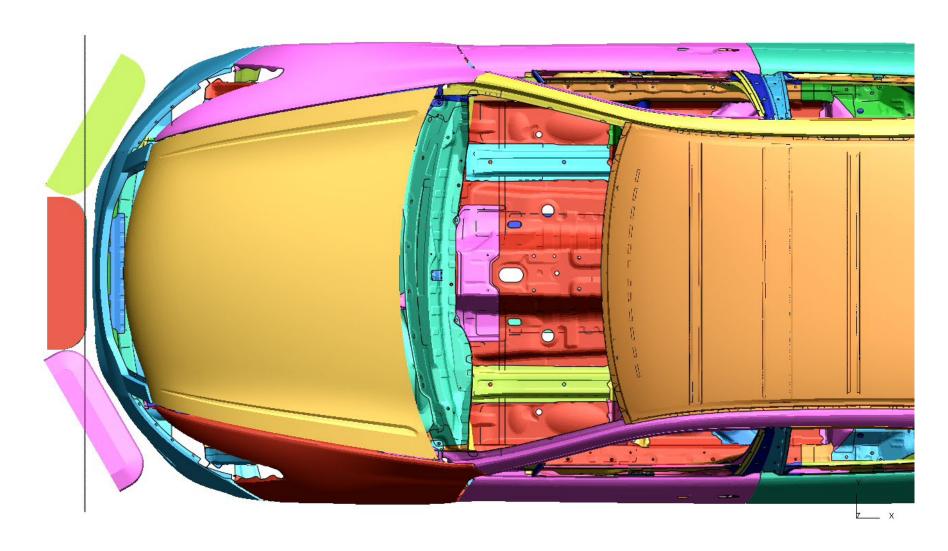


Multi-stage Analysis Approach to Low-Speed Vehicle Impacts using the *SENSOR Keywords

14th European LS-DYNA Conference



Low-Speed Vehicle Impacts Analysis





Bumper Regulations

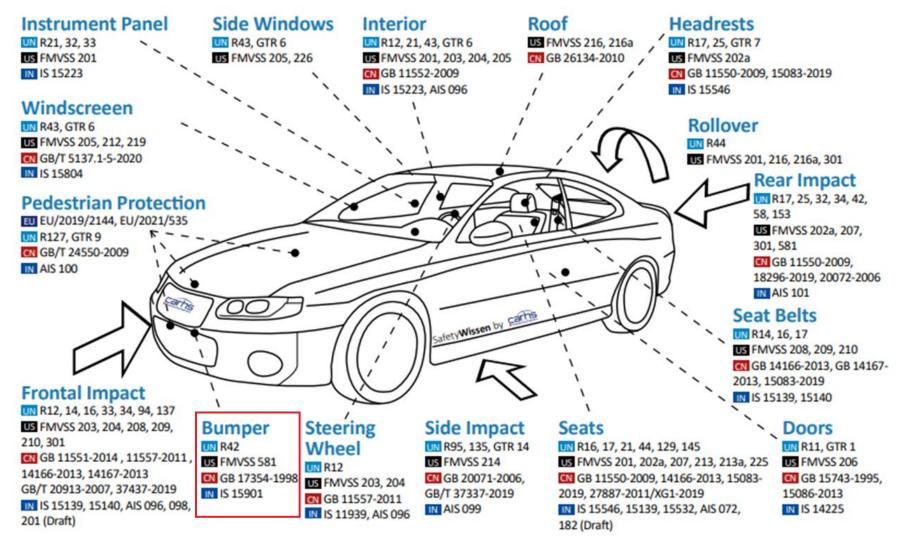
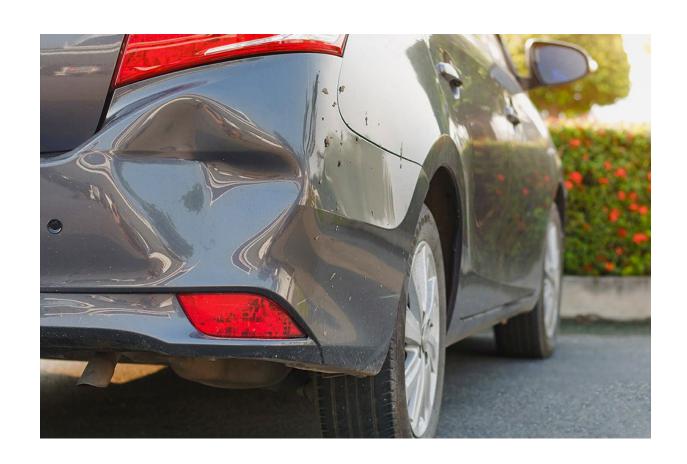


Image taken from Carhs Safety Companion 2023 (page 21)



Bumper Regulations

Purpose



Minimise vulnerability to damage and reduce repair costs resulting from low-speed front and rear collisions.



Bumper Regulations

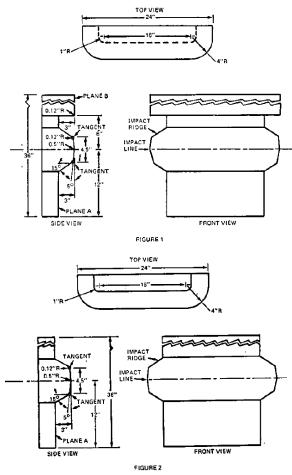
FMVSS CFR 581

Successive impacts are performed on the same vehicle. The bumper and supporting structure cannot be replaced or repaired between impacts.

- 1. Right-hand corner impact 1.5 mph
- 2. Left-hand corner impact 1.5 mph
- 3. Longitudinal impact 2.5 mph
- 4. Longitudinal impact 2.5 mph
- 5. Flat wall impact -2.5 mph



Test Rig



Pendulum Drawings a.) double ridge b.) single ridge

Images taken from:



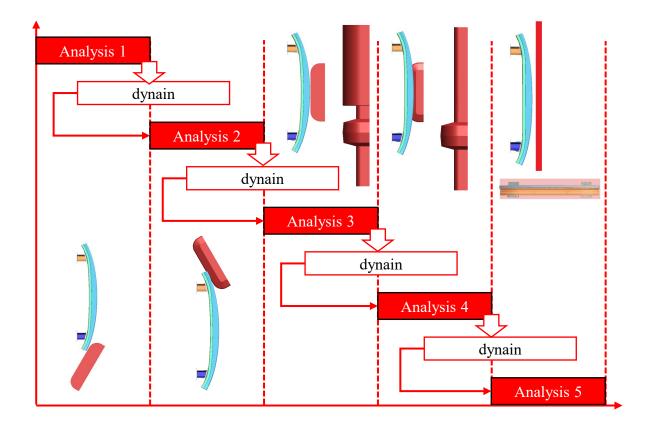
CAE Analysis Approach

Legacy Methodology

Run each analysis individually with necessary information transferred to the next impact.

Limitations

- Transfer ('dynain') files can be large
- Requires modification of master model to remove data included within transfer file
- Intermediate model modification steps



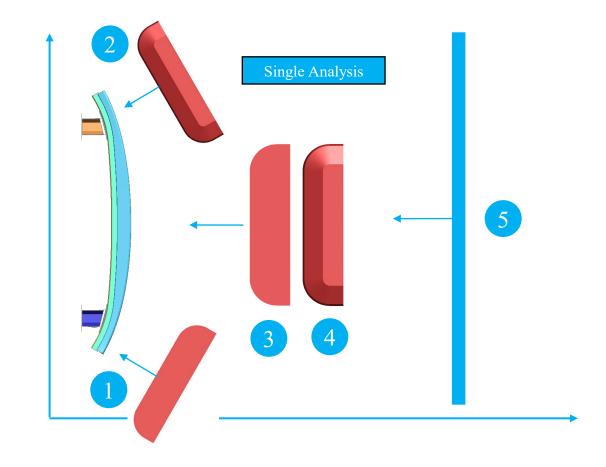


CAE Analysis Approach

Improved Methodology

Combine the sequential analysis into a single analysis with the following functionality:

- 1. Detect when one impact is over
- 2. Slow the vehicle down and bring it to a full stop
- 3. Initiating the next impact in the sequence
- 4. Terminate analysis once all impacts have taken place





What is a sensor?



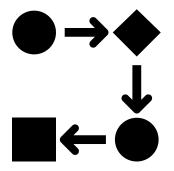
Devices that respond to a physical input and transmit a resulting output



Sensors in LS-DYNA

In LS-DYNA, the *sensor keywords provides a convenient way of activating and deactivating other keywords based on model responses.

Possible applications:



Multi-staged analyses



Termination control



*SENSOR Keywords

3 definitions are required to define and utilise a sensor:

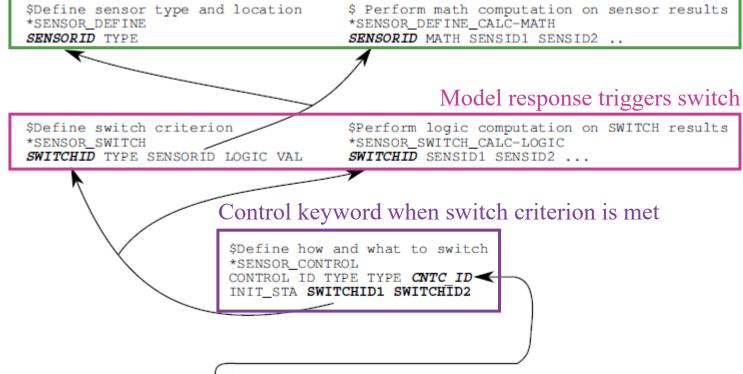
*SENSOR DEFINE

*SENSOR SWITCH

*SENSOR_CONTROL

*TERMINATION_SENSOR

Define monitored model responses se sensor type and location \$ Perform math computation on sensor results *SENSOR DEFINE CALC-MATH



\$Entity to be controlled by sensor *CONTACT_...._ID

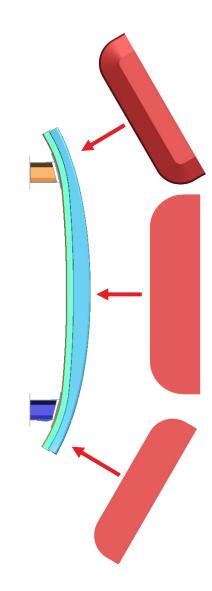


Triggering Switches

Often the most difficult aspect of using sensors is ensuring switches trigger at the right time.

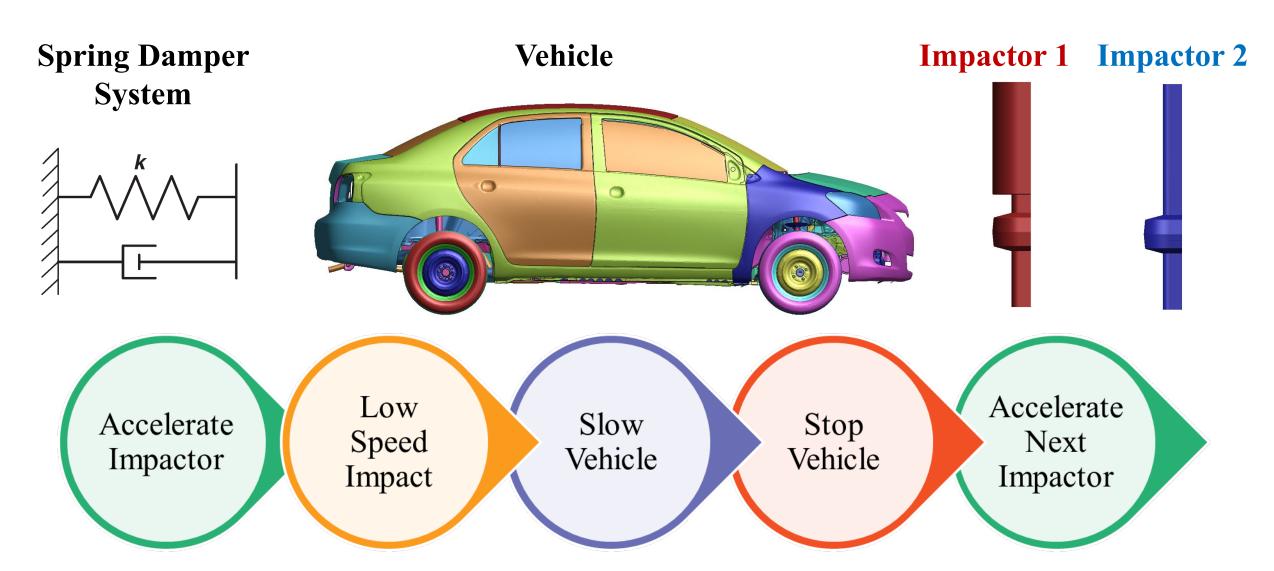
Three key methods are utilised to manage this issue, which can be used individually or in combination:

- Delays
- Combining switches with AND/OR gates
- Ordering switches



ARUP

Analysis Steps



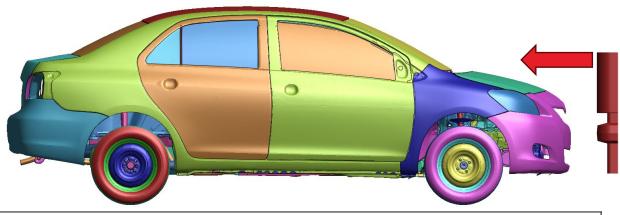


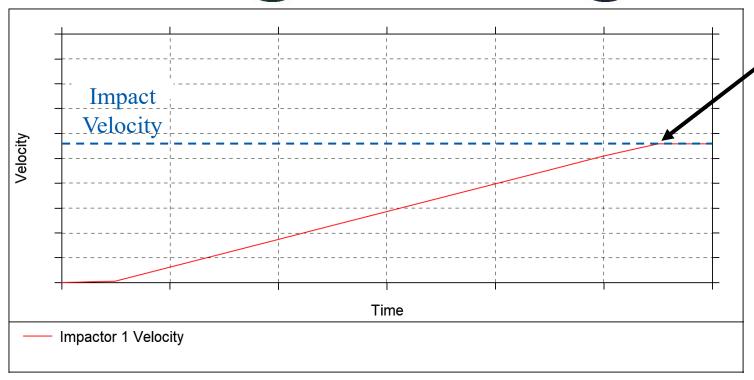
Accelerate Impactor

Accelerate

Impactor







Turn off impactor acceleration

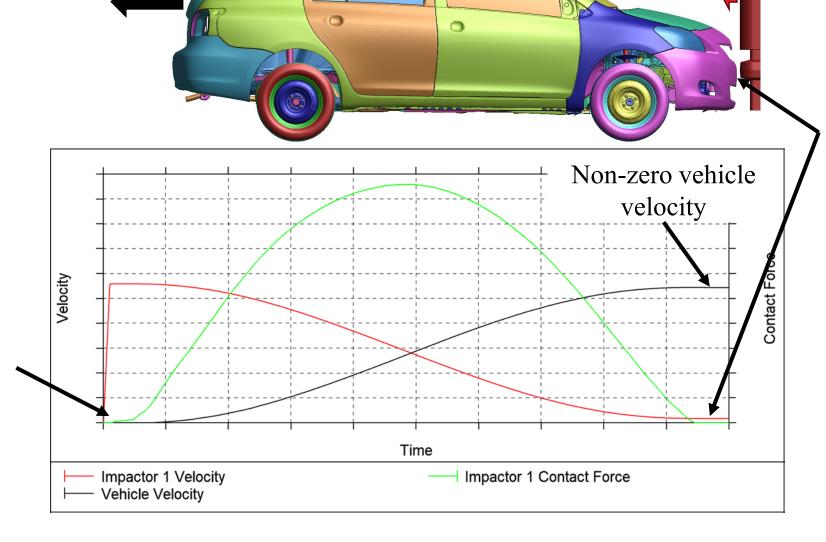
ARUP

Analysis Steps

Low Speed Impact

Low Speed Impact

Zero contact force before impact



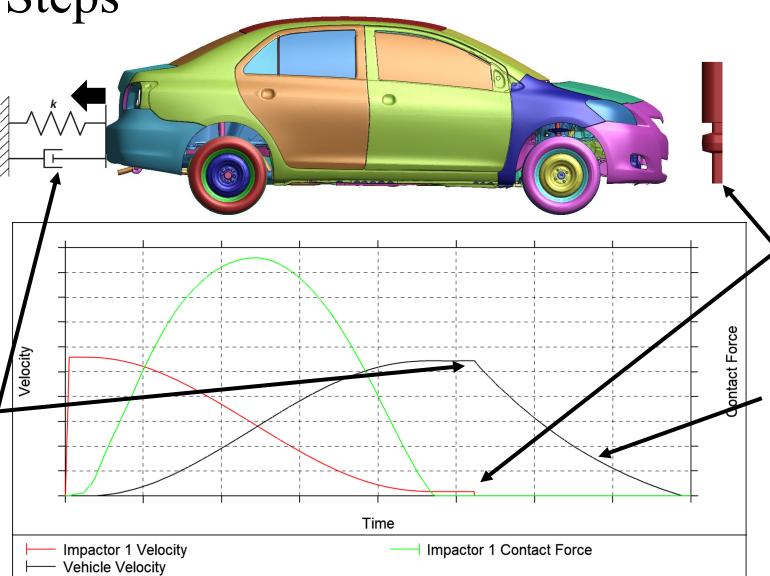
Impactor loses contact signalling the end of the impact



Slow Vehicle

Slow Vehicle

Engage spring damper system

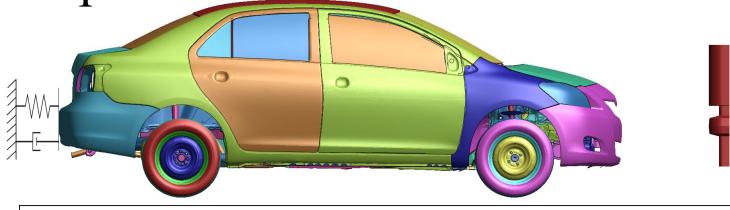


Impactor brought to stop to avoid second impact with vehicle

Critically damped slowing of vehicle

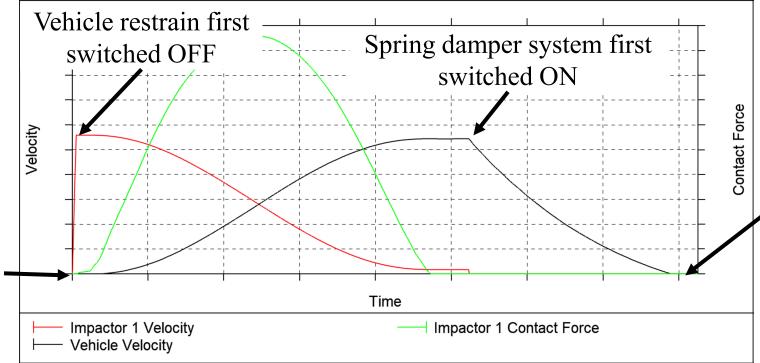


Stop Vehicle



Stop Vehicle

Vehicle and impactor at a complete stop for an instant

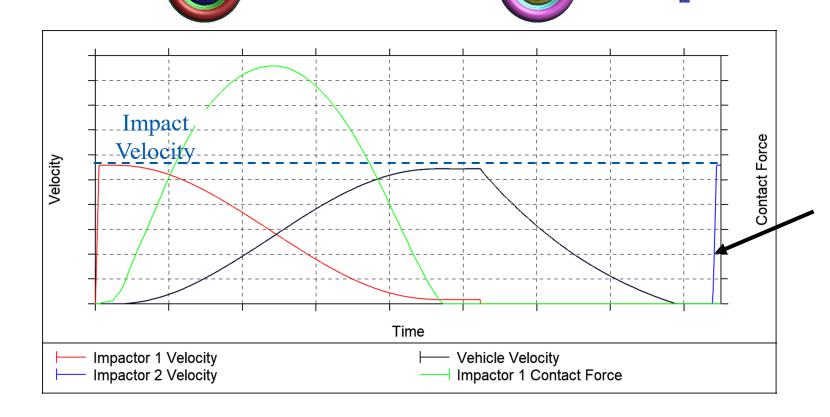


Vehicle and impactor at a complete stop for prolonged period



Accelerate Next Impactor

Accelerate Next Impactor

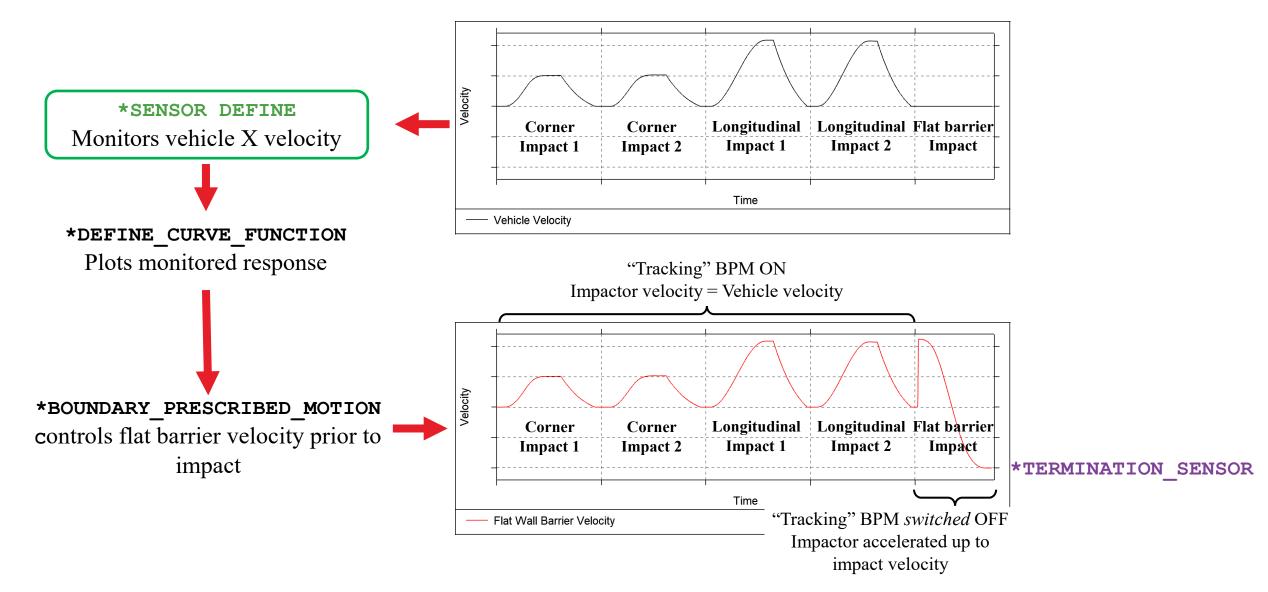


0

Second impactor accelerated to impact velocity



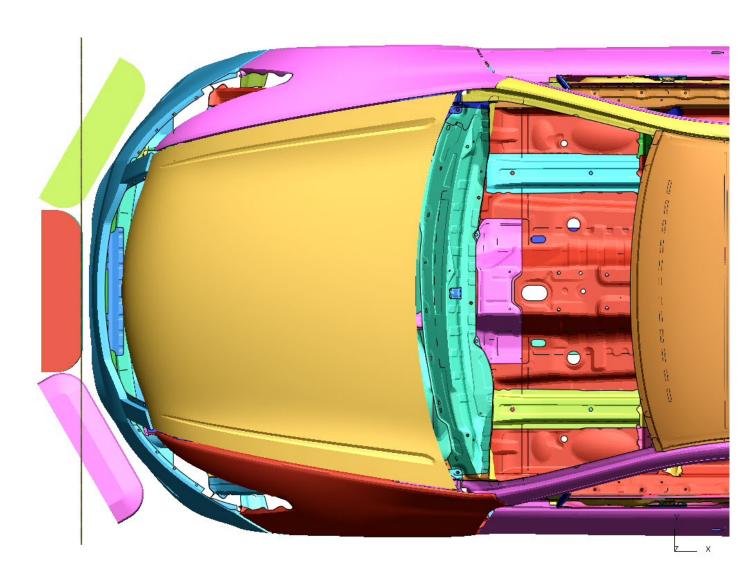
Impactor Positioning





Final Result

- Single integrated analysis
- Eliminated large transfer files
- Easier file management and set-up
- Removed intermediate post-processing and model modification stages
- Analyses can be run overnight or over a weekend







Contact
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Engineer

Thank You

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