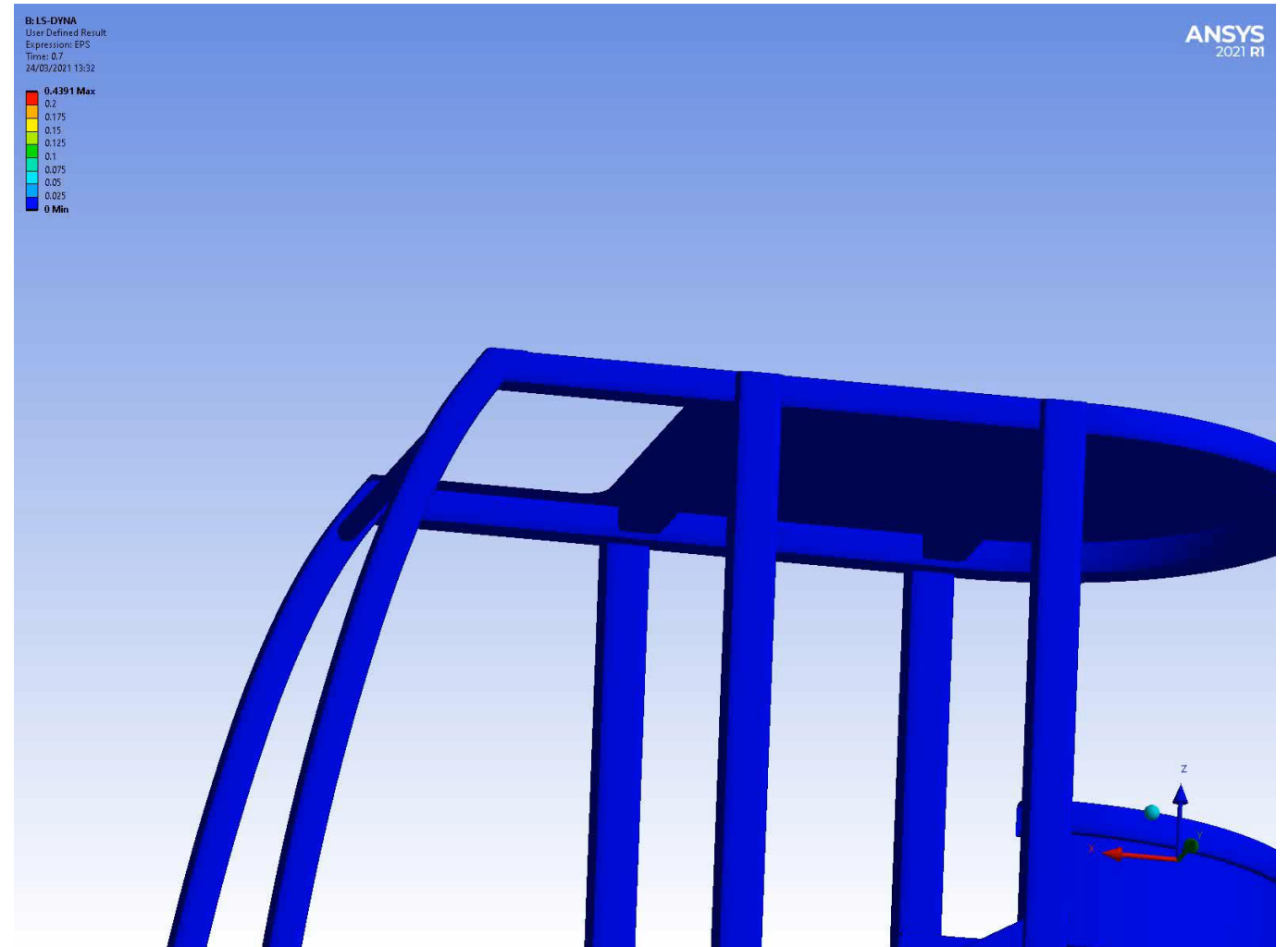
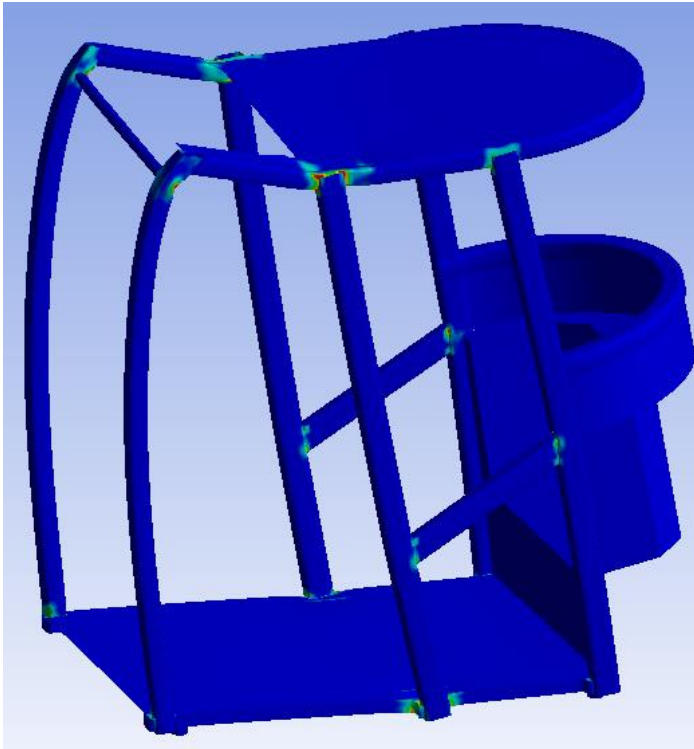
■ ROPS

- Simulation time: 0.7 s
- Computational time: 1.28 h
(6 cpus on laptop)



Postprocessing

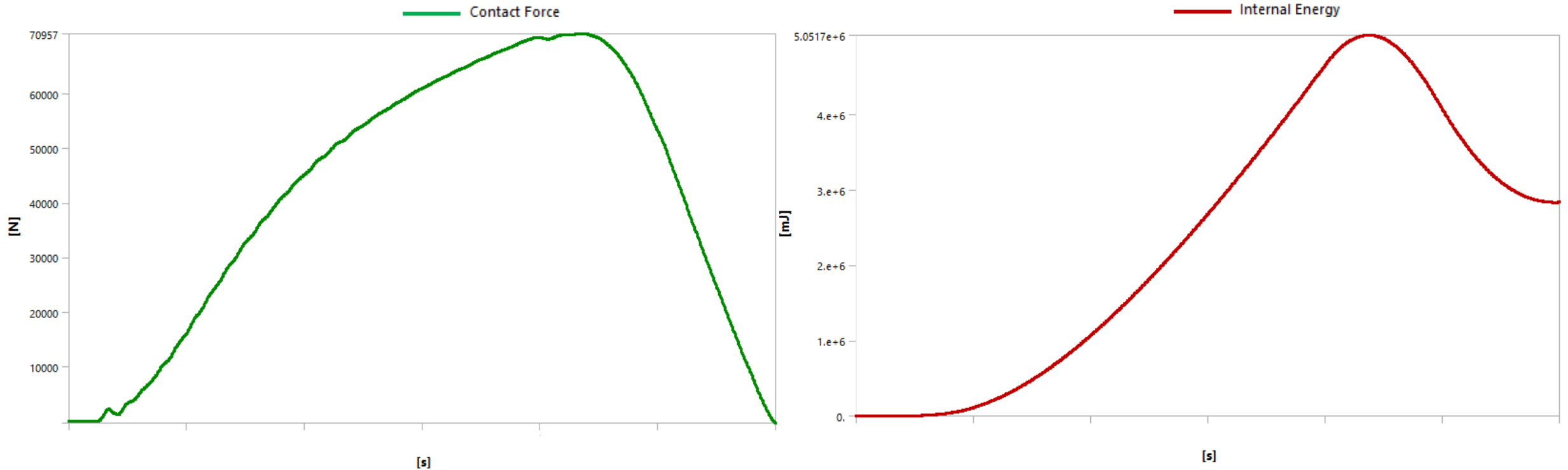
- ROPS
- Plastic strain



Postprocessing

■ ROPS

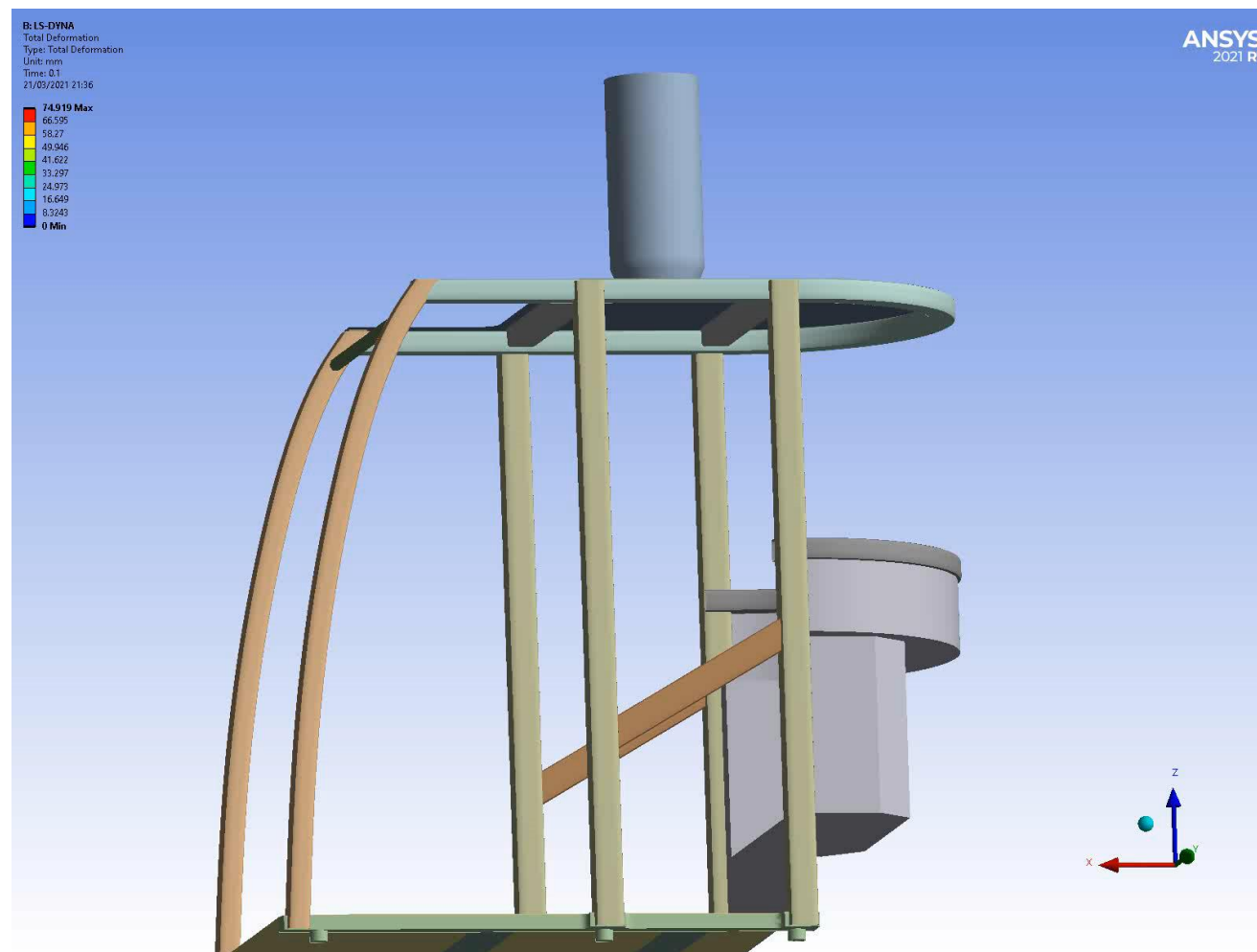
- Contact force and energy for lateral load case



Postprocessing

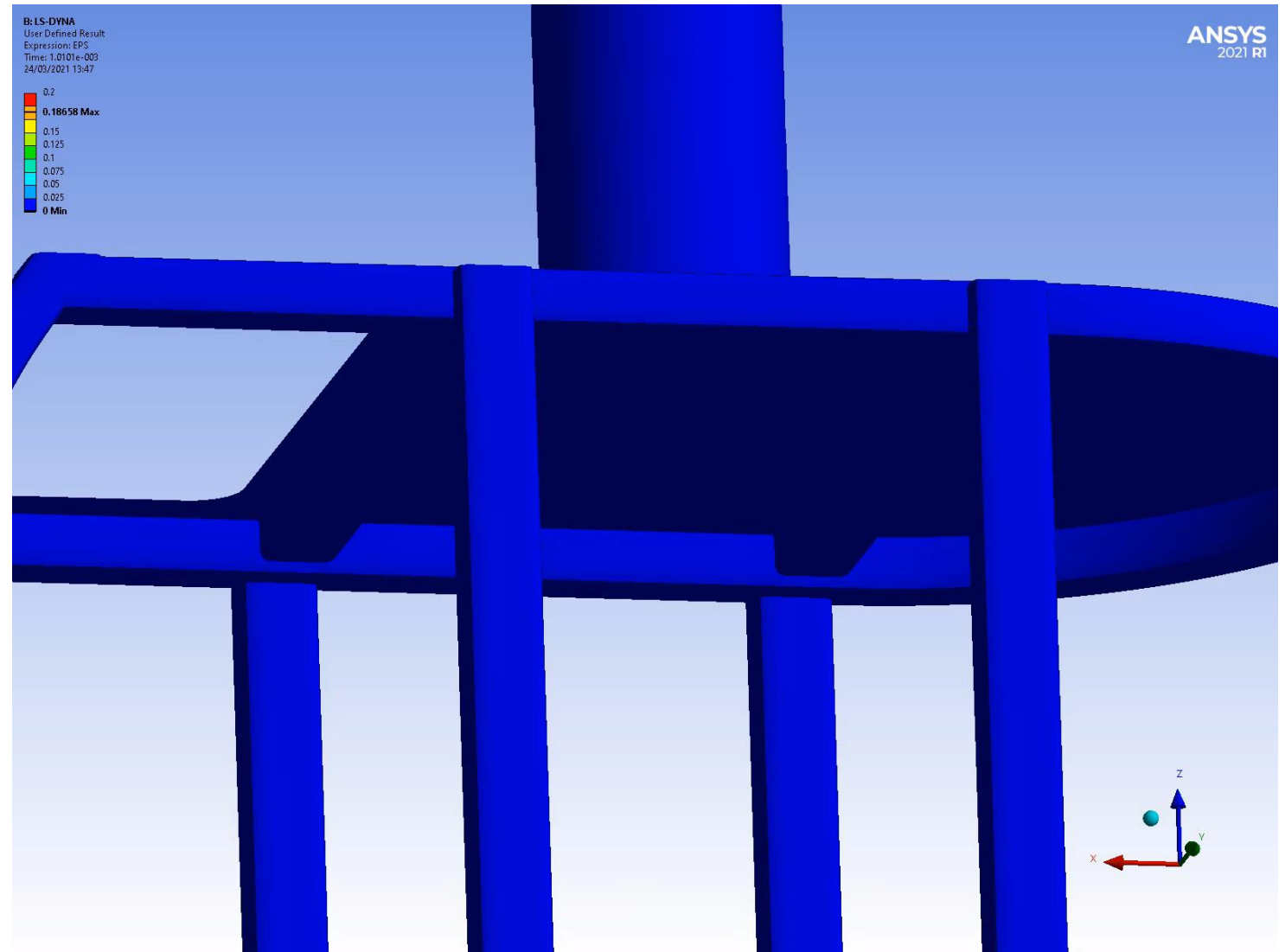
■ FOPS

- Simulation time: 0.1 s
- Computational time: 13 min
(6 cpus on laptop)



Postprocessing

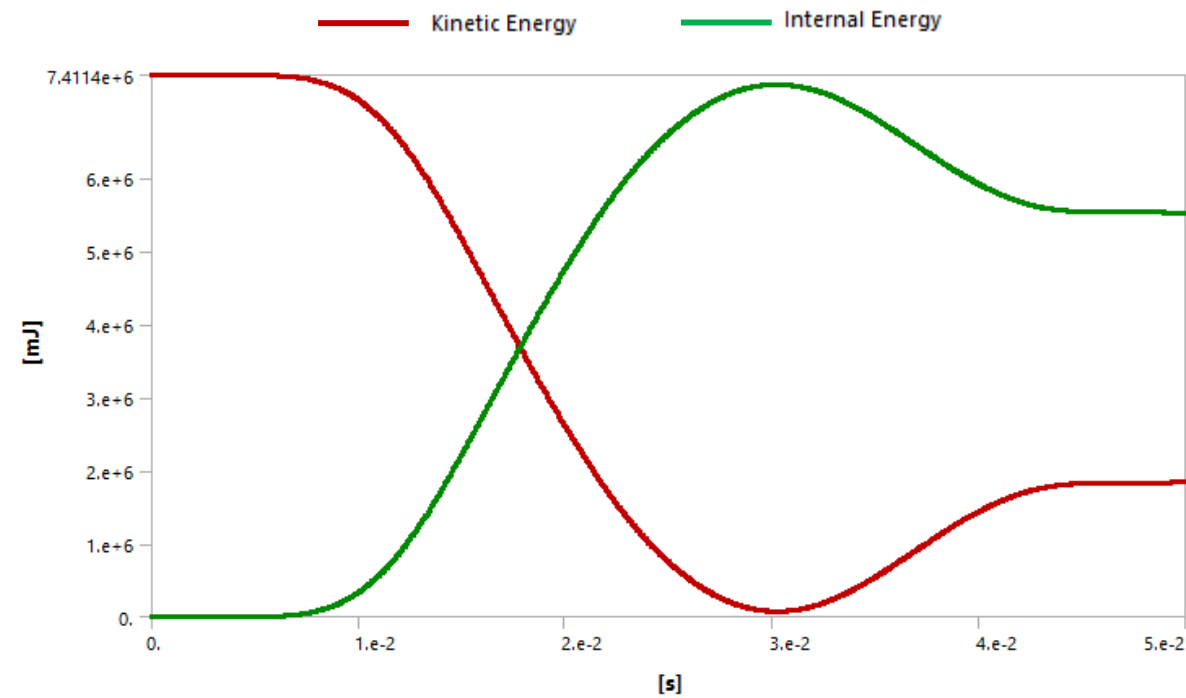
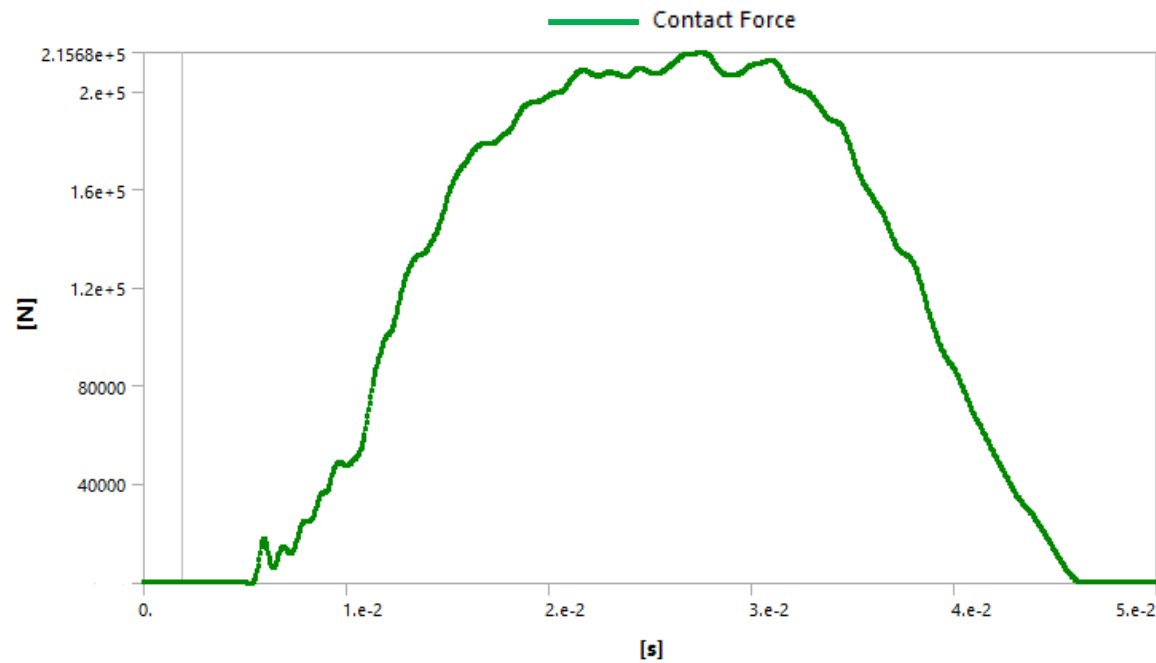
- FOPS
- Plastic strain



Postprocessing

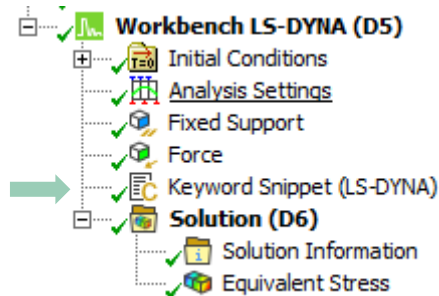
FOPS

Contact force and energies



Additional input to LS-DYNA model

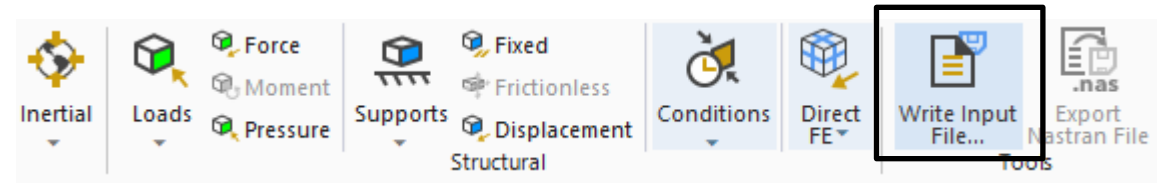
- Not all existing LS-DYNA keywords are accessible through Workbench LS-DYNA
- The Keyword Snippet function gives the user to input the wanted keywords



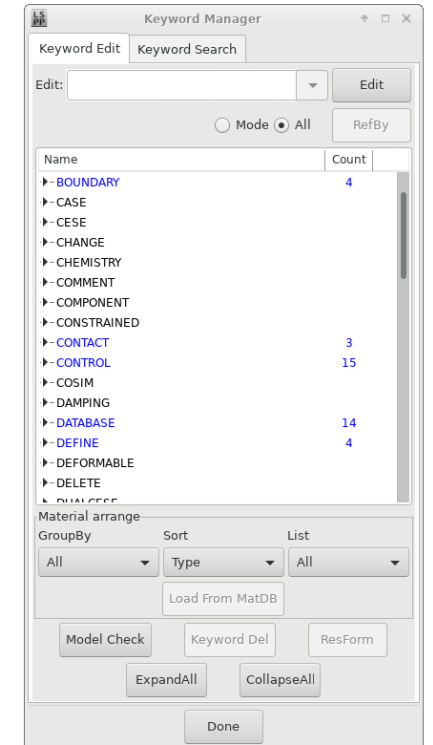
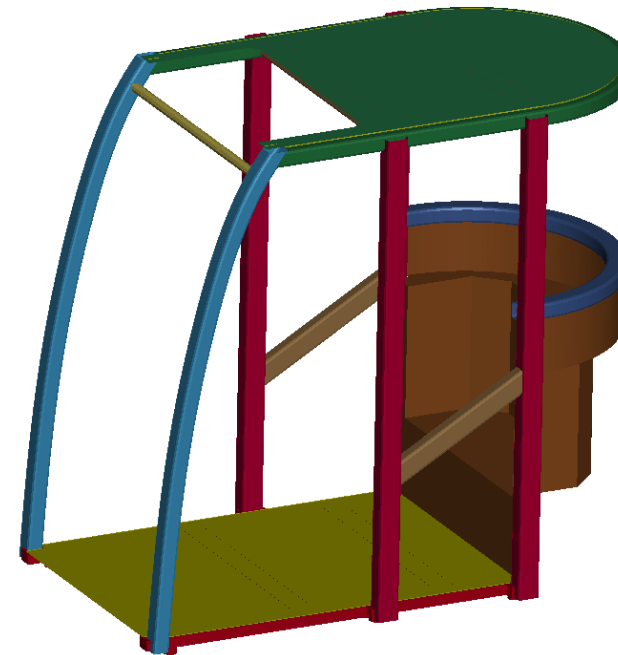
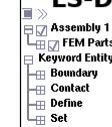
```
Commands
1  $  Keyword Snippet
2  $  Do not leave any unintentional empty lines in this editor
3  *CONTROL_IMPLICIT_GENERAL
4  $$  imflag      dt0      imform      nsbs      igs      cnstn      form      zero_v
5      1          0.1      2          1          2          0          0          0
6  *CONTACT_AUTOMATIC_SURFACE_TO_SURFACE_MORTAR_ID
7  $$      cid                      title
8      10
9  $$      ssid      msid      sstyp      mstyp      sboxid      mboxid      spr      mpr
10     3          1          3          3          0          0          0          0
11  $$      fs      fd      dc      vc      vdc      penchk      bt      dt
12     0.2      0.0      0.0      0.0      0.0      0          0.01.000000E20
13  $$      sfs      sfm      sst      mst      sfst      sfmt      fsf      vsf
14     1.0      1.0      0.0      0.0      1.0      1.0      1.0      1.0
15
```


Additional input to LS-DYNA model

- Export the keyword file from Mechanical
- LS-PrePost can then be used to add extra keywords that doesn't exist in Workbench LS-DYNA
- LS-PrePost is a free software and supports all existing keywords in LS-DYNA



LS-DYNA keyword deck by LS-PrePost



Additional input to LS-DYNA model

- Alternatives for ROPS model
- Implicit solver
 - Add the necessary implicit keywords with Keyword snippets
 - Change element formulation in Mechanical
 - Use double precision for solver
- CASE option
 - Start one simulation that automatically runs individual simulations for different load cases
 - Individual keywords and parts can be added for each individual load case
 - Use LS-PrePost for setup
- Sensors
 - The sensors can monitor responses (e.g. contact force and energy)
 - When sensor criterias are met, boundary conditions can start or stop
 - Useful for the prescribed motion of the impactors
 - Use LS-PrePost for setup

Conclusion and Future

- Workbench LS-DYNA is a user-friendly application to set up and run LS-DYNA models
 - In many cases the default settings are sufficient to run a structural explicit simulation
 - By using Keyword Snippets or LS-PrePost the functionality can be increased
- More functions and keywords will be available in the user interface
- DYNAmore Nordic will continue to work with Workbench LS-DYNA and further investigate the functionality in upcoming releases
- An introduction course is available on Ansys Learning Hub

Conclusion and Future



The screenshot shows the LS-DYNA website with a navigation bar at the top containing links for Products, Services, Support, Training, Company, and News. A search bar and download links are also present. The main banner features a large image of a conference hall with the text "13th European LS-DYNA Conference 2021" and a sub-headline stating the event will take place on October 5 and 6, 2021, in Ulm. Below the banner is a section titled "DYNAmore News" with a row of four thumbnail images: a mechanical assembly, a close-up of a mechanical joint, a software interface showing a simulation, and a 3D model of a mechanical part.

Links  Downloads  

DYNA
MORE

Products Services Support Training Company News

« **13th European LS-DYNA Conference 2021** »

The 13th European LS-DYNA Conference will take place on October 5 and 6, 2021 in Ulm.
[more »](#)

DYNAmore News »

Thank you!



Your LS-DYNA distributor and
more

