



LSTC
Livermore Software
Technology Corp.

Meshless Methods in LS-DYNA: An Overview of EFG and SPH

Yong Guo

Livermore Software Technology Corporation

LS-DYNA Seminar

Stuttgart, Germany

November 24, 2010



Outline

- 1. Introduction to Meshless Methods**
- 2. EFG and SPH in LS-DYNA**
- 3. EFG Applications**
- 4. SPH Applications**
- 5. Conclusions**

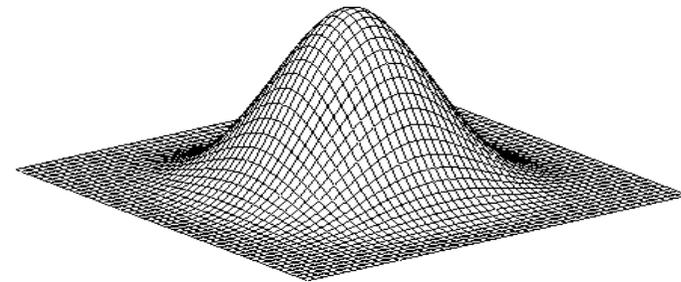
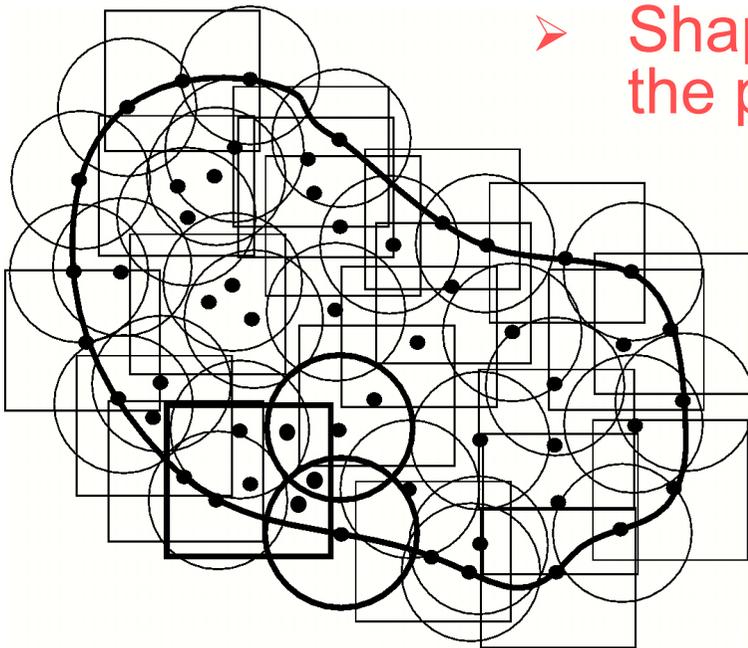


1. Introduction to Meshless Methods



What is the Meshfree/Meshless/ Particle Method?

- Physical domain is discretized with particles.
- Approximation solution is solved at the particles.
- Shape functions are constructed from the particles; no mesh required.



Meshfree Shape Function



History and Research Trend

● Meshfree Method

● Meshfree Collocation Method

- Smooth Particle Hydrodynamics (SPH) [Lucy1977, Monaghan 1980, Libersky1993]
- Finite Point Method [Onate et al.1996]

● Meshfree Galerkin Method

- Element Free Galerkin (EFG) [Belytschko et al. 1994]
- Reproducing Kernel Particle Method (RKPM) [Liu et al. 1995]
- Partition of Unity Method [Babuska and Melenk 1995]
- HP-Clouds [Duarte and Oden 1996]
- Free-Mesh Method [Yagawa et al. 1996]
- Natural Element Method [Sukumar et al.1998]
- Meshless Local Petrov-Galerkin Meshfree Method(MLPG) [Atluri et al.1998]
- Local Boundary Integral Equation (LBIE) [Atluri et al. 1998]
- Finite Sphere Method [Bathe 1998], Particle Finite Element Method [Idelsohn et al.2004] ...

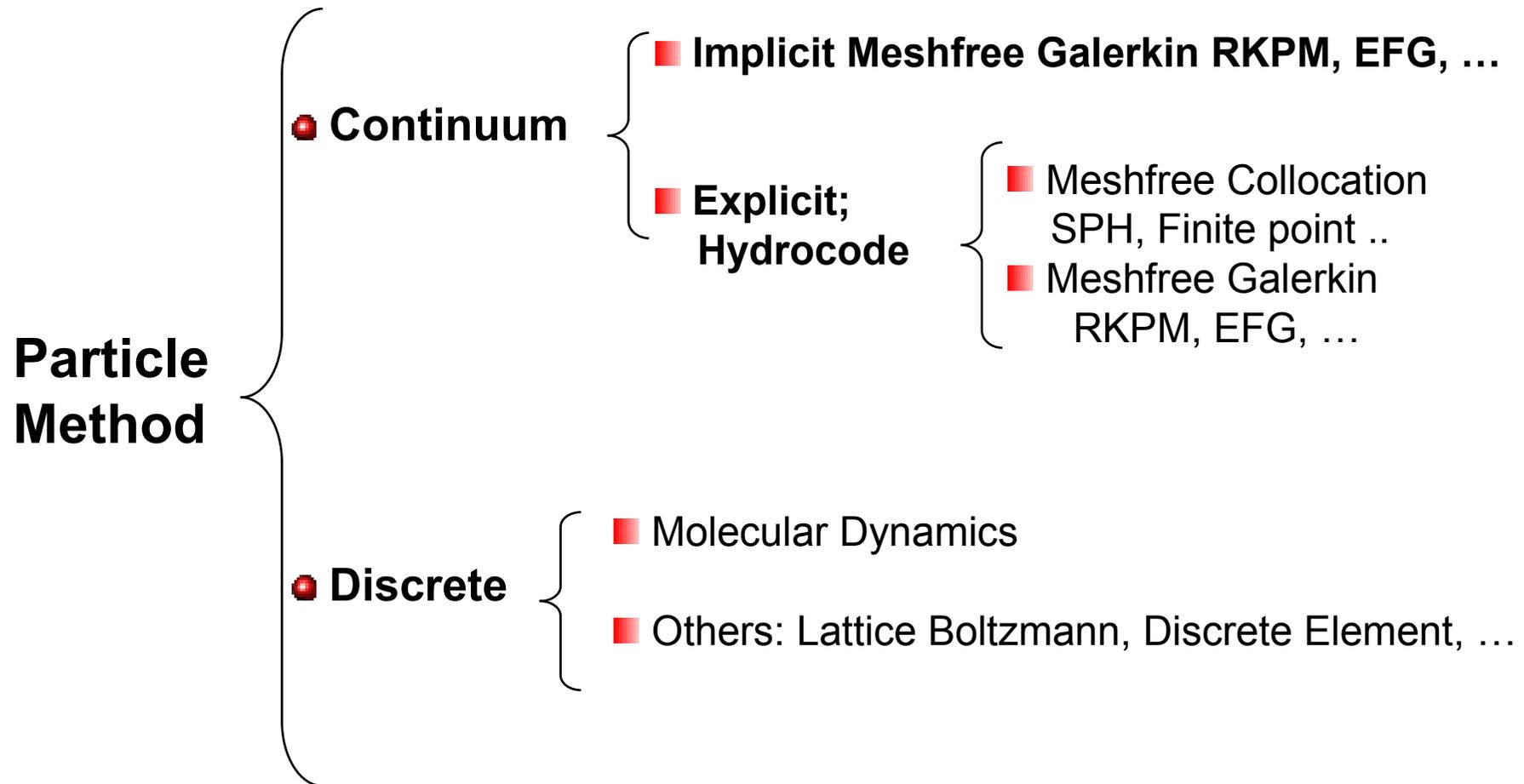
● Meshfree Least Square Method, ...

● (FEM, Control Volume, BEM ...) + Meshfree Method

- Coupled FEM/Meshfree Method [1995]
- Extended FEM Method [1999]
- Finite Particle Method [1999]



Classification of Particle Methods





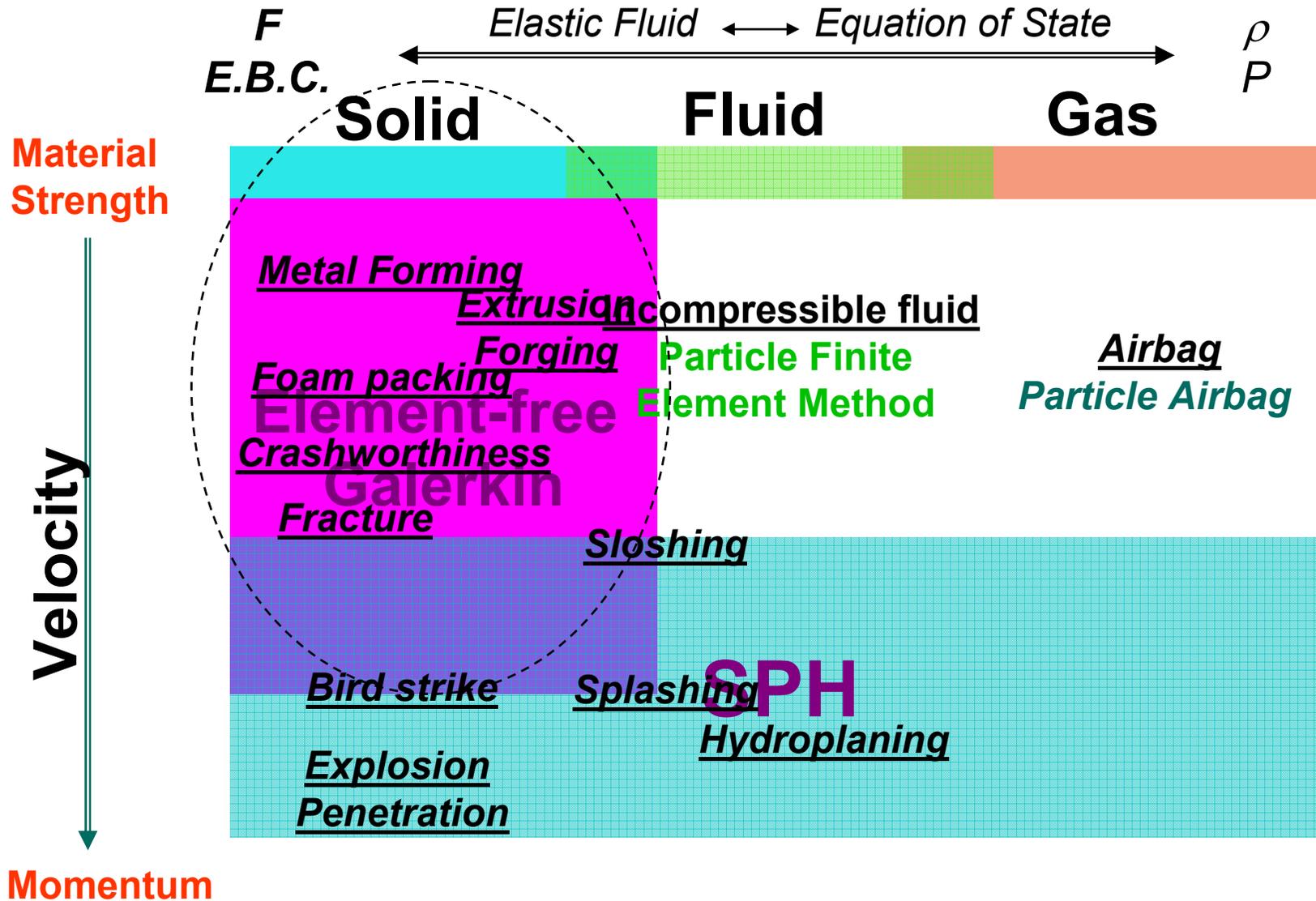
Classification of Transient Dynamic Code

- Hydrocode**
- **Lagrangian Hydrocode**
 - **FEM explicit**
(LS-DYNA, PAM-CRASH, ABAQUS ...) structure
 - **Smooth Particle Hydrodynamics (SPH)**
(LS-DYNA, PAM-CRASH, PRONTO3D ...) structure, fluid, fluid-structure
 - **Mesh-free Galerkin Explicit Method**
(LS-DYNA, TAHOE, DYNA) structure
 - **Semi-Lagrangian (Eulerian) Hydrocode; Adaptivity**
 - **Mesh-free Galerkin Explicit Method**
(LS-DYNA) structure, fluid, fluid-structure, metal forming adaptivity
 - **Arbitrary Lagrangian-Eulerian Hydrocode**
(LS-DYNA, MSC/DYTRAN, ALE3D, CALE ...) fluid-structure interaction
 - **Eulerian Hydrocode**
(LS-DYNA, MSC/DYTRAN, ALE3D, DYSMAS ...) fluid flow



Meshfree Application Range

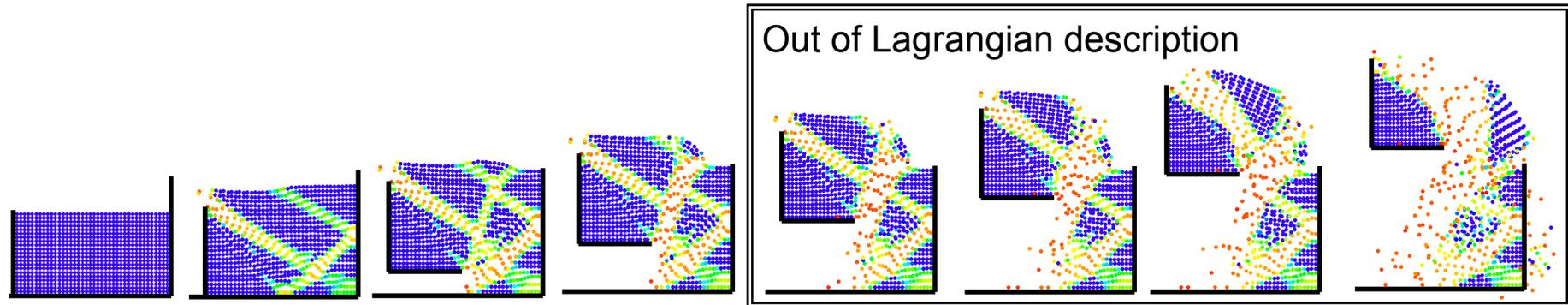
"Meshfree Solution looking for problems"





Problem Looking for Meshfree Solution

Multi-Physics : *shear band + history dependent large deformation + failure*



Numerical : *multi-resolution + avoid mesh tangle + failure mechanics*

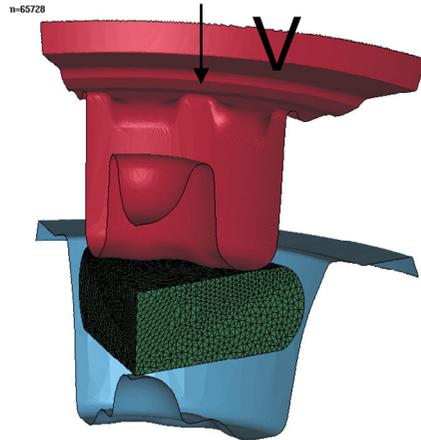
Spectral element method
The variational multiscale method
Partition of unity method
(strong discontinuity)

ALE
Eulerian
Adaptivity
Mesh-free

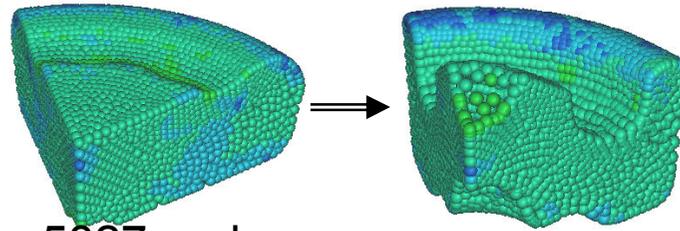
Damage mechanics
Cohesive model
Discrete element method



Large Deformation Simulation

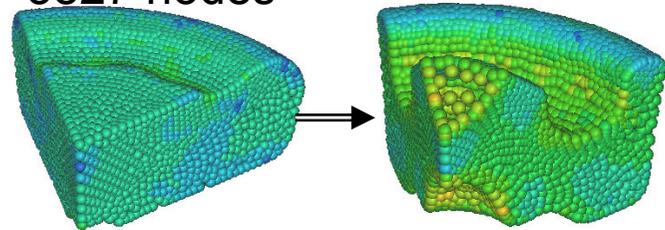


EFG

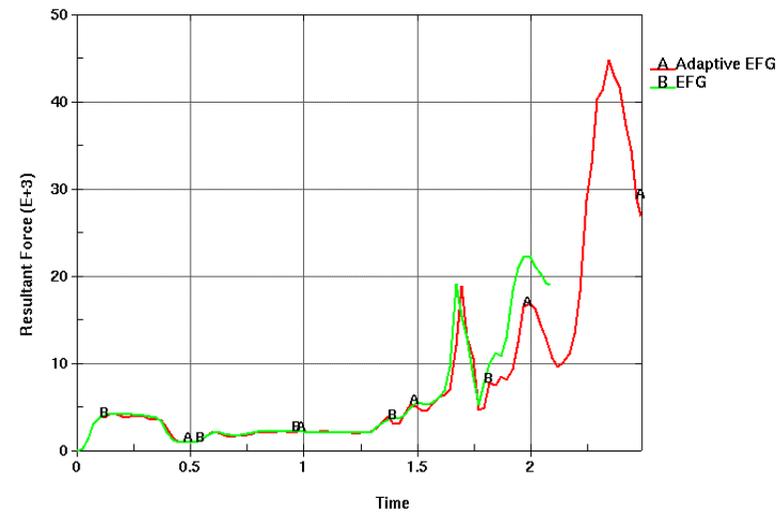
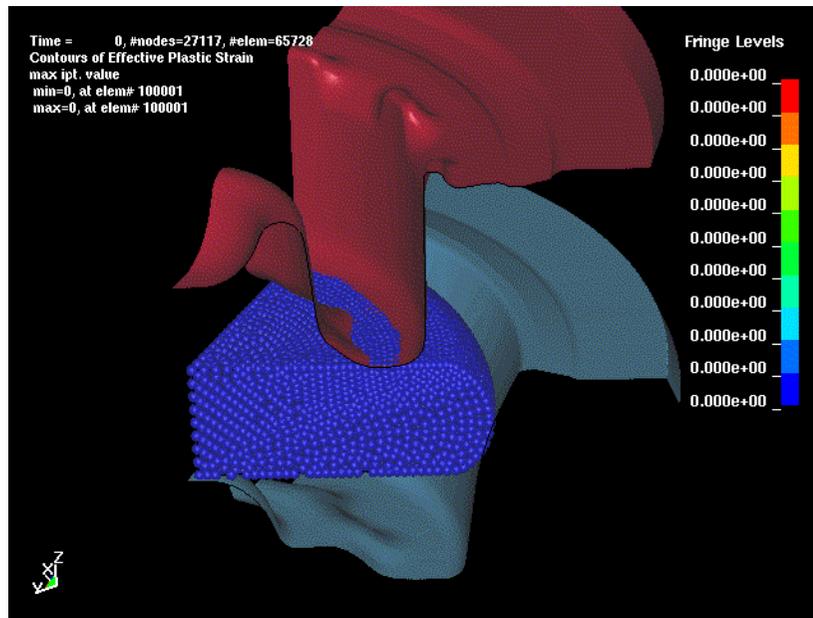
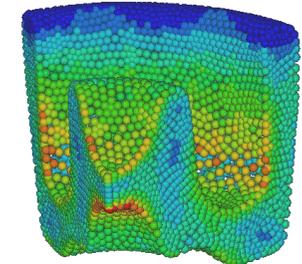


5827 nodes

EFG
Adaptivity



13661 nodes



Force



Overview on Element Free Galerkin Method (EFG)

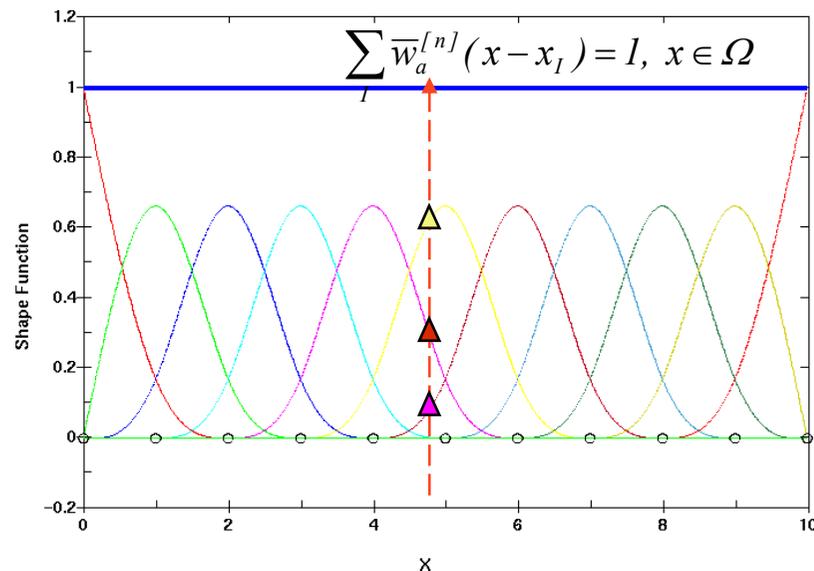
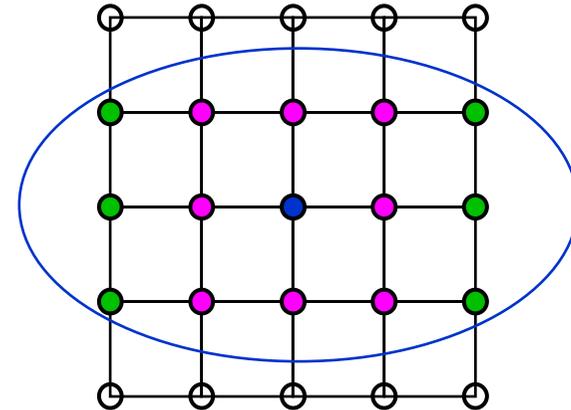
$$u^h(x) = \sum_{I=1}^{NP} \bar{w}_a^{[n]}(x - x_I) u(x_I) \Delta x_I$$

Moving Least-Squares approximation
or Reproducing Kernel approximation

$$\bar{w}_a^{[n]}(x - x_I) = \underbrace{\mathbf{H}^{[n]T}(0) \mathbf{M}^{[n-1]}(x) \mathbf{H}^{[n]}(x - x_I)}_{n\text{-th order completeness}} \underbrace{w_a(x - x_I)}_{\text{weighting function}}$$

$$\bar{w}_{aI}^{[n]}(x_J) \neq \delta_{IJ}$$

$$\mathbf{A}^{-T} \mathbf{M} \mathbf{A}^{-1} \Delta \ddot{\mathbf{d}} + \mathbf{A}^{-T} \mathbf{K} \mathbf{A}^{-1} \Delta \mathbf{d} = -\mathbf{A}^{-T} \mathbf{R}$$



- Higher-order approximation
- More neighboring nodes
- Complicated domain integration
- Special treatment on B.C.
- Special treatment in nearly incompressible limit



Overview on Smooth Particle Hydrodynamics (SPH)

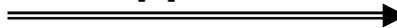
Basic SPH Equation of Motion

Strong Form

$\frac{d\rho}{dt} = -\rho \frac{\partial v^\beta}{\partial x^\beta}$
$\frac{dv^\alpha}{dt} = -\frac{1}{\rho} \frac{\partial \sigma^{\alpha\beta}}{\partial x^\beta}$
$\frac{dE}{dt} = -\frac{\sigma^{\alpha\beta}}{\rho} \frac{\partial v^\alpha}{\partial x^\beta}$

$$v(x) = Tu = \int_{-\infty}^{\infty} w_a(x-s)u(s)ds$$

Kernel approximation



Weak Form

$\frac{d\rho_i}{dt} = \rho_i \sum_j \frac{m_j}{\rho_j} (v_i^\beta - v_j^\beta) W_{ij,\beta} \quad \checkmark$
$\rho_i = \sum_j m_j W_{ij}$
$\frac{dv_i^\alpha}{dt} = -\sum_j m_j \left(\frac{\sigma_i^{\alpha\beta}}{\rho_i^2} + \frac{\sigma_j^{\alpha\beta}}{\rho_j^2} \right) W_{ij,\beta} \quad \checkmark$
$\frac{dv_i^\alpha}{dt} = -\sum_j \frac{m_j}{\rho_i \rho_j} (\sigma_i^{\alpha\beta} \pm \sigma_j^{\alpha\beta}) W_{ij,\beta}$
$\frac{dE_i}{dt} = \frac{\sigma_i^{\alpha\beta}}{\rho_i^2} \sum_j m_j (v_i^\alpha - v_j^\alpha) W_{ij,\beta} \quad \checkmark$

✓ in LS-DYNA 960, 970, 971



Comparison of SPH and EFG

SPH	EFG
Explicit Lagrangian Collocative method	Explicit/implicit Lagrangian/Eulerian Galerkin method
Impact/penetration compressible flow	Manufacturing Crashworthiness Fracture
2D and 3D	2D, 3D and shell
Efficient Difficult Boundary condition	Accurate Slow



● Advantages of Using Meshfree Method

- ✓ ■ Large material distortion, e.g., **crashworthiness, hyper-velocity impact**
- ✓ ■ Moving boundaries, free surface, e.g., **fluid and structure interaction**
- ✓ ■ Adaptive procedure, e.g., **forging and extrusion**
 - Multiple-scale phenomenon, e.g., **shear band**
- ✓ ■ Moving discontinuities, e.g., **crack propagation**

● Disadvantages of Using Meshfree Method

- High CPU and memory in implicit/explicit analysis (EFG)
- Complicated in parallel (EFG)
- Tensile instability and zero-energy mode (SPH)
- Difficult essential boundary condition treatment (SPH)
- Does not pass *Patch Test* (most mesh-free methods); Dispersed wave properties in coarse model



2. EFG and SPH in LS-DYNA



Element-Free Galerkin Method in LS-DYNA

LSTC
Livermore Software
Technology Corp.

- ❑ Applied to solids, shell and fluid (trial version)
- ❑ Fully coupled with finite element model
- ❑ Easy change from finite element formulation to EFG formulation
- ❑ Various formulations for industrial applications
- ❑ More effort spent on improving efficiency
- ❑ Available in SMP and MPP; Explicit/Implicit solver



Representative EFG Applications

EFG Basic Features

1. Smoother stress and strain
2. Less sensitive to the discretization
3. No hourglass control
4. Higher accuracy
5. Natural in adaptivity
6. Higher CPU
7. More memory
8. Difficult in parallel
9. More difficult in theory
10. More developments and refinements on theory

• Solid

- EFG Plane strain #43
- EFG Axisymmetric #44
- EFG 3D solid #41
#42

- Rubber industry
- Highly compressible foam
- Defense and safety design
- Human dummy and barrier
- Adaptive forging simulation
- Fracture simulation

• Shell

- EFG shell #41
- EFG shell #42

- Metal Forming
- Crashworthiness

• Fluid

- EFG 3D fluid #41
(limited version)

- Compressible fluid flow



Current EFG Formulations for Industrial Applications

- **Metal materials in Forging/Extrusion analysis: Adaptive formulation**
 - **Foam materials: Semi-Lagrangian kernel formulation**
 - **Rubber materials: Lagrangian kernel formulation**
- Stabilized Method**
- **Meshfree Shell: Lagrangian kernel, adaptivity**
 - **Quasibrittle material fracture: Strong discontinuities formulation**
 - **E.O.S. materials: Eulerian kernel formulation (trial version)**



- ◆ CPU time

RI FEM: SR FEM : Meshfree (8 I.P.) = 1: 4: 10

- ◆ Stabilized Meshfree formulation (1 I.P.) +

Switch to fully integrated (8 I.P.)

RI FEM: SR FEM : Meshfree (8 I.P.) = 1: 4: 3~5

- ◆ 99% > Compression > 85% requires

Formulation change to Eulerian kernel + data remapping **or**

Smooth meshfree approximation



- ◆ CPU time

FEM: Meshfree = 1: 2~3

- ◆ Global refinement behaves more robust than local refinement
- ◆ Adaptivity can be controlled by fixed frequency or interactively activated by distortion triggers.
- ◆ Mass scaling is allowable.
- ◆ Element erosion is allowed and surface reconstructed for metal cutting.



Smooth Particle Hydrodynamics in LS-DYNA

LSTC
Livermore Software
Technology Corp.

- A Lagrangian collocative method – explicit
- Efficient
- Choices of formulations to improve accuracy
- Applied for Impact/Penetration, In/compressible Flow
- Most material laws and all E.O.S are available
- Coupled with Finite Elements through 3 contacts or hybrid element
- Implemented in MPP version



IFORM : Particle approximation theory

0 : standard formulation (default)

1 : renormalized formulation

2 : symmetric formulation

3 : symmetric formulation with renormalization

4 : elliptical formulation

5 : fluid formulation

6 : fluid formulation with renormalization



3. EFG Applications

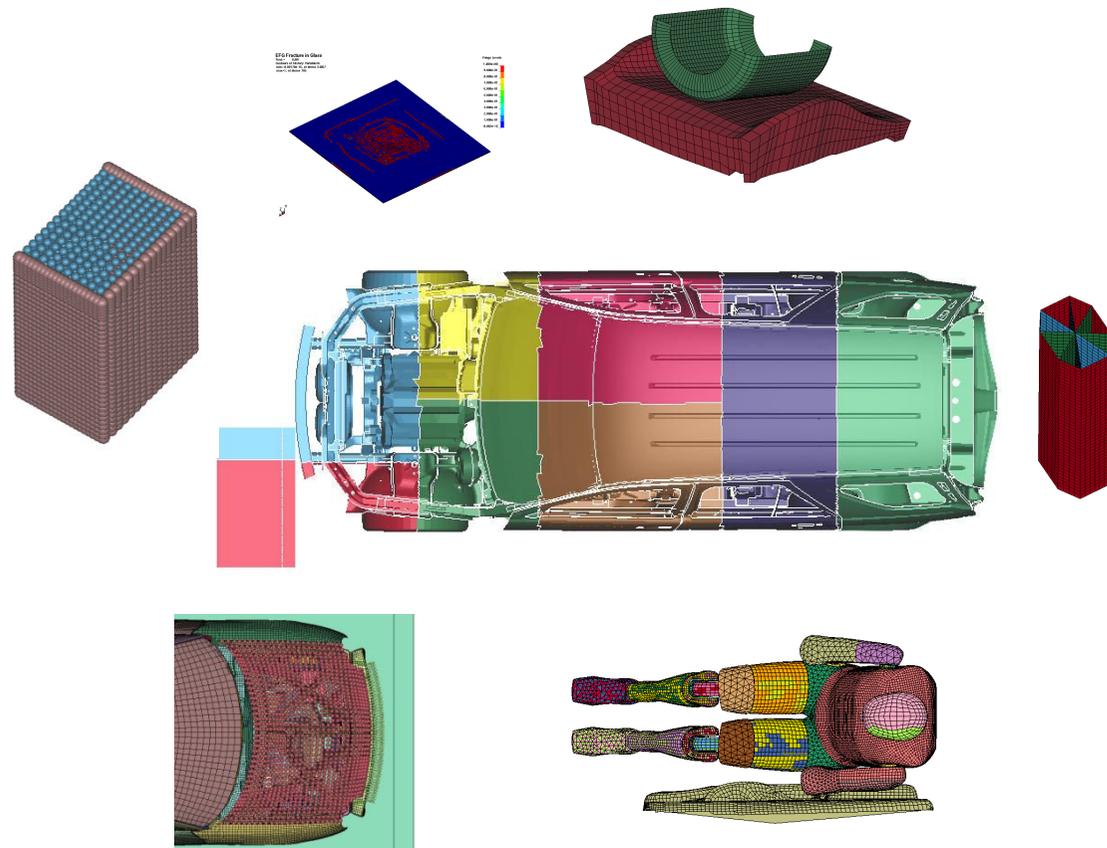


Meshfree Applications in Production Level

Robustness > Efficiency > Accuracy ?

Meshfree Components in Crashworthiness Model

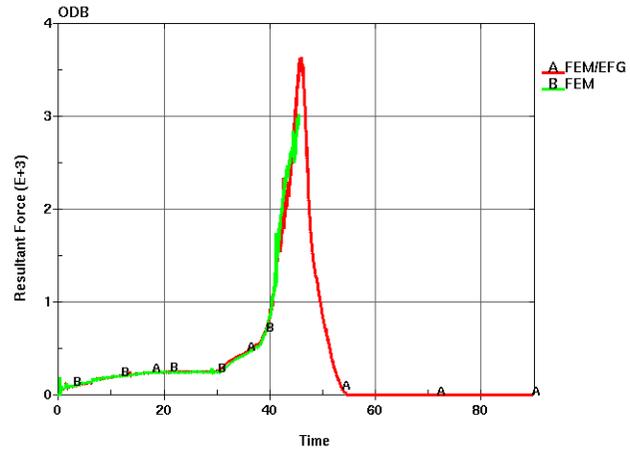
- Barriers; bumpers
- Car seats
- Human dummies
- Crush tubes
- Windshields
- Fuel slashing
- ...



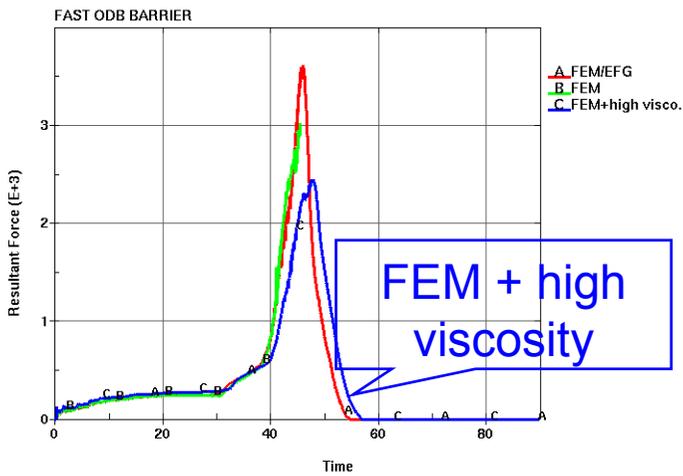
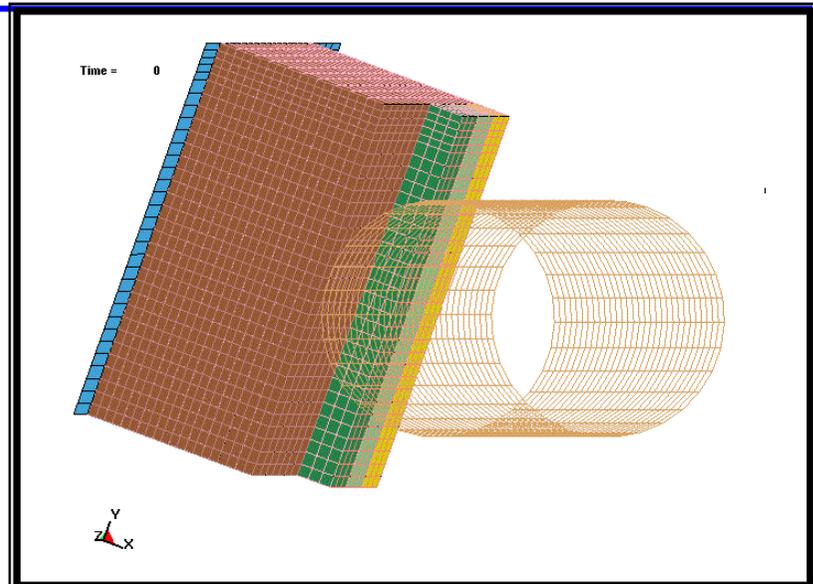


ODB Simulation

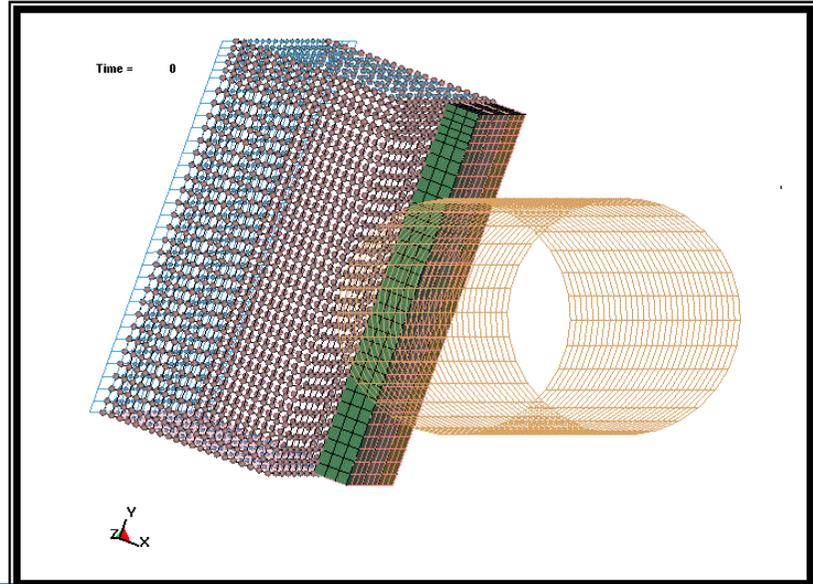
Impact Force



FEM

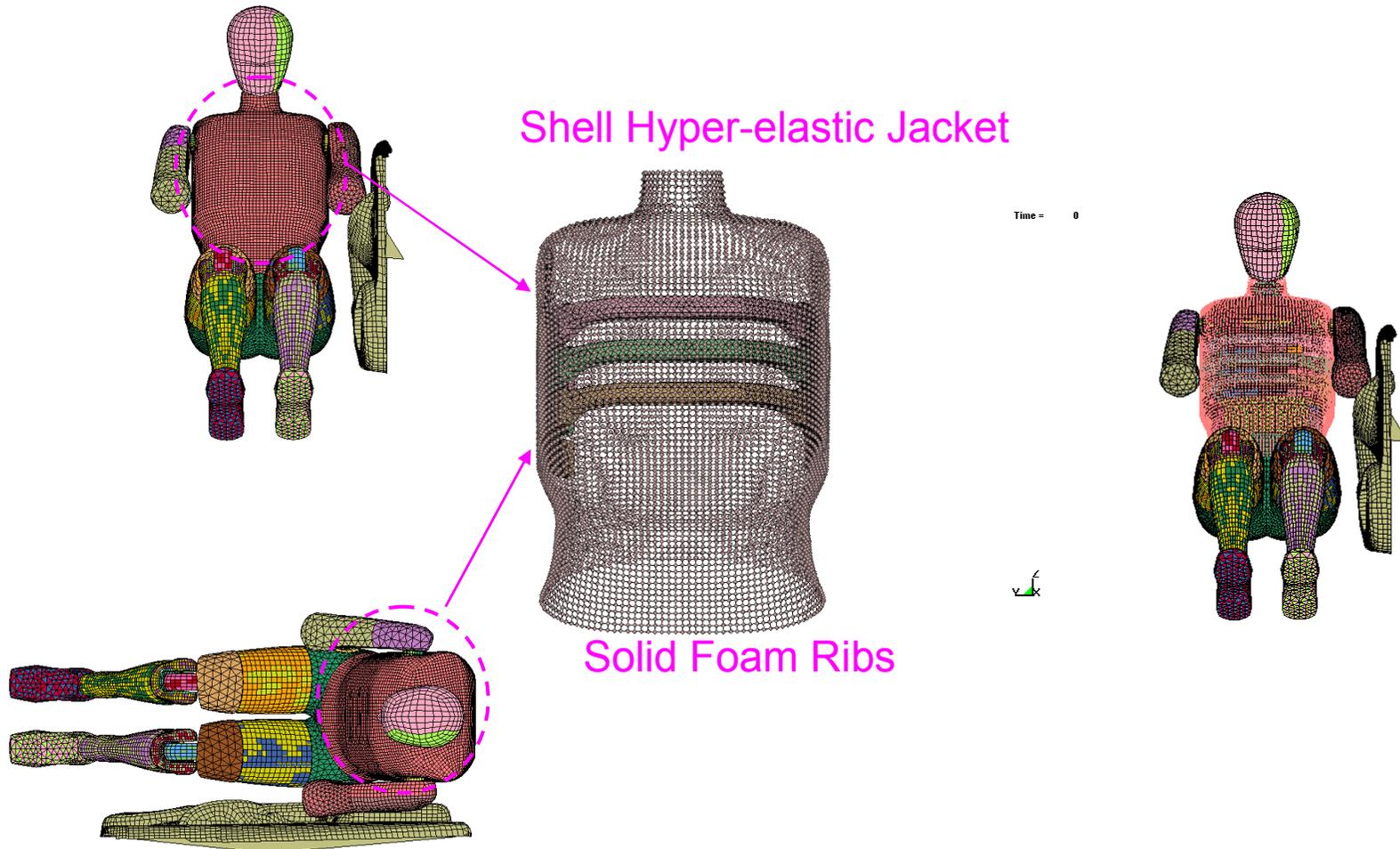


FEM/Meshfree





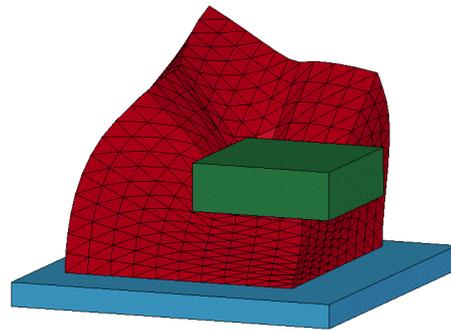
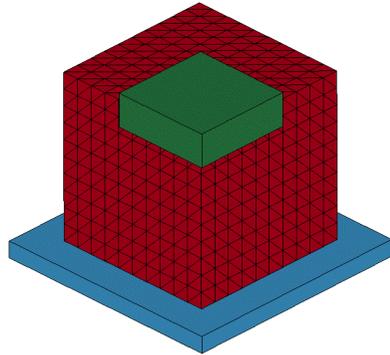
Dummy with Side Impact



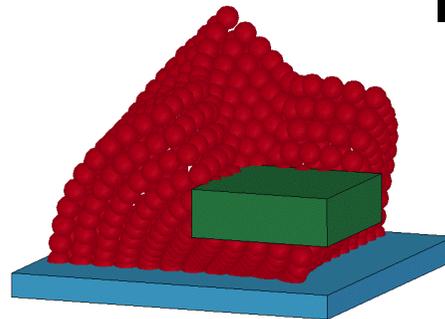
Courtesy of GM



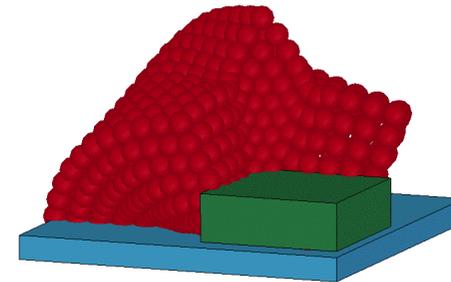
Foam Compression Simulation



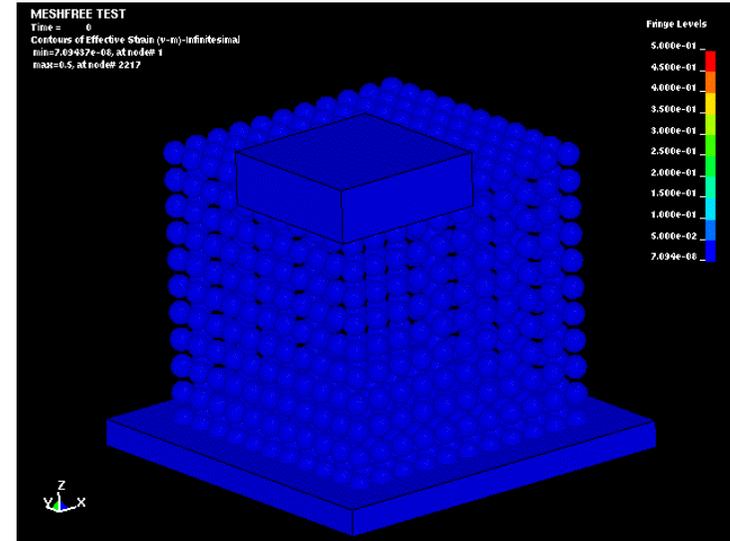
FEM



EFG



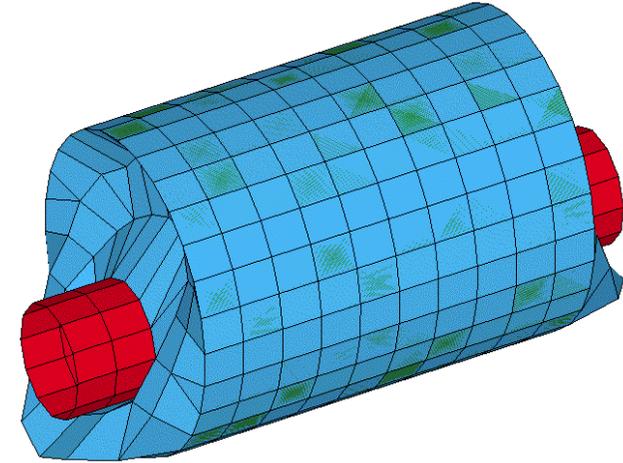
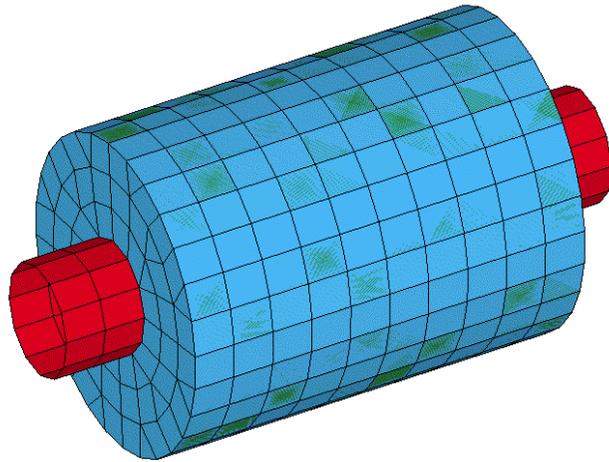
EFG +
Semi-Lagrangian Kernel



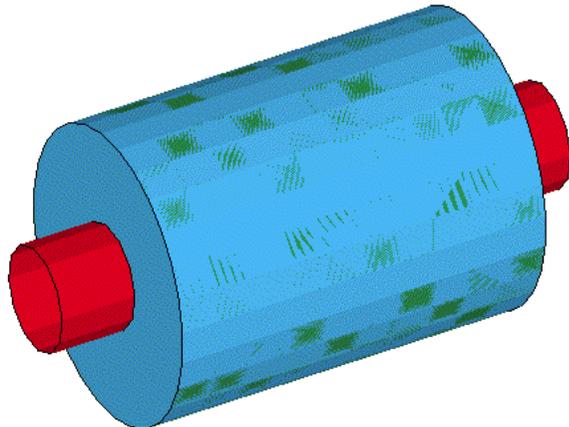
Foam materials : Semi-Lagrangian kernel



Rubber Bushing Analysis using Stabilized EFG Method



Time = 0



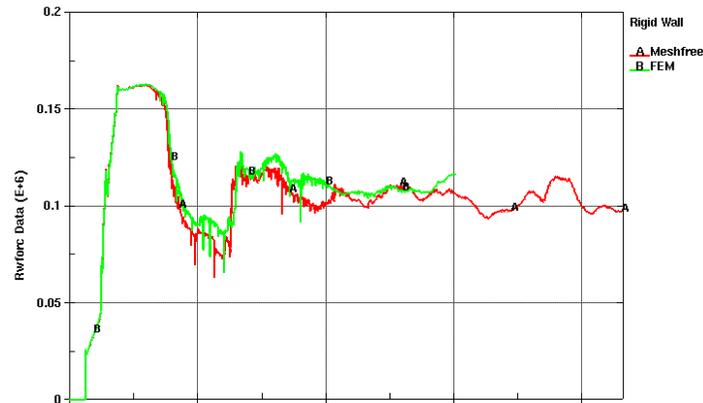
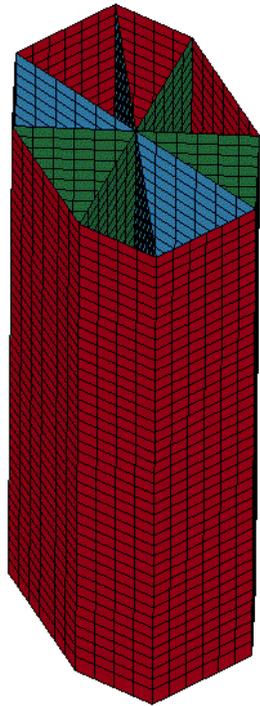
Mooney-Rivlin Rubber
Poisson's = 0.4995
Stabilized EFG explicit analysis
Switched to full integration at t=100
Completion at t=150

CPU comparison at t=50

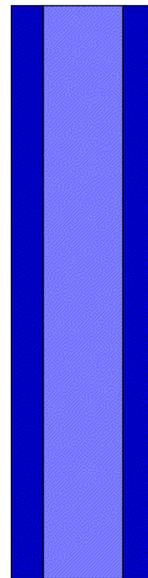
Methods	S-FEM(#1)	F-FEM(#2)	EFG	S-EFG
CPU	1.0	4.1	5.4~12.9	2.6



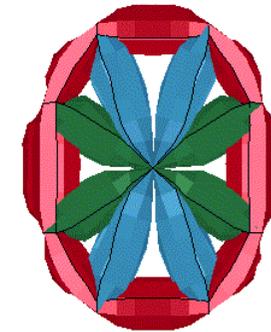
Crushing Tube



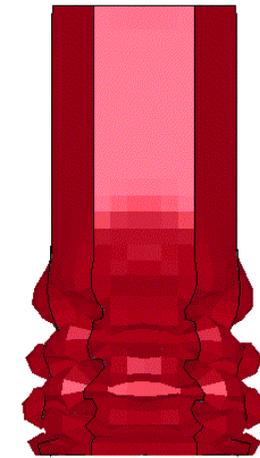
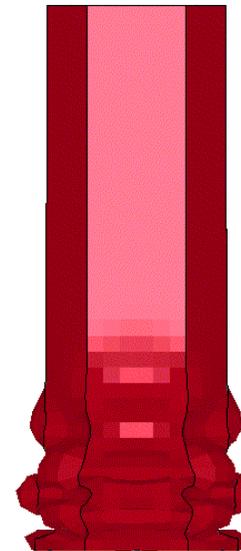
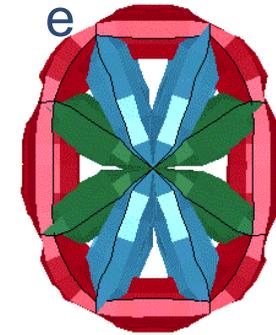
Time = 0
Contours of Effective Plastic Strain
max ipt. value
min=0, at elem# 1
max=0, at elem# 1



FEM



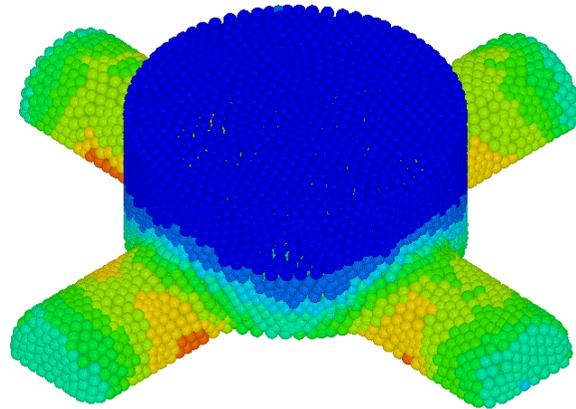
Meshfre



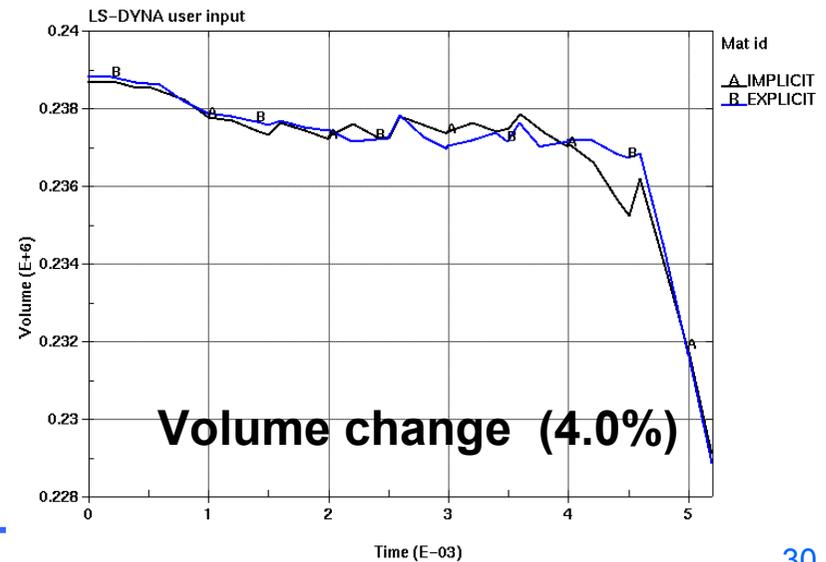
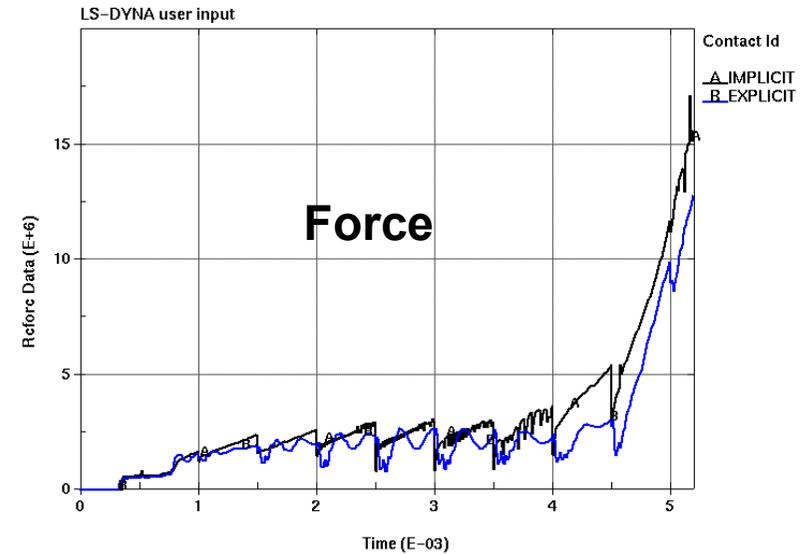


Cross Joint Forging

Comparisons of Implicit and Explicit Analysis

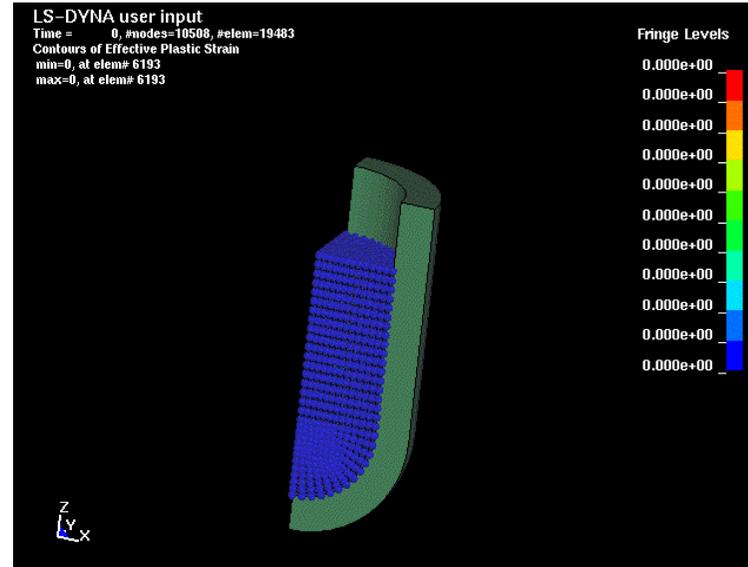
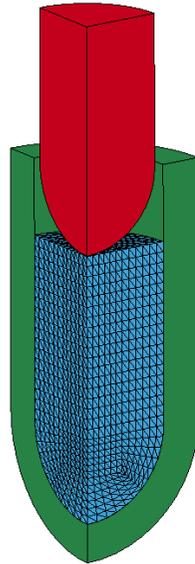


LS-DYNA user input
Time = 0, #nodes=160969, #elem=150163
Contours of Effective Plastic Strain
max ipt. value
min=0, at elem# 34001
max=0, at elem# 34001

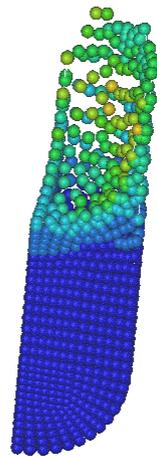




Metal Extrusion



2769 nodes



EFG



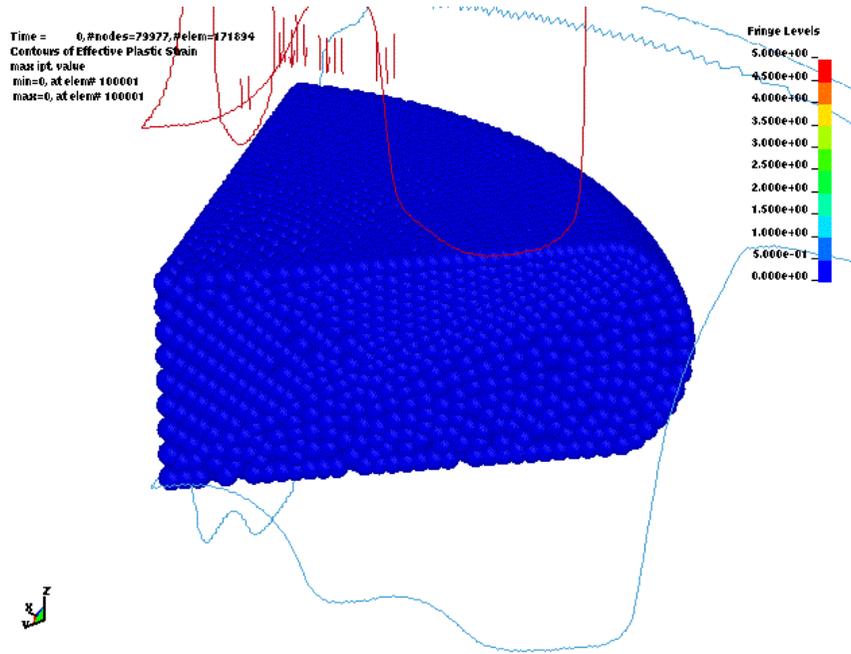
10410 nodes

Adaptive EFG



Wheel Forging Simulation

Interactive Adaptivity



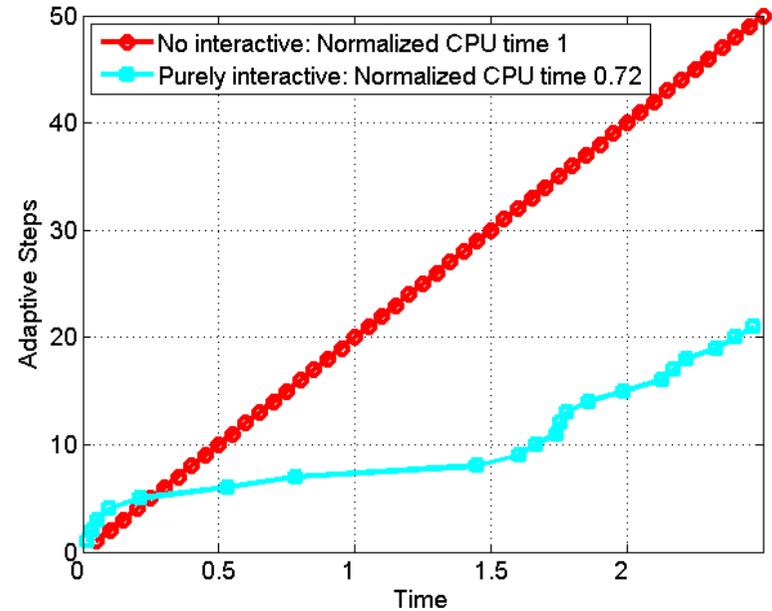
```

*CONTROL_ADAPTIVE
      2.5 ...
...
*CONTROL_REMESHING_EFG
      0.15      0.30
           3           1
      0.20      3.5      0.80
  
```

* SMP with 6 CPUs Traditional adaptivity

IAT	0	3
Normalized CPU time	1.0	0.72
# of adaptive steps	50	22

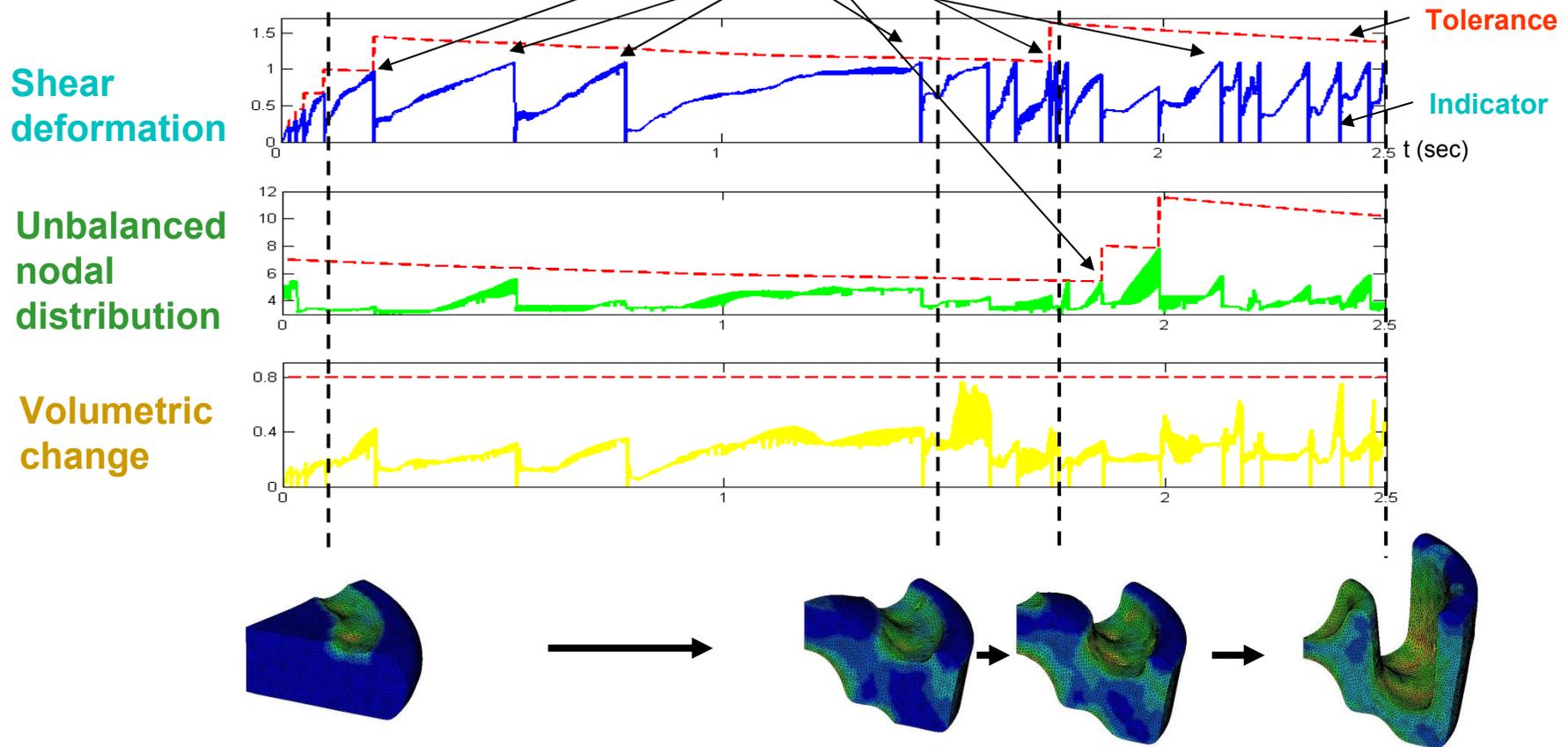
Purely interactive adaptivity





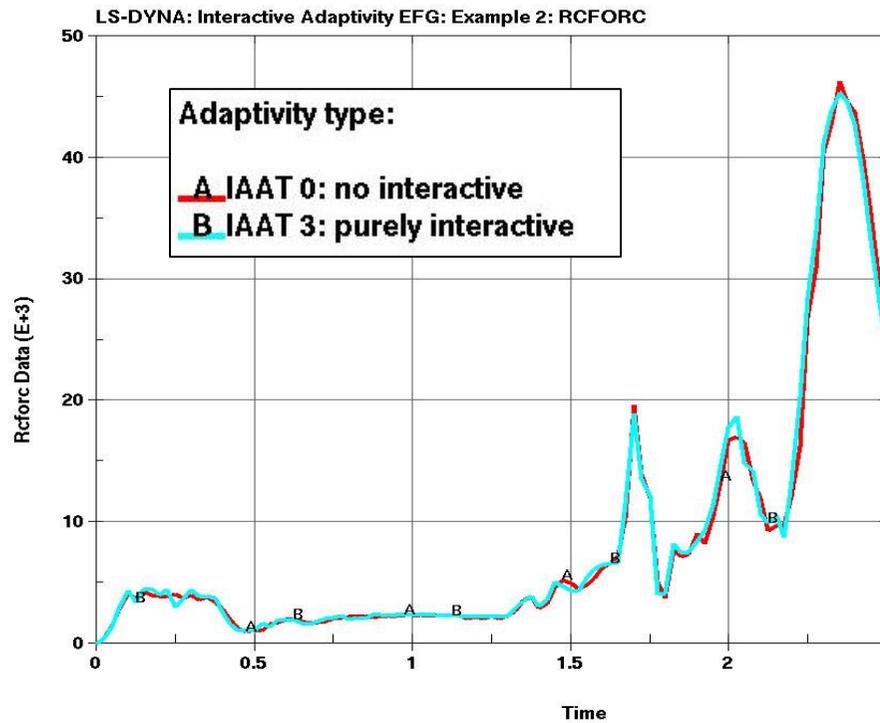
Wheel Forging Simulation

Interactive adaptivity triggered by *indicators*
Interactive adaptivity triggered by *rate of indicator change*

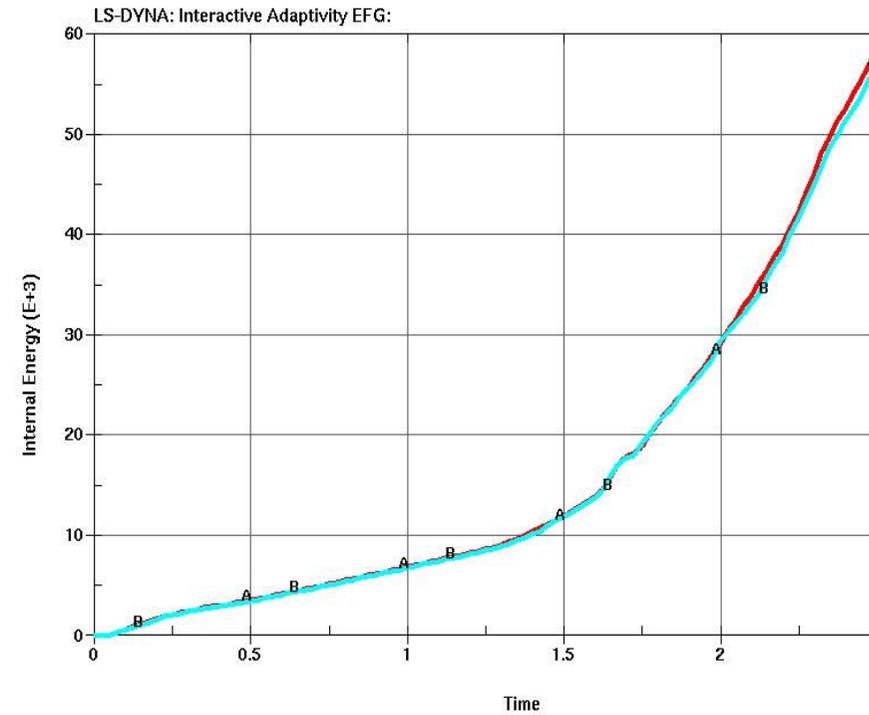




Wheel Forging Simulation



Contact force

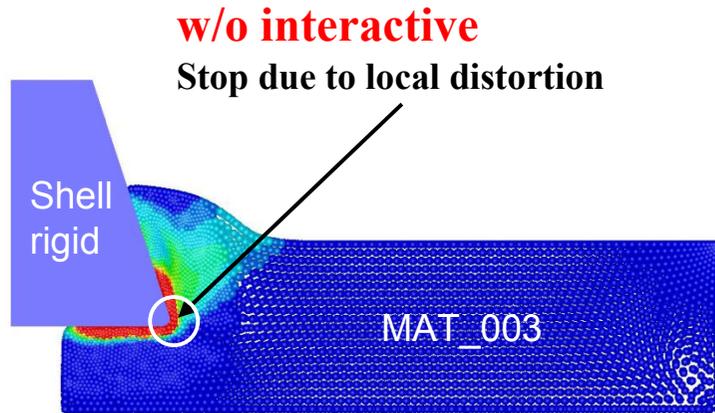


Internal energy



Metal Cutting Simulation

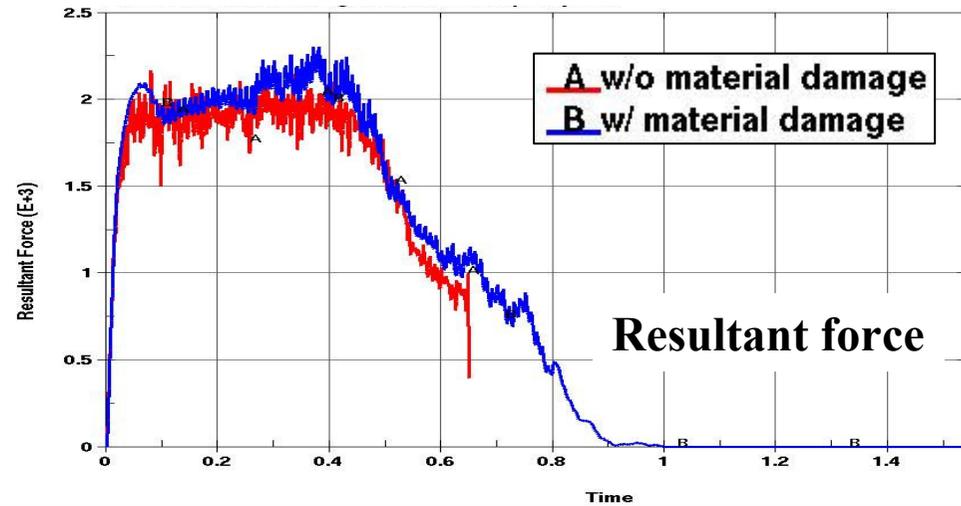
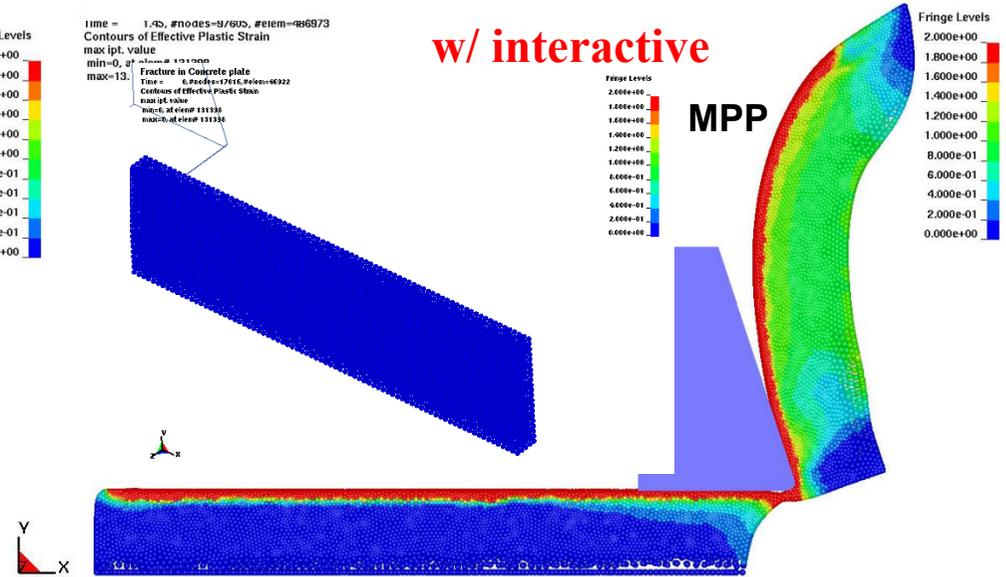
Time = 0.22215, #nodes=34081, #elem=139321
Contours of Effective Plastic Strain
max ipt. value
min=0, at elem# 131398
max=40.77, at elem# 24112



Fringe Levels
2.000e+00
1.800e+00
1.600e+00
1.400e+00
1.200e+00
1.000e+00
8.000e-01
6.000e-01
4.000e-01
2.000e-01
0.000e+00

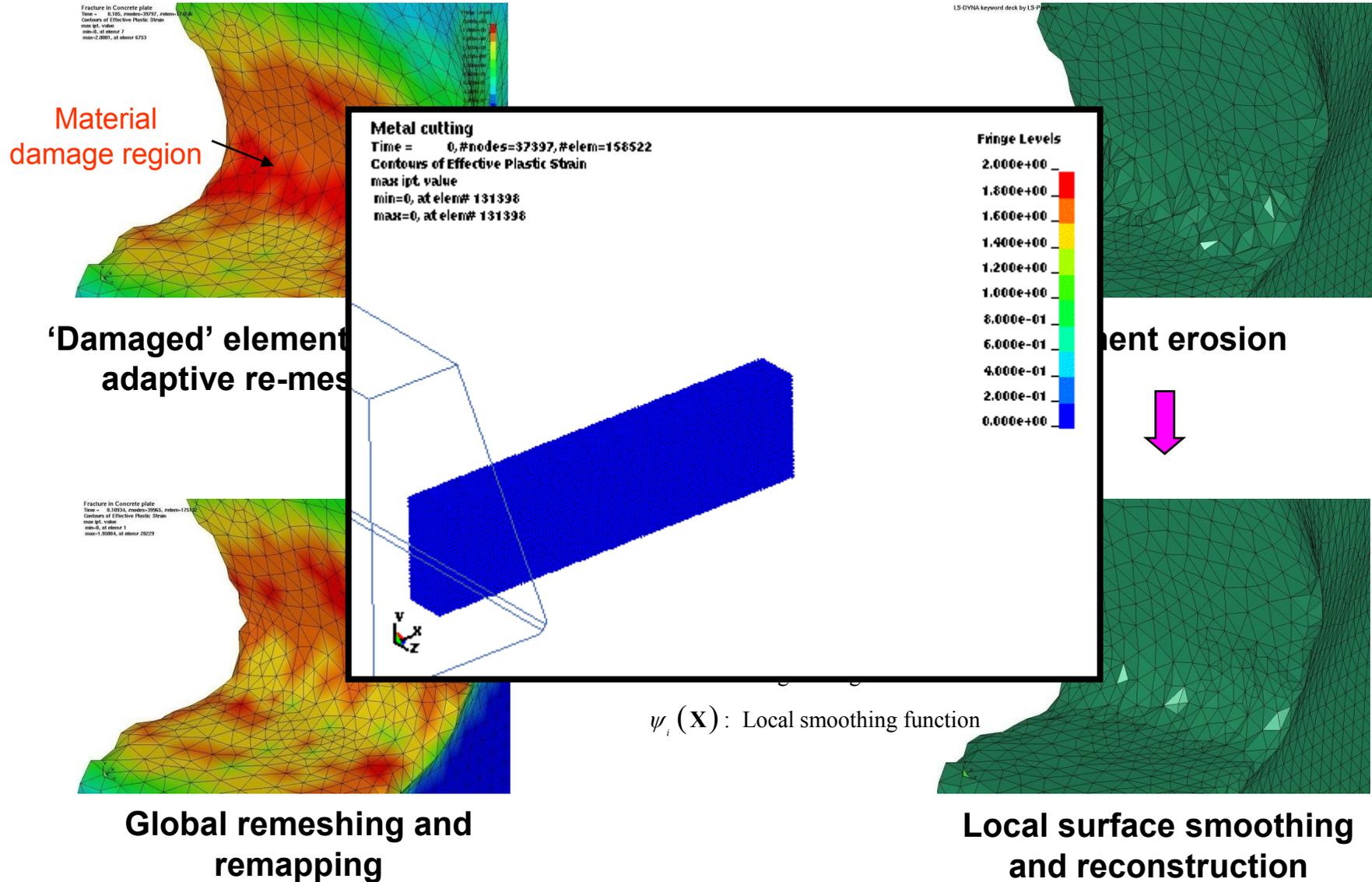
Time = 1.73, #nodes=97605, #elem=486973
Contours of Effective Plastic Strain
max ipt. value
min=0, at elem# 131336
max=13, at elem# 131336
Fracture in Concrete plate
Time = 0.22215, #nodes=34081, #elem=139322
Contours of Effective Plastic Strain
max ipt. value
min=0, at elem# 131338
max=40.77, at elem# 24112

w/ interactive





Metal Cutting Simulation





4. SPH Applications



High Velocity Impact

CONFIGURATION:

Projectile:

material: 304 L Steel

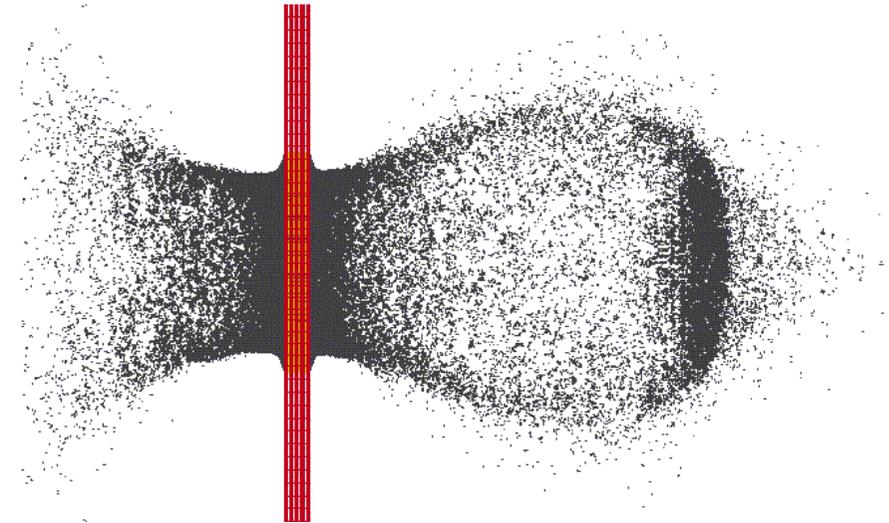
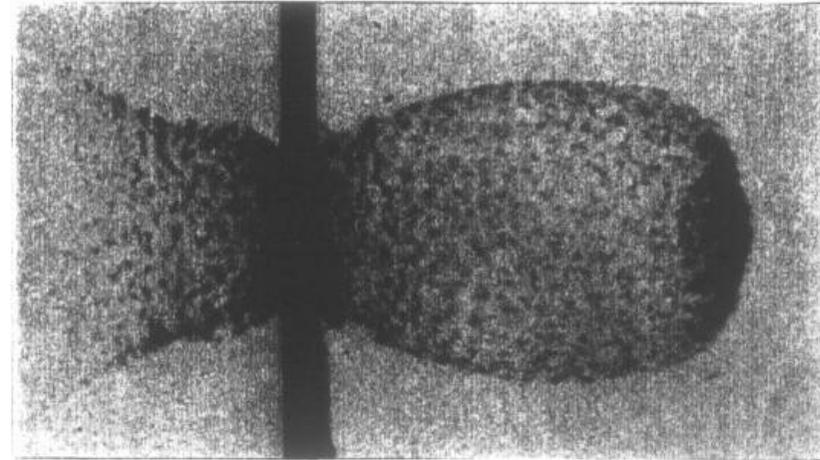
velocity: 5530 m/s

geometry :sphere, $\phi = 5$ mm

Target :

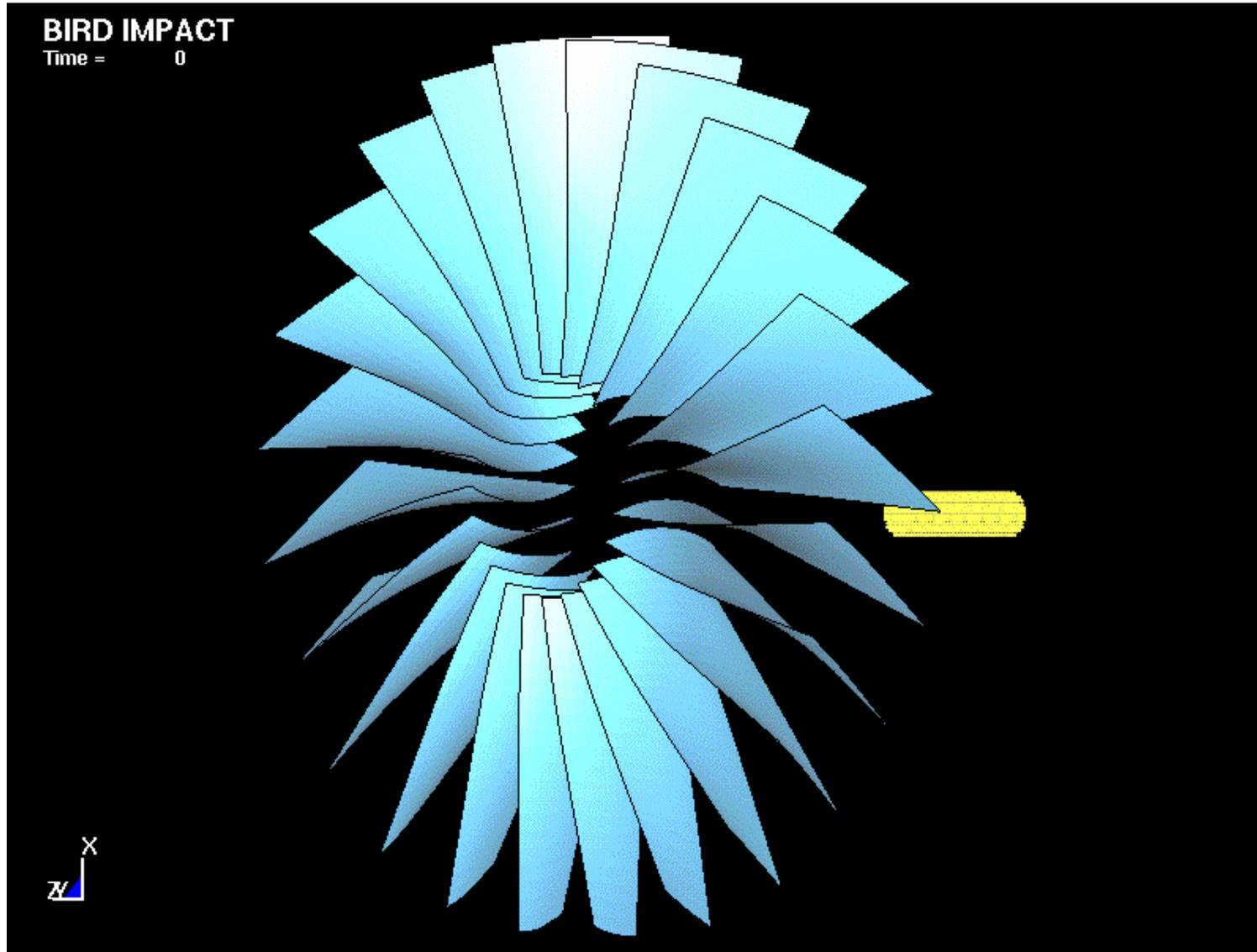
material: 6061-T651 Al

Thickness : 2.85 mm



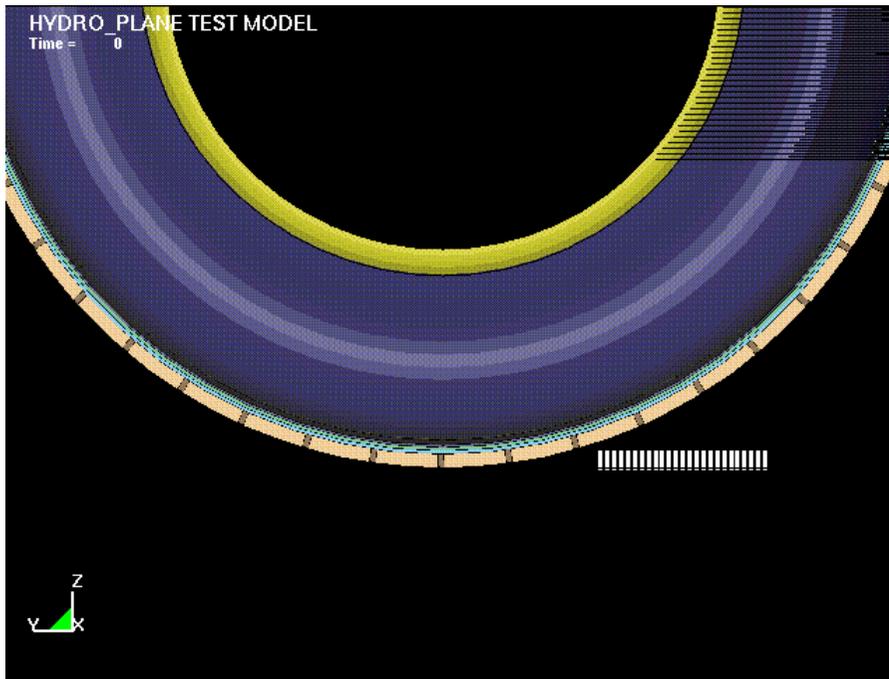


Bird Strike

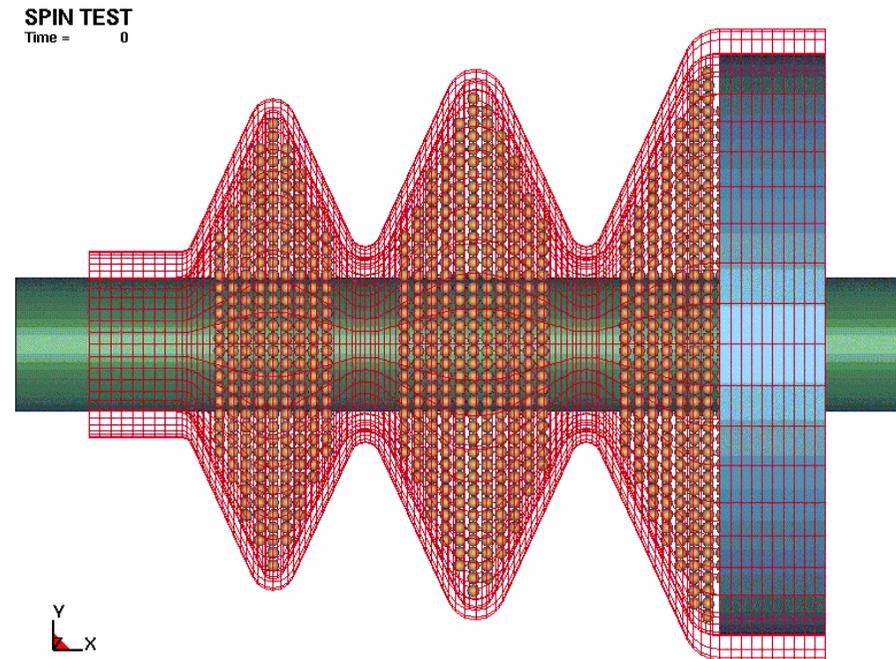




Automotive Applications



Hydro-plane



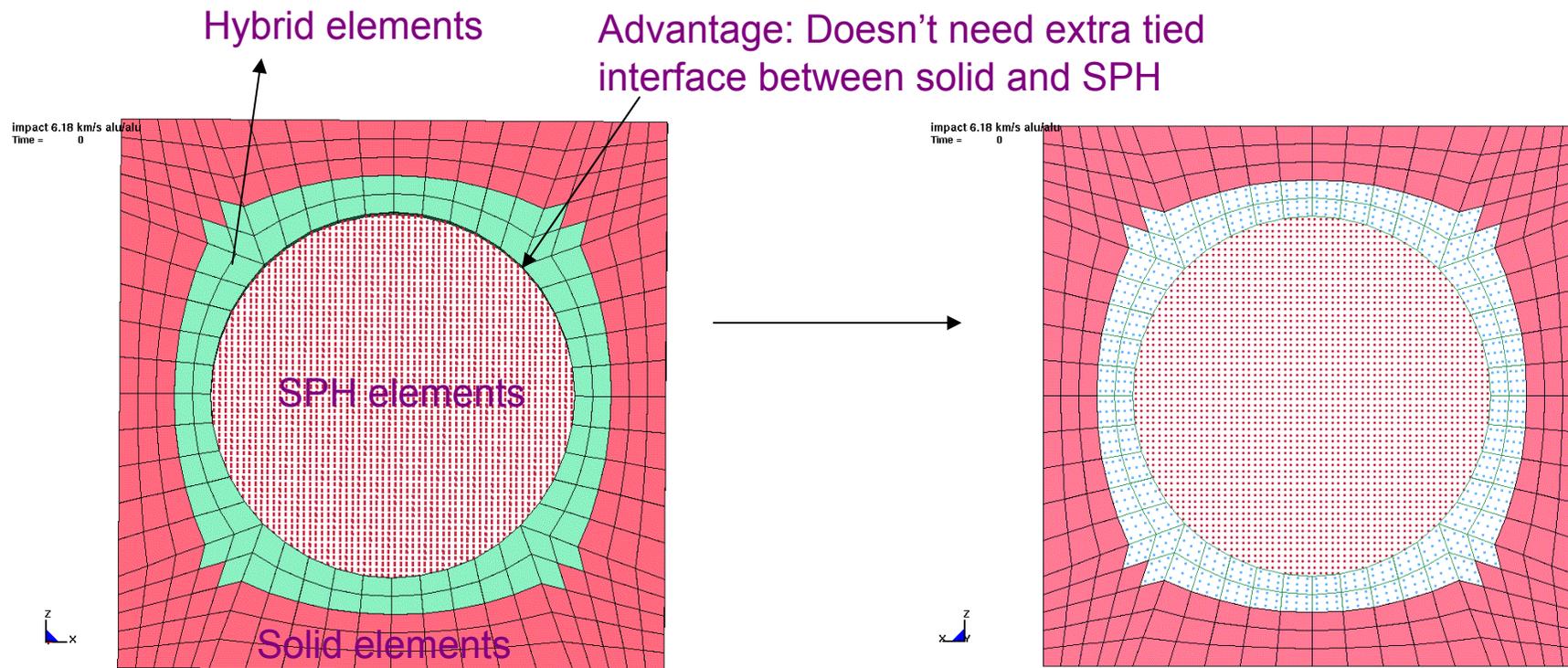
Spin test



Hybrid Element Coupling SPH with Solid

Hybrid element: Solid elements constrain SPH nodal locations. SPH elements provide "penalty force" against solid nodal motion. Hybrid elements are used as transit layers between SPH elements and solid elements. (shared part ID)

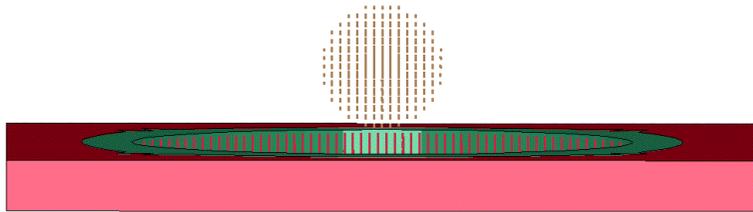
Advantage: We have the SPH formulation which can endure quite large deformation and at the same time we have the solid mesh which clearly describes the material interface.



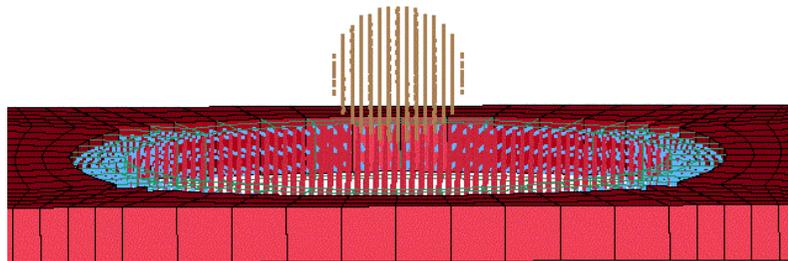


Impact Example

Impact 6.18 km/s alu/alu
Time = 0



Set up

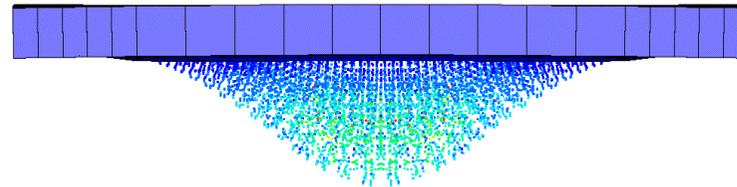
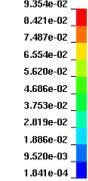


Coupling layers



Impact 6.18 km/s alu/alu
Time = 22.491
Contours of Effective Stress (v-m)
min=0.000184083, at node# 1
max=0.0535444, at node# 10006354

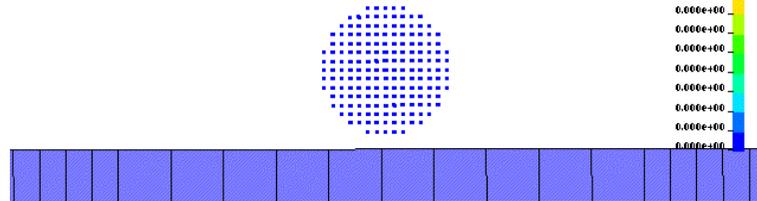
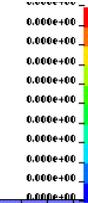
Fringe Levels



Final shape



min=0, at node# 1
max=0, at node# 1



Effective stress





5. Conclusions

- Meshfree methods can solve problems that finite element methods have difficulties.**
- EFG in LS-DYNA provides engineers a powerful tool with robustness, efficiency and accuracy.**
- EFG has been successfully applied to crashworthiness, metal forging/extrusion, and can be used in metal cutting and fracture analysis.**
- SPH in LS-DYNA is an efficient tool for high velocity impact, penetration and can simulate solid, fluid materials.**