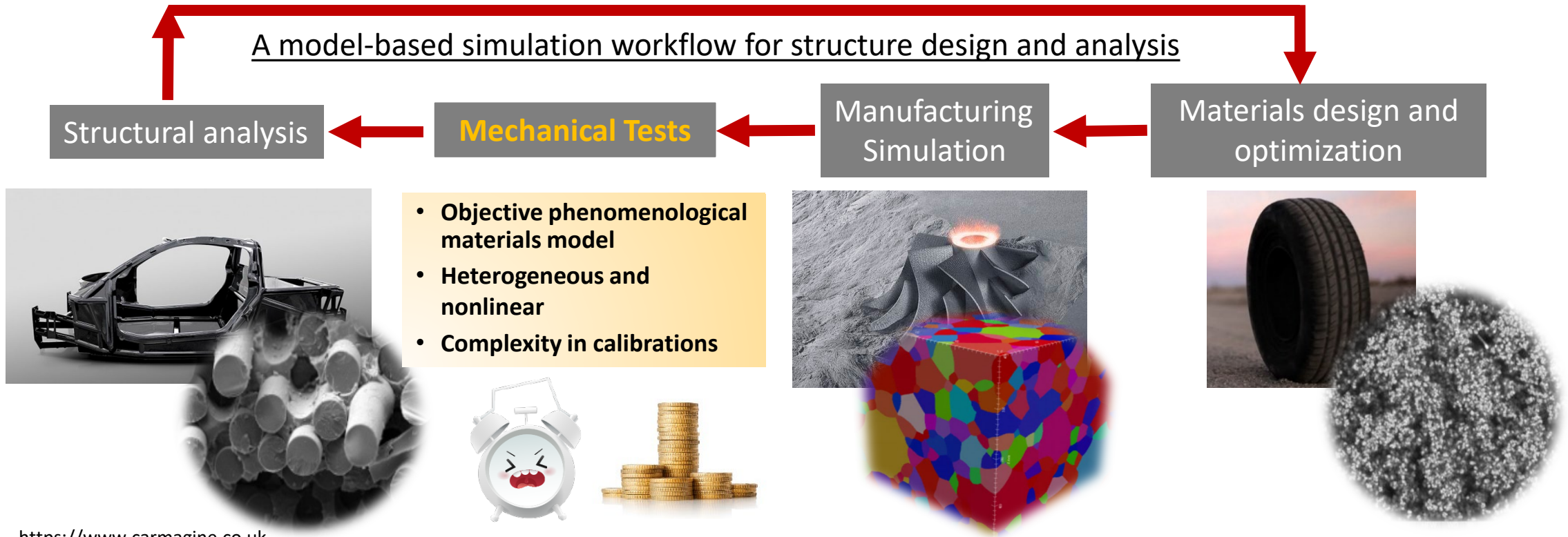


2023 LS-DYNA Development Updates for Manufacturing and Multiscale Simulations

C. T. Wu on behalf of
Computational and Multiscale Mechanics Group (CMMG)
Livermore, CA

Background

- Multiscale problems arise in material design, manufacturing, structural analysis, and optimization.
- With more new materials and modern manufacturing techniques, we need **more experiments, material calibrations and much refined mesh** for structure analysis, thus high cost in product development process.
- **Multiscale analysis** plays an important role in accelerating the virtual product development for industries (Digitalization, Digital Transformation, etc.).



<https://www.carmagine.co.uk>

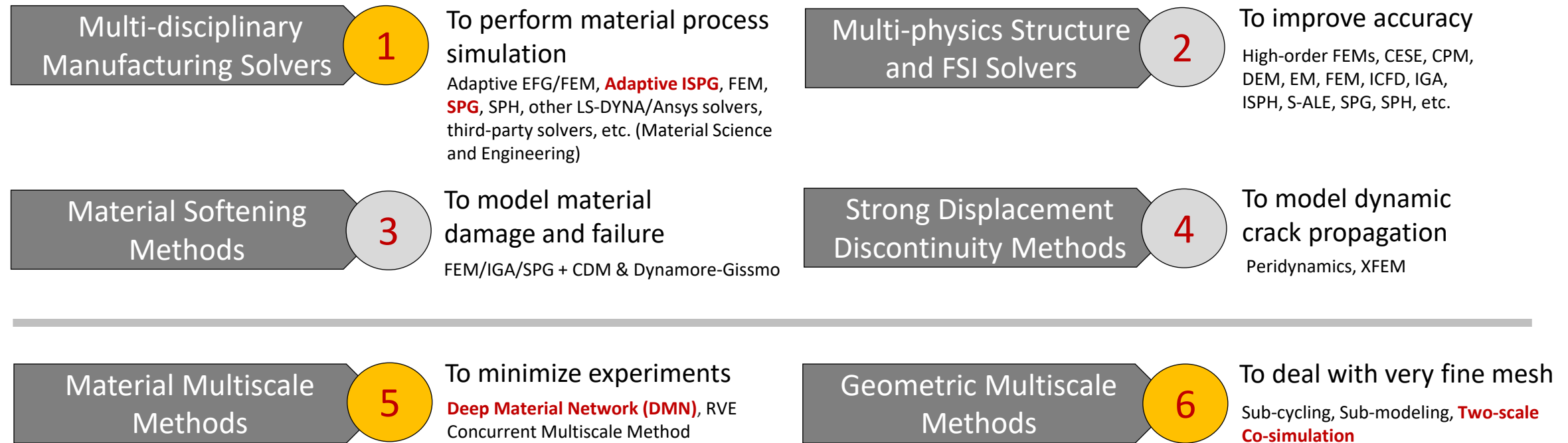
Goal

Develop advanced numerical methods including multiscale methods integrating structural analysis with manufacturing information to reduce experiments for digital prototyping

✓ Manufacturing information

- As-manufactured geometry/warpage, residual stress, defects, heterogeneous material properties, microstructures, etc.

✓ Numerical methods involved



Outline

1. Methods for Manufacturing Simulation

1.1 **Incompressible Smoothed Particle Galerkin (ISPG) Method** for Adhesive Fluid Mechanics Analysis

1.2 **Smoothed Particle Galerkin (SPG)** for Solid Mechanics Analysis

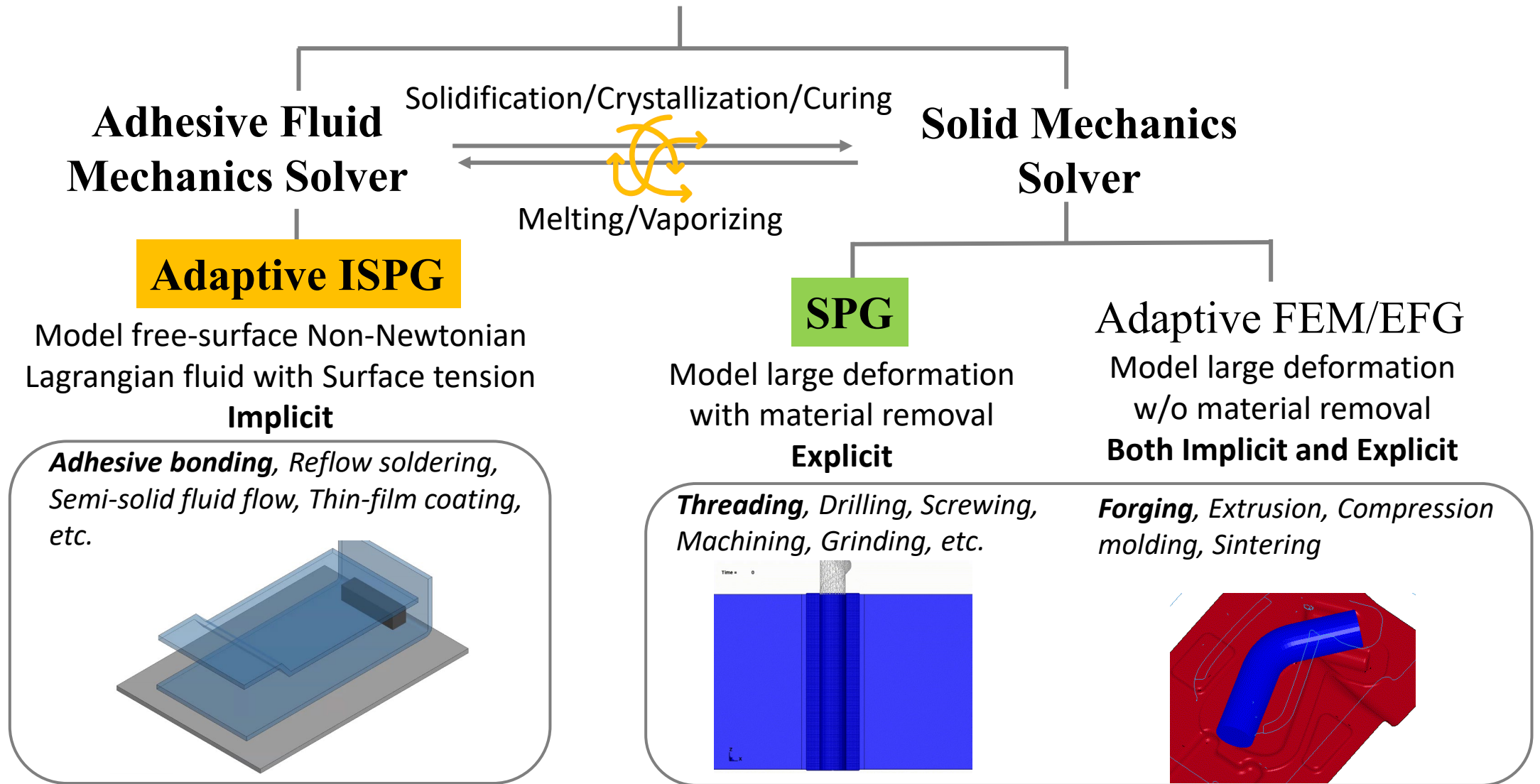
2. Methods for Multiscale Simulation

2.1 **Deep Material Network (DMN)** for Component Material Characterization

2.2 **Two-scale Co-simulation** for Assembly Structural Analysis

3. A Paradigm Integrating Structural Analysis with Manufacturing Information Using Multiscale Methods

PART 1 ISPG and SPG for Manufacturing Simulation



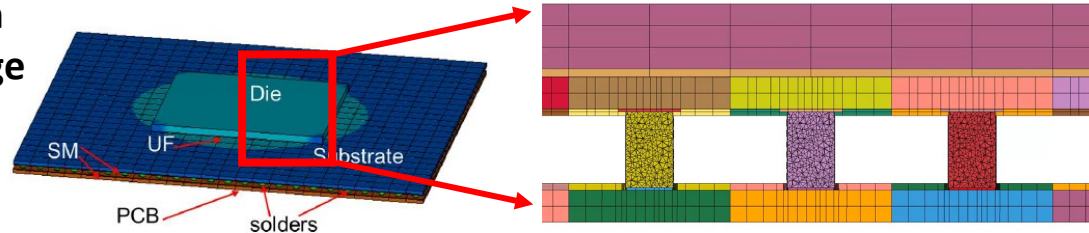
Incompressible Smoothed Particle Galerkin (ISPG) method^{1,2}

- ISPG developed by LS-DYNA is a new Navier-Stokes solver for modeling free-surface Non-Newtonian adhesive fluid flow with surface tension and adhesion force (soldering, glue bonding, semi-solid alloy forming, etc.).
- ISPG approximates the Navier-Stokes equation using weak form discretized by Lagrangian particle approximations

$$\frac{D\mathbf{v}}{Dt} = -\frac{1}{\rho}\nabla p + \frac{\partial}{\partial t}\nabla^2\mathbf{v} + \mathbf{g}, \quad \nabla \cdot \mathbf{v} = 0. \quad \boldsymbol{\sigma} \cdot \mathbf{n} = \gamma\kappa\mathbf{n} \text{ on } \Gamma_s \quad \mathbf{u}^h(\mathbf{x}) = \sum_{I \in Z_I} \Psi_I^a(\mathbf{x})\mathbf{u}_I \quad \forall \mathbf{x} \in \Omega,$$

- **A full-implicit method** with a second-order upwind scheme for time discretization.
- Penalty method for fluid-solid wall interaction.
- Alpha Shape algorithm for free surface detection and tracing.
- A Momentum-Consistent (MC) smoothing scheme² is applied to the particle velocity field and position update.
- Fluid particle inserting and merging for optimal efficiency and accuracy.

Ex 1: Reflow of 480 solder balls on PCB with thermal-induced warpage using R15 MPP version



~2.5 M elements, 64 cores
CPU 1.17 hours << Established numerical methods in weeks

(Courtesy of Ansys ACE, Arka Sengupta)

- MPP linear scalability was achieved in R15 Adaptive ISPG method.

CPU cost			
CPU cores:	8	32	64
Clock time[hours]:	8.4	2.1	1.17
Speed up:	1	4	7.6

¹ IJNME, 121 (17), 3979-4002, 2020 ; ² Comp. Part. Mech., 7 (2), 177-191, 2020

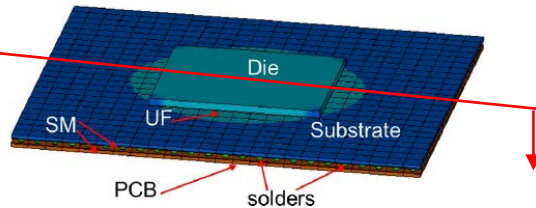
2023 R15 New Release - Adaptivity

- ✓ R15 ISPG introduces an **adaptivity ISPG method** to model complex reflow and severe contact angle.
- ✓ **Full-implicit** version based on MF2 solver was implemented for decomposition of solder balls on all CPUs for optimal scalability.
- ✓ The Beta version of **LS-Prepost (4.11)** supports the desired functions for Adaptive ISPG display.

Ex2 : Large-scale Reflow Soldering Simulation using R15 Adaptive ISPG method

(Courtesy of Ansys ACE, Arka Sengupta)

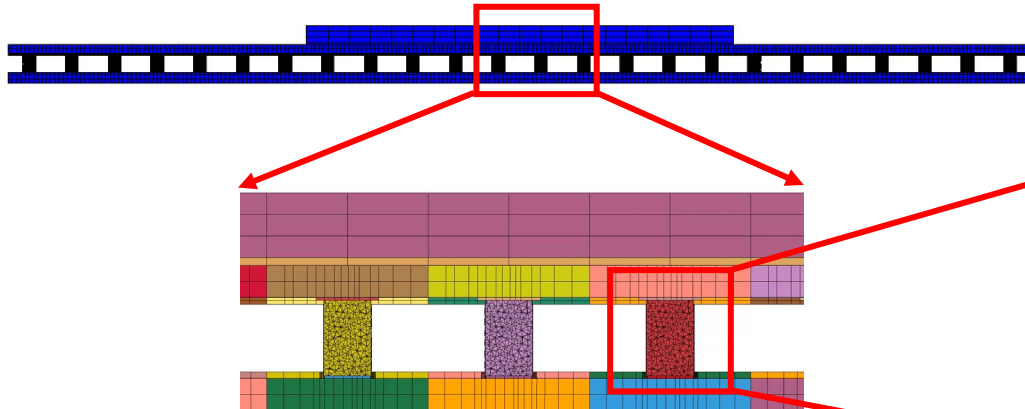
480 solder balls, ~2.5 M elements, 64 cores, **1.17 hours** in R15



- Theoretical linear scalability was achieved in R15 Adaptive ISPG method.

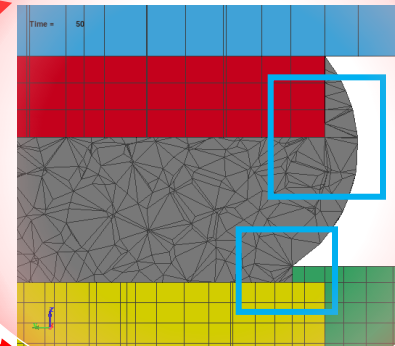
Computation cost	R15	R15	R15	R14
CPU cores	8	32	64	80
Clock time[hours]	8.4	2.1	1.17	10.0
Speed up	1	4	7.6	

- Heterogeneous deformation of solders due to large PCB thermal warpage

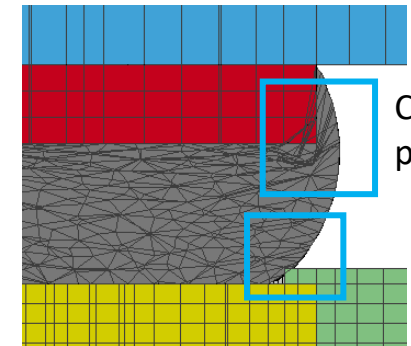


- R15 Adaptive ISPG resolves resolution issue in R14 non-adaptive ISPG

R15 Adaptive ISPG



R14 ISPG



Contact penetration

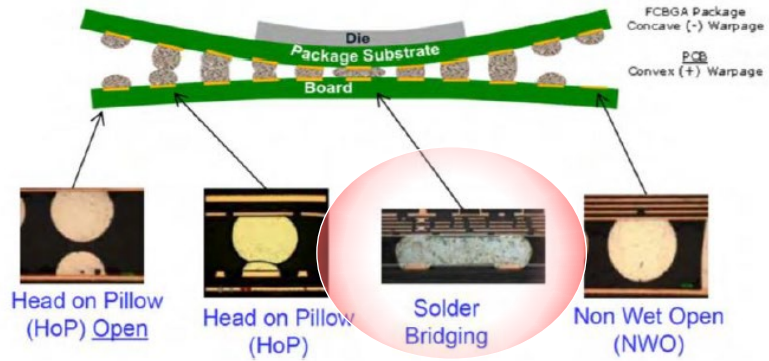
Corner gap formation

- Tight alignment of Adaptive ISPG fluids with the solid mask and PCB at contact regions

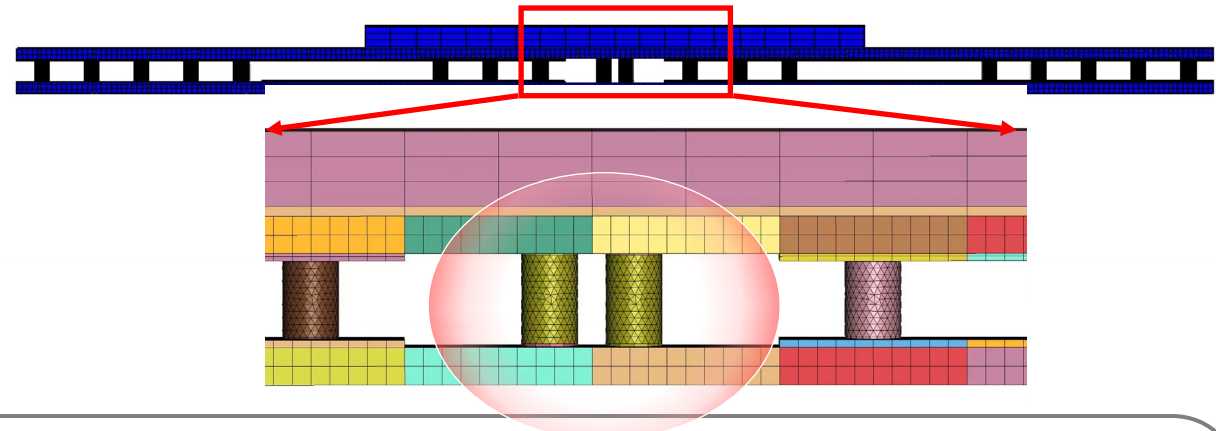
2023 R15 New Release – Solder bridging defects

- ✓ R15 Adaptive ISPG can model **solder bridging critical defects**
- ✓ A new full-implicit **sub-cycling scheme** for speed-up

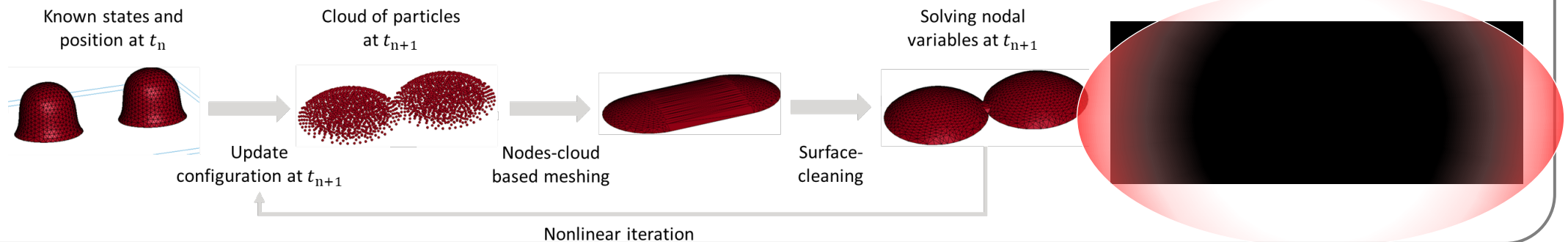
Ex3: Simulating solder bridging defects due to PCB warpage with wetting condition *(Courtesy of Ansys ACE, Arka Sengupta)*



Critical Solder defects at SMT (Loh et al., 2016)

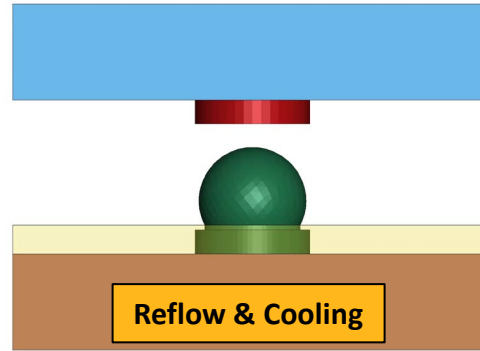
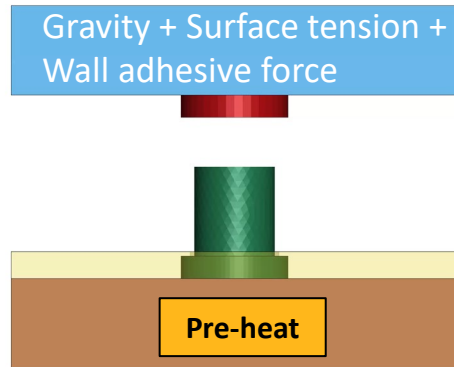


ISPG material fusion scheme for solder bridging under surface tension and wall adhesion force

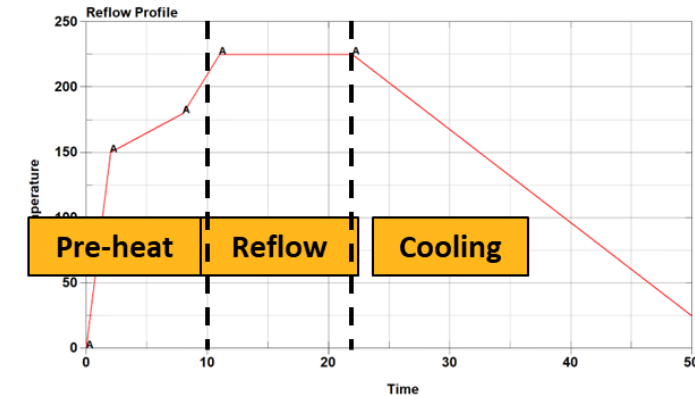


2023 R15 New Release – Temperature-dependent viscosity

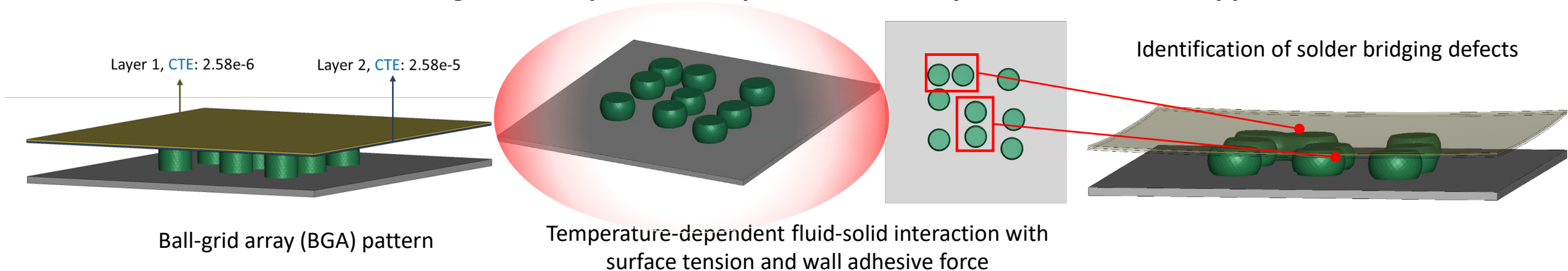
- ✓ R15 features also consider **solder pre-heat and cooling** stages
 - Non-Newtonian fluids and temperature-dependent viscosity



- Time history of thermal loading



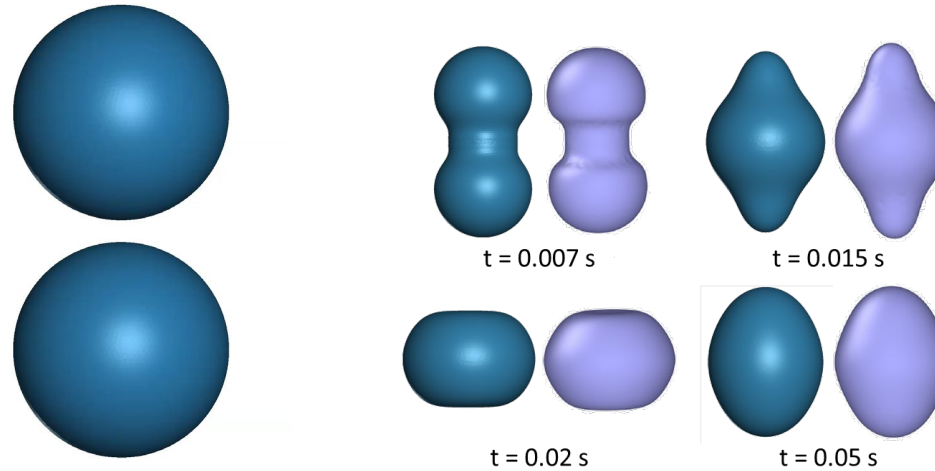
Ex 4: Defect of reflow soldering with temperature-dependent viscosity in semiconductor application



Application - 3D droplet-coalescence

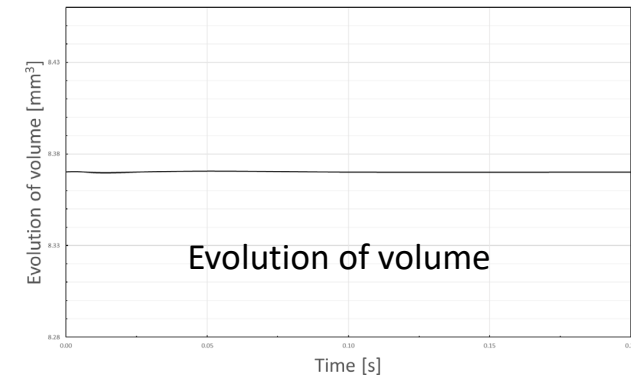
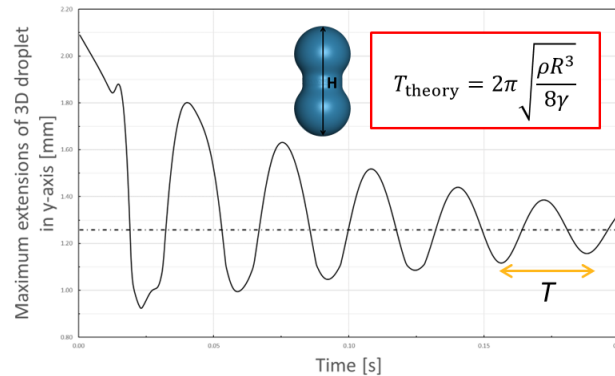
Ex 5: 3D droplet-coalescence simulation in surface engineering application

- UV-curing epoxy resins.
- For dotting, potting and filling in chip encapsulating applications.
- Other applications such as adhesive dispensing and thin film coating.



The droplet shapes at different times, comparing to the work of G. Duan (2022, CMAME)

Initial radius of each droplet, R	0.001 m
Initial approaching velocity	0.02 m/s
Density, ρ	1000 kg/m ³
Viscosity, μ	0.005 Pa s
Surface tension, γ	0.01 N/m
Ohnesorge number, $\frac{\mu}{\sqrt{2\rho\gamma R}}$	0.000997
Collision time	c.a. 0.2 s



Time dependence of the surface extension in y-direction

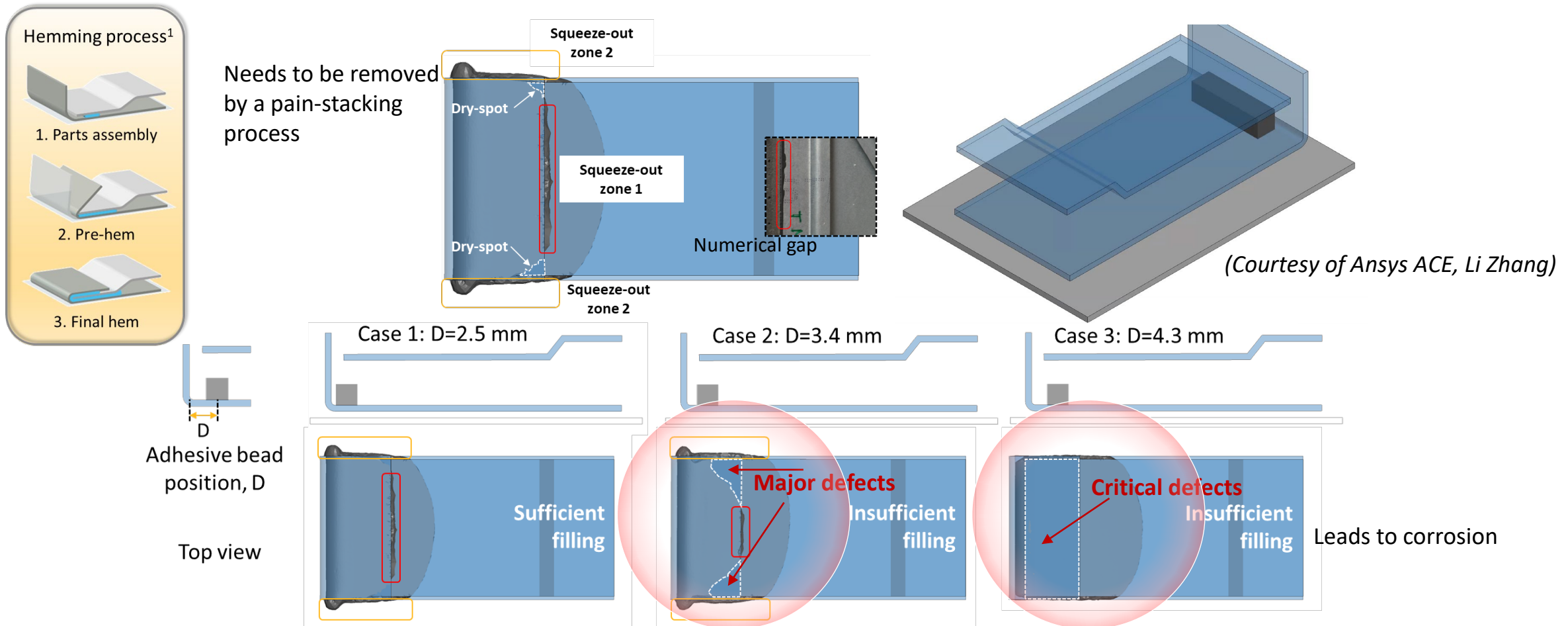
Simulated period, T [s]	Theoretical period, T_{theory} [s]	Relative error
0.0315	0.0314	0.317%

Initial volume	Volume at final time step	Relative volume error
8.37022	8.37004	0.00215%

Application – Structural adhesive bonding

Ex 6: Simulating adhesive flow and bonding defects in automotive **Hem Flange Bonding Process**

- **Adhesive bead position** plays an important role on optimal filling inside the hemmed area: Squeeze outs or insufficient filling
- Resultant adhesive layer thickness and gap-filling affect the mechanical properties of bonded structure

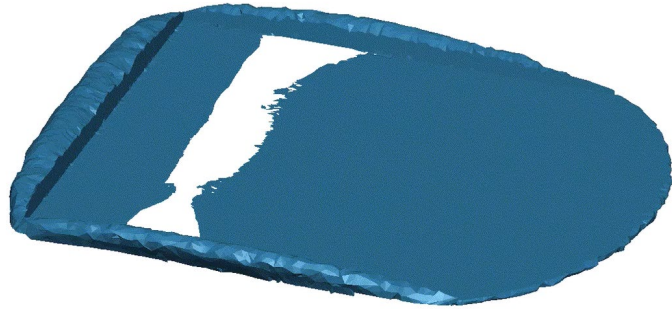


Application – Structural adhesive bonding

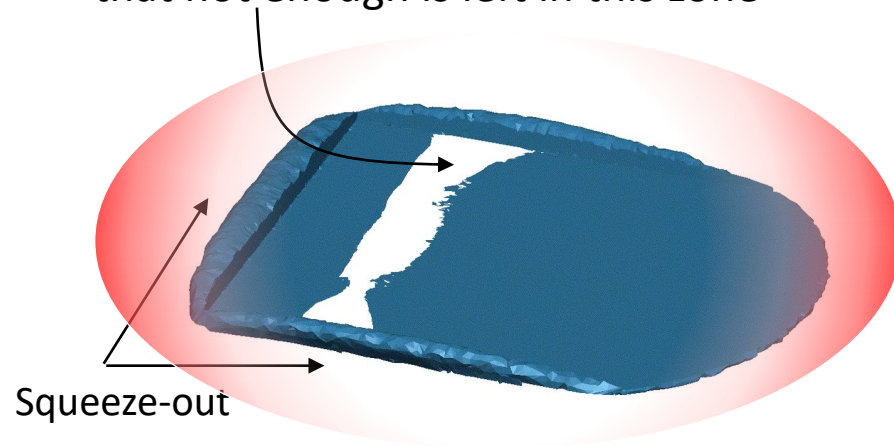
Ex 7: Study of critical defect - excessive glue squeeze-out

(Courtesy of Ansys ACE, Li Zhang)

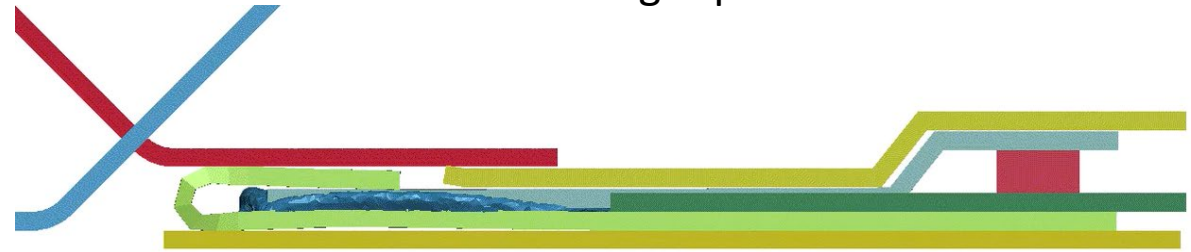
- Joining similar or dissimilar materials with structural adhesives



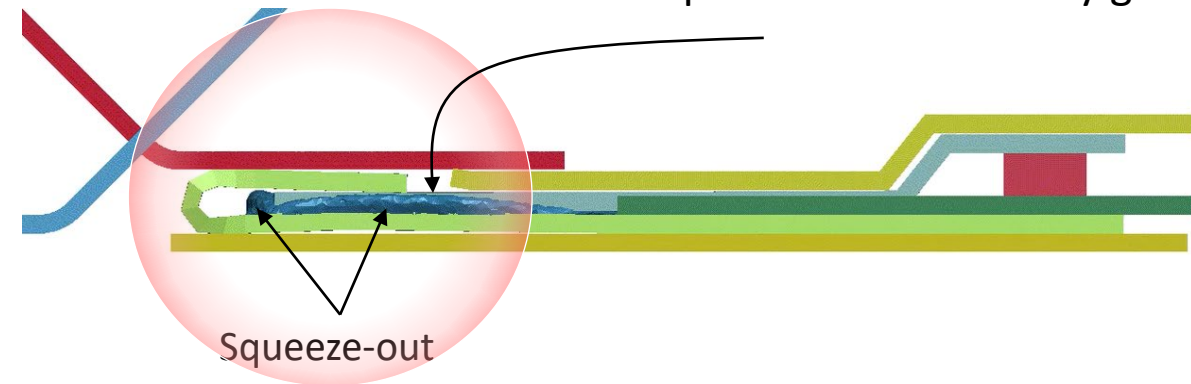
Defect prediction: excessive glue squeeze-out that not enough is left in this zone



Straight position



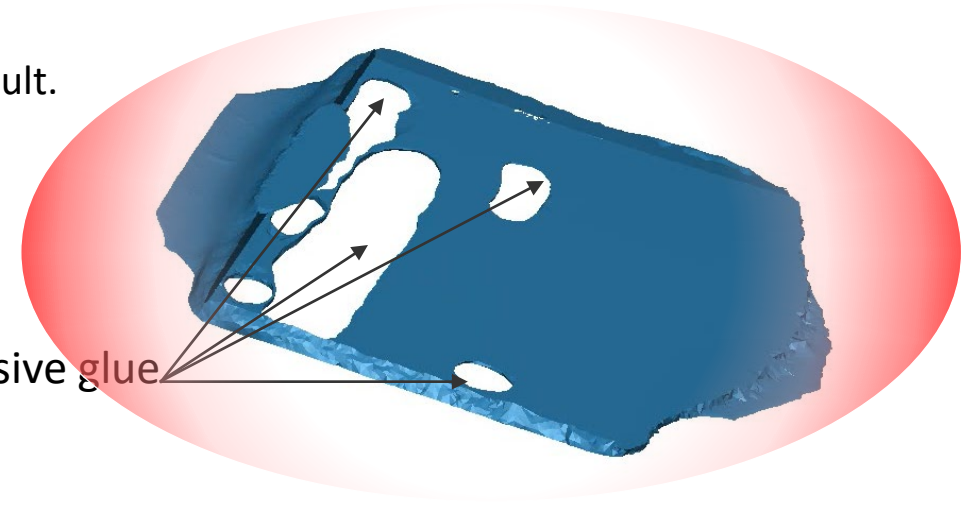
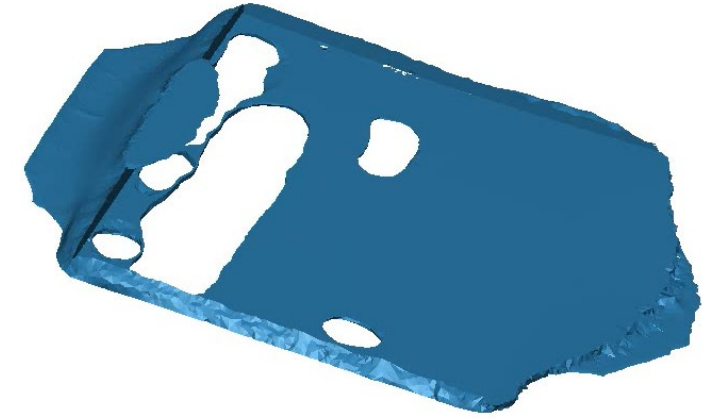
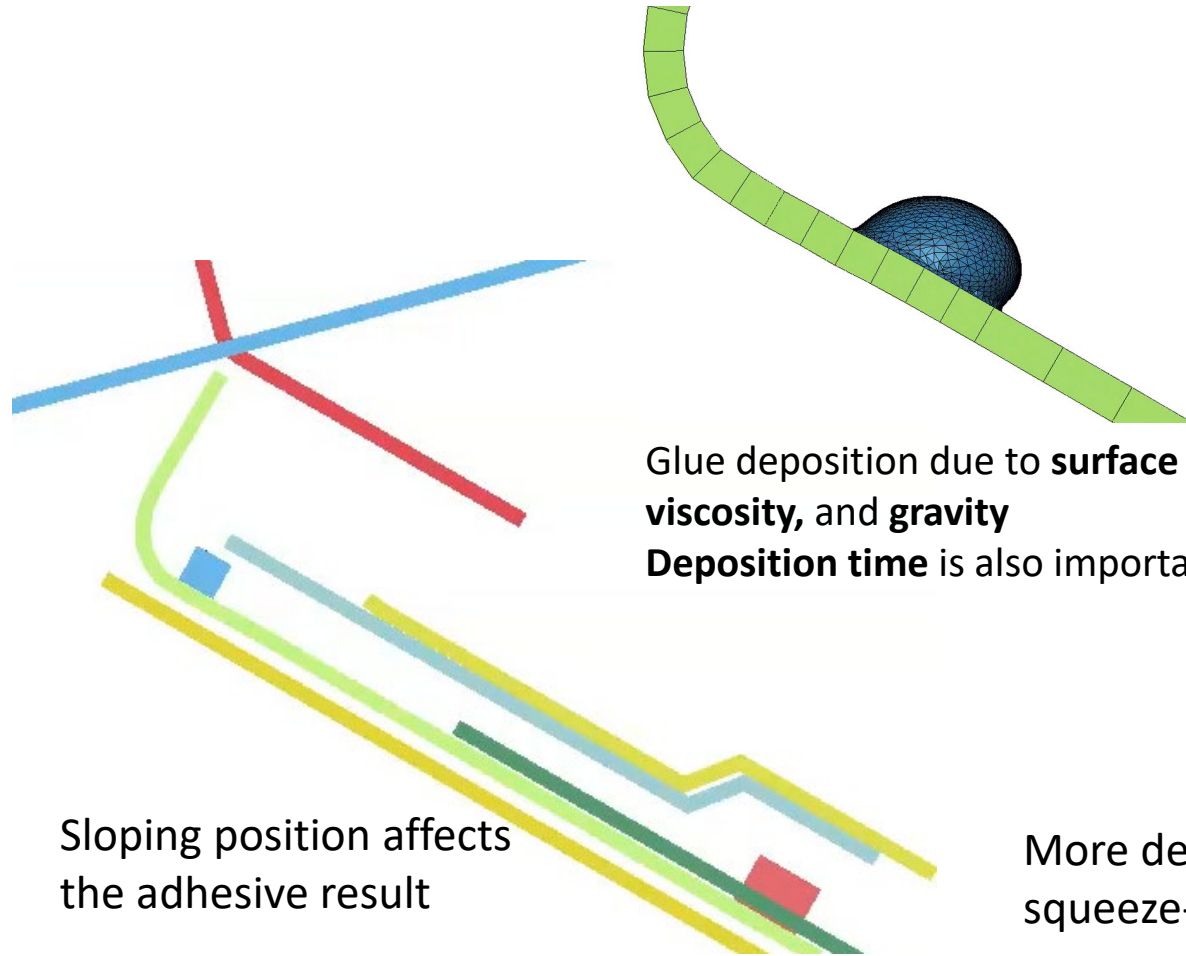
Three workpieces are bonded by glue



Application – Structural adhesive bonding

Ex 8: Study of critical defect under gravity effect

(Courtesy of Ansys ACE, Li Zhang)

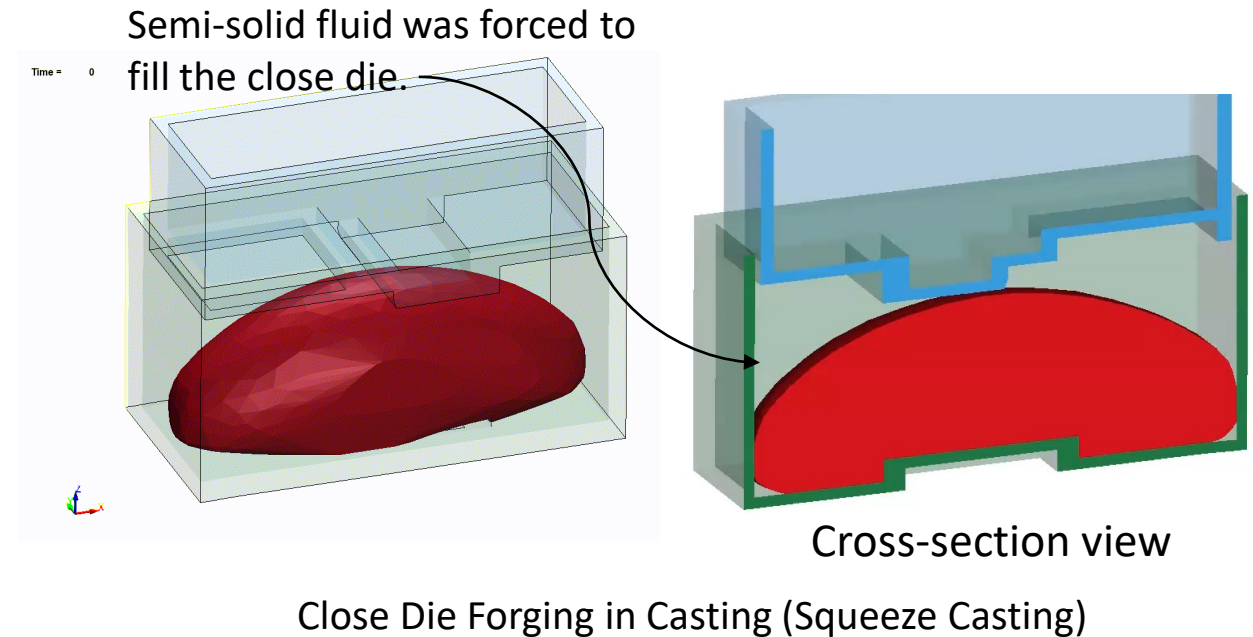
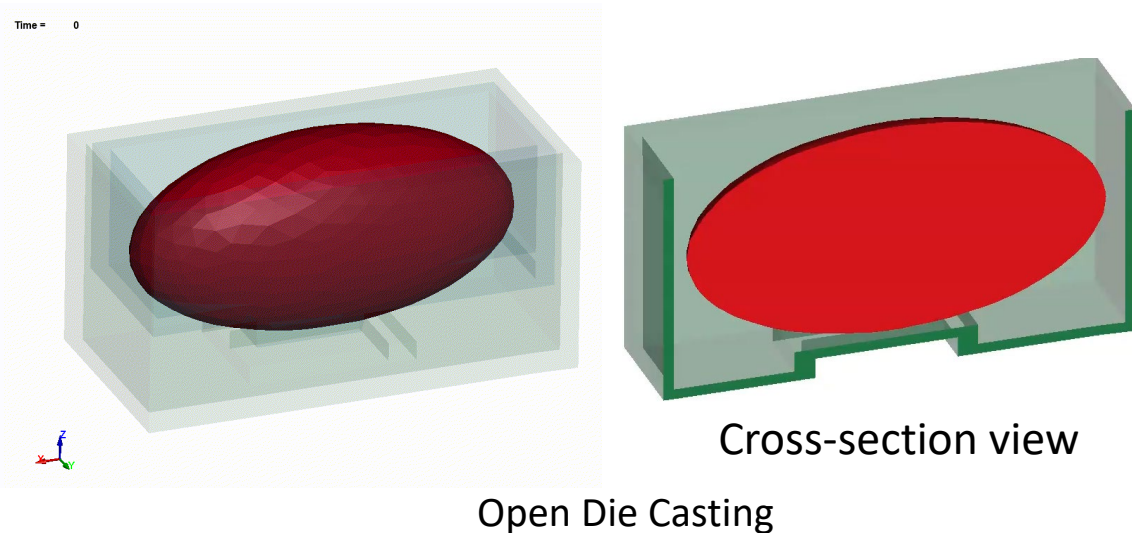


Application – Semi-solid material flow in metal processing

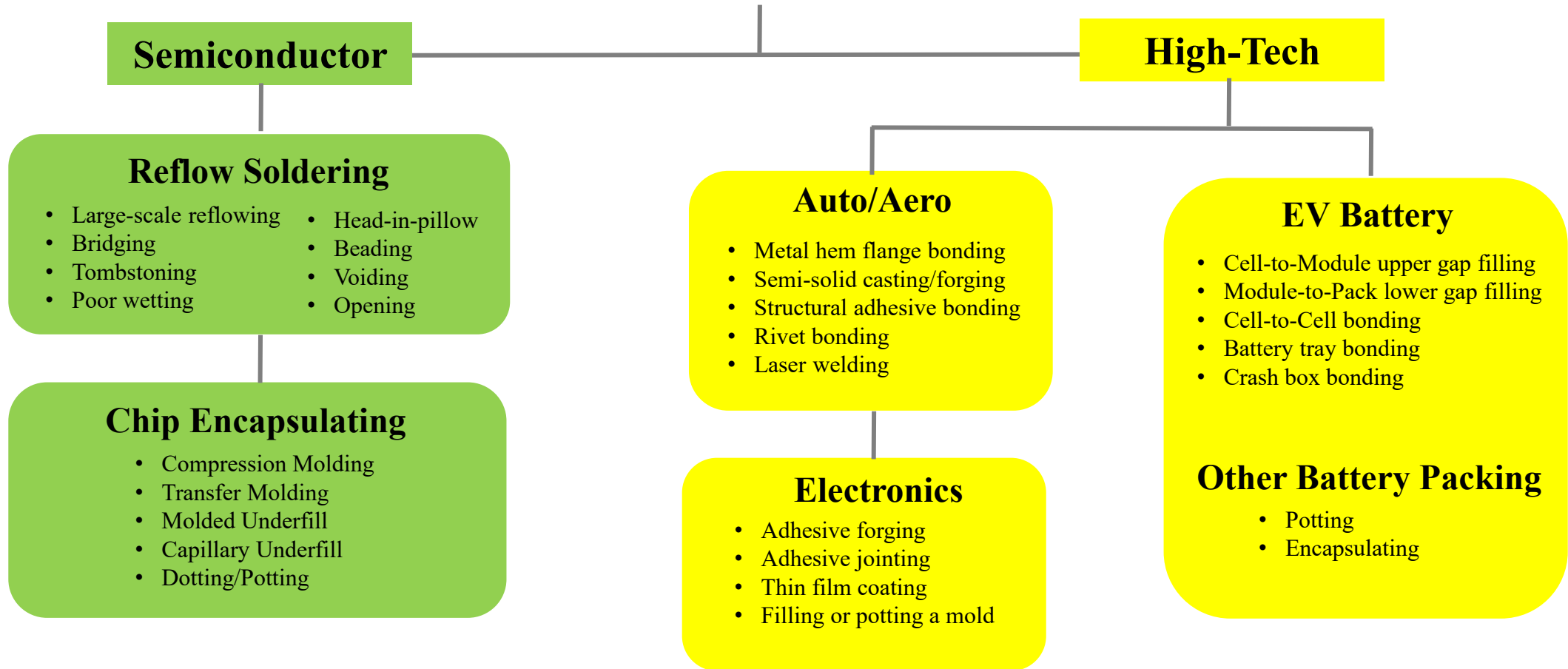
Ex 9 : Simulating aluminum semi-fluid flow in automotive **semi-solid metal (SSM) die casting process**

- Under different names such as Squeeze Casting, Thixoforging, and Thixocasting
- Combine the advantages of casting and forging for the high-end net shape products in auto, aero, high-tech, medical, etc.
- **Non-ferrous metals**, such as aluminum, magnesium, copper, ... with **non-dendritic microstructure**.
- Complex parts, porosity-less, reduced shrinkage, thin walls, good surface finish, excellent mechanical performance..

(Courtesy of Ansys ACE, Li Zhang)



ISPG Applications



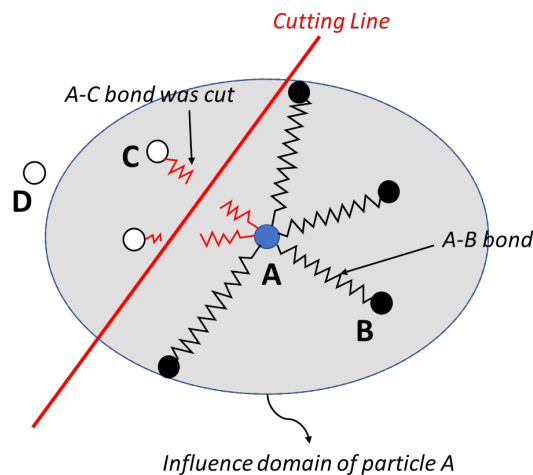
Smoothed Particle Galerkin (SPG) Method^{1,2}

- SPG is a new particle method for simulating severe deformation and material removal processes.
- SPG approximates the dynamic equation of motion using weak form discretized by particle approximations.

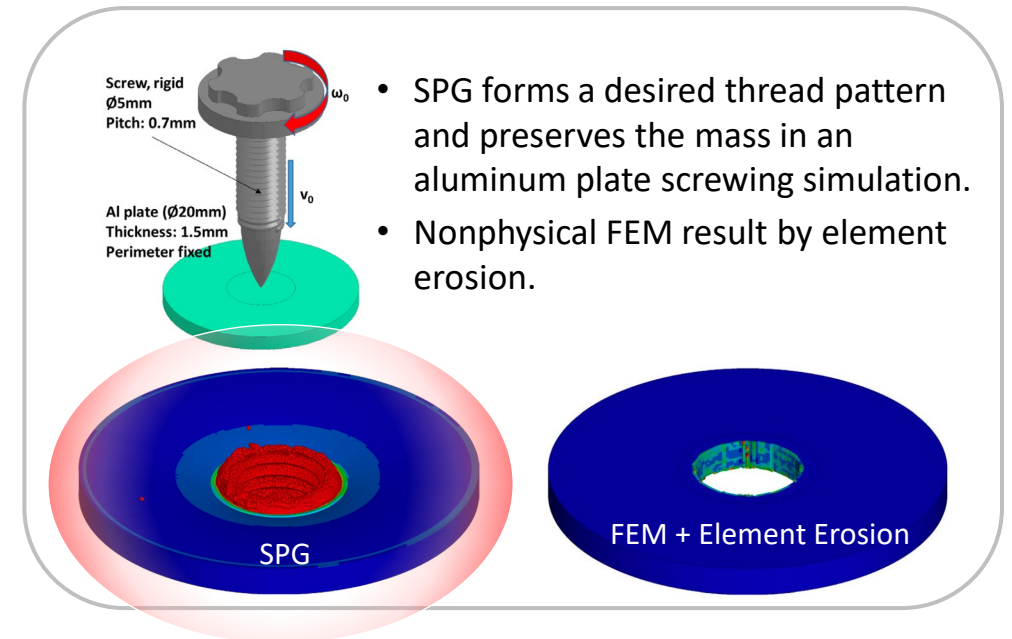
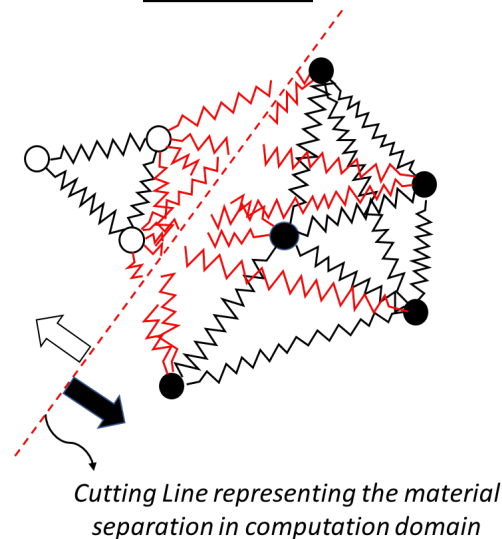
$$\int_{\Omega} \rho \ddot{\mathbf{u}}^h \cdot \delta \mathbf{u}^h d\Omega + \int_{\Omega} \boldsymbol{\sigma} \cdot \nabla \delta \mathbf{u}^h d\Omega - \int_{\Omega} \mathbf{b} \cdot \delta \mathbf{u}^h d\Omega - \int_{\partial\Omega^h} \mathbf{h} \cdot \delta \mathbf{u}^h = 0 \quad \mathbf{u}^h(\mathbf{X}, t) = \sum_{I \in Z_I} \phi_I^a(\mathbf{X}) \mathbf{u}_I(\mathbf{X}, t) = \sum_{I \in Z_I} \phi_I^a(\mathbf{X}) \mathbf{u}_I \quad \mathbf{P}_I := \sum_{J \in Z_I} \hat{m}_J \phi_I^a(\mathbf{X}_J) \hat{\mathbf{u}}_J$$

- MC smoothing algorithm removes the low-energy modes and preserves linear/angular momentum.
- **Bond-breaking scheme** avoids element/material erosion thus system mass is preserved in material removal simulation.
- **Bond-breaking scheme** prevents non-physical material fusion in solid mechanics simulation.

Bond breaks permanently within the Influence domain of particle A



Collection of breaking bonds forms the cutting line



¹. Comp. Part. Mech., 7 (2), 177-191, 2020; ². Comp. Mech., 64 (3), 625-644, 2019

2023 R15 New Release – Particle-to-Surface contact

- ✓ Main feature in R15 release: **a SPG particle-to-surface contact algorithm**
- ✓ Importance: new feature can improve the contact stability due to the **complex geometry of drilling/machining tools**.
- ✓ New Keyword: ***DEFINE_SPG_TO_SURFACE_COUPLING** .vs. *NODE_TO_SURFACE
 - Surface part can be rigid or deformable
 - Thermal-mechanical coupling
 - Include sliding and tied contact options
 - Released in SMP version; but MPP version is also available for trial use in R15

Ex1: A grooving tool design for a spiral chip formation in the metal dry drilling simulation *(Courtesy of Ansys ACE, Amit Nair)*

Types of drill bits

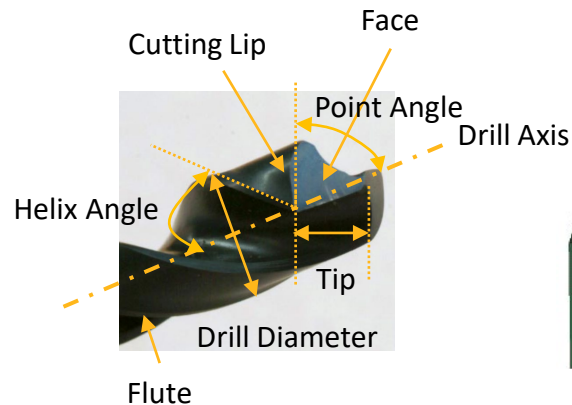


https://en.wikipedia.org/wiki/Drill_bit

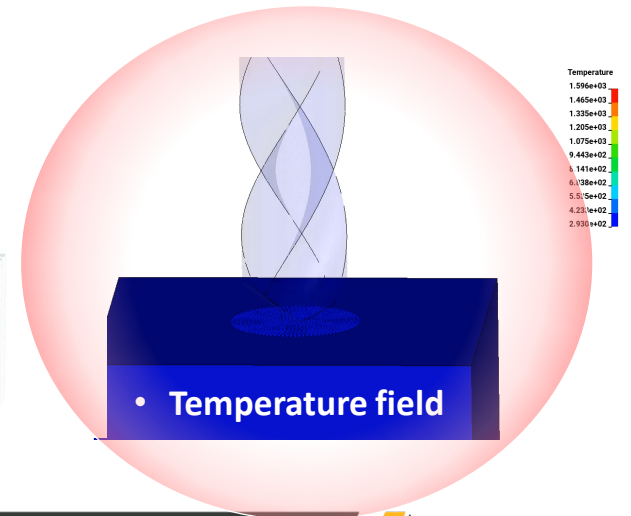
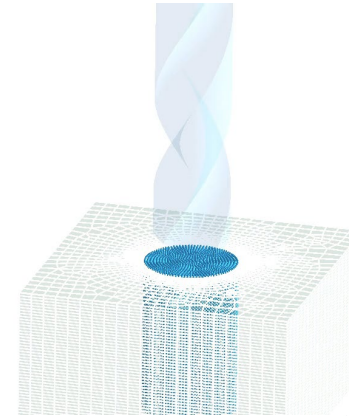
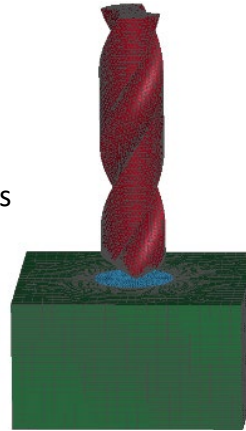


<https://www.123rf.com>

Drill bit geometry



- Material is not eroded in simulation (thus mass/momentum conservation)
- Spiral-shaped chips can be reproduced



Application – Orthopedic Screw Mechanics

- Orthopedic screw design affects the bone fixation for fractures.
- The **pull-out strength** of orthopedic screws is used to measure the **screw fixation strength**.
- New feature can simulate the formation of bone threads and residual stress in insertion process determining the pull-out strength.
- SPG is an exclusive numerical method to perform this process simulation.

Types of bone screws



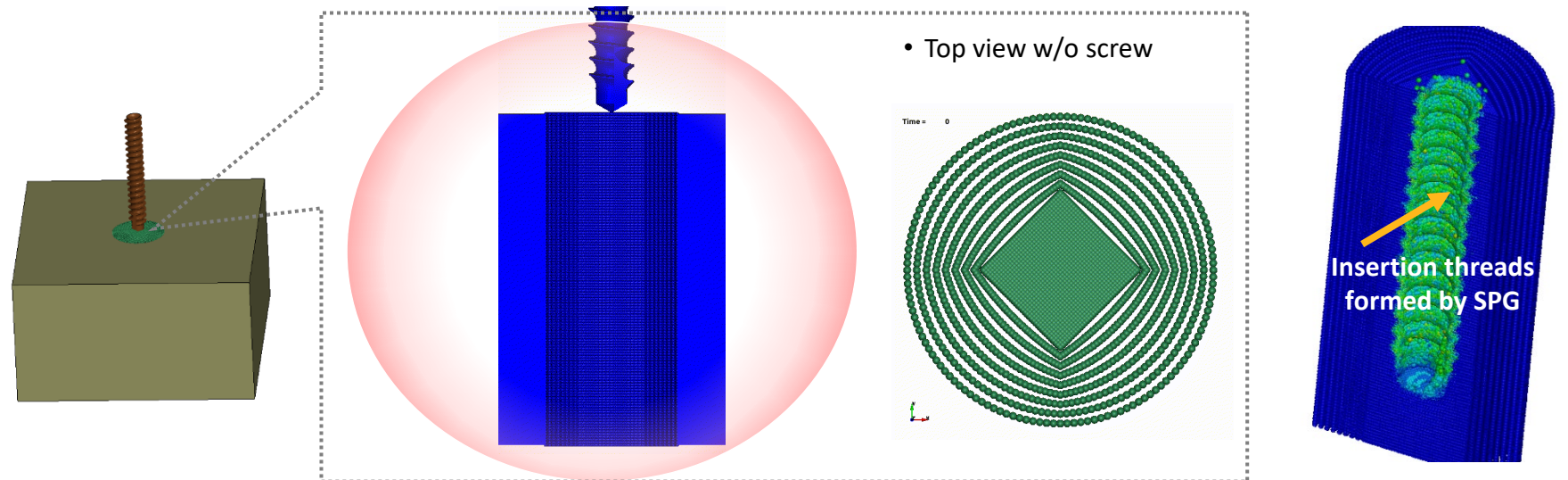
<https://giapius.com/ortnopeaic-screws>



Front. Bioeng. Biotechnol. 10:816250, 2022

Ex2: Simulation of surgical screw insertion & pullout in sawbones

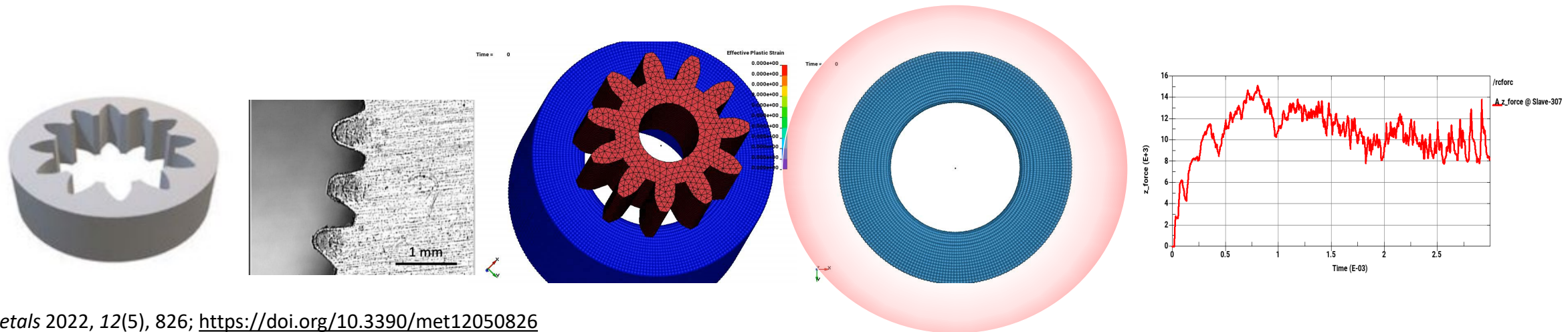
- Threads can be formed in sawbones during inserting
- Residual material is captured on screw affecting the pullout strength



Application – Open-die Cold Extrusion

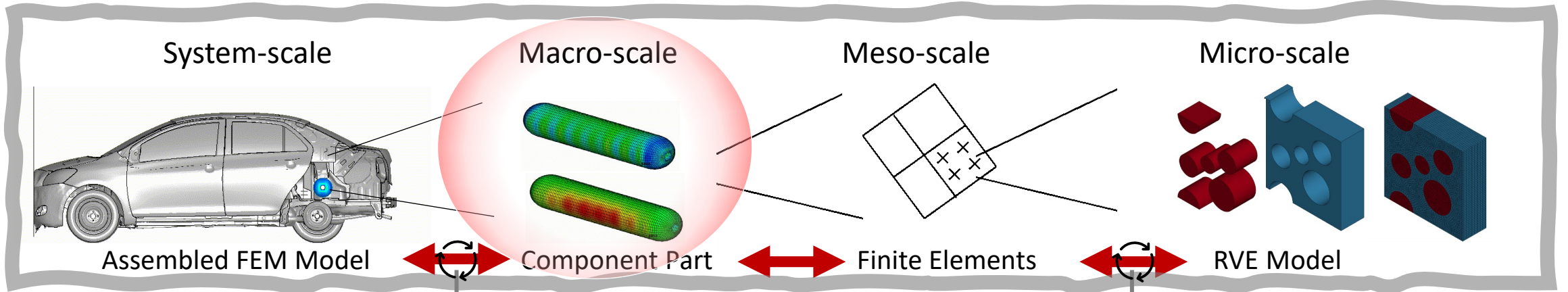
- Cold extrusion usually yields better mechanical properties than machining.
- **But the forming quality and defects** are difficult to control (lubricating condition, entrance angle, blank size, and extrusion speed).
- New SPG feature can prevent contact penetration and maintain the numerical stability in precision extrusion simulation.

Ex3: Formability and defect cause analysis in Cup-shaped (Spur) Internal Gear manufacturing



PART 2 Multiscale Simulation Methods

Ex. Study of composite components in the system analysis



Geometric Multiscale Method

Speed up bridging macro – system scale for assembly analysis to deal with fine mesh

Two-scale Co-simulation

Modeling joints, components and adhesives in system analysis

Material Multiscale Method

Speed up bridging micro – meso scale for material characterization to minimize experiments

DMN

Heterogeneous microstructure
Short fiber reinforced composite
Polycrystalline metal, UD

RVE Concurrent Multiscale

Homogeneous microstructure
Weaved
Plain woven

Material Multiscale Methods

- Fill the gap between manufacturing simulation and structural Analysis
- Requires the **microstructure reconstruction, RVE technology and Material Multiscale method**

Classification of Microstructure Systems

Manufacturing Simulation and Solvers

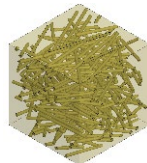
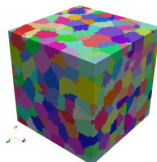

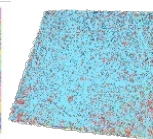
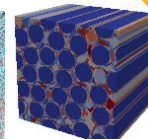

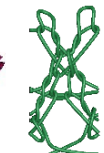
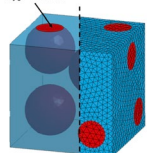
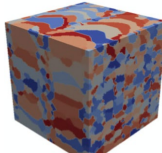
Numerical Methods

Physical Descriptors

As-manufactured geometry/warpage, residual stress, microstructures, defects, etc.

Microstructure Reconstruction

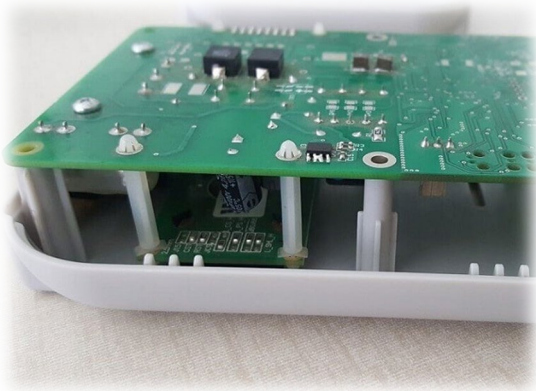
Material Multiscale Methods

Short-Fiber Injection Molding	Multi-stage Metal Fabrication	Bulk Compression Molding (CM)		Weaving	Unexplored			
		(chopped fiber)	(glass fiber)					
Amorphous Thermoplastics PC/ABS/PS/PVC/PSU, ...	Forging, Extrusion, Rolling, Machining, Grinding, Jointing, etc.	Thermoplastic epoxy /Carbon fiber	Polyamide Nylon6 /Glass fiber	Textile materials	Die-casting, Laser welding, Fiber-reinforced 3D Printing, Micro-injection Molding, Nanomaterials and Nano-manufacturing, etc.			
CFD (Moldex3D, Moldflow) Third party software	ISPG, SPG, FEM, 3D adaptive FEM/EFG	3D adaptive FEM/EFG		Winding software	ISPG, ICFD, etc.			
Fiber Orientation/Volume Fraction Rheology model	Grain Density, Size, Orientation Dir/Rheology model	Forming indicators		Weaving methods	Imagine-based methods (Computed Tomography, CNN/Transfer Learning)			
 Short fiber ✓ 2022 R14	 Polycrystalline R&D	 Chopped fiber	 Long fiber	 UD R&D	 Plain Woven	 Weaved ✓ 2023 R15	 Nano-particle	 Dendritic/Eutectic R&D
(a) Deep Material Network (DMN) AI for Heterogeneous Microstructures					(b) RVE Concurrent Multiscale Method FE ² for Homogeneous Microstructures		(c) AI-EBSD + GNN/DMN	

Short Fiber Composites

- Injection-molded short-fiber-reinforced composite (SFRC) is a high performance, low-cost, and environmental friendly material (light weigh, high productivity, chemical/corrosion resistant, recyclable, shock absorbing).
- They are widely used in Electronics, Auto, Consumer Goods, Protective equipment, Aerospace, Healthcare, Construction, etc.
- Modeling SFRC materials has been a challenging task for years.

PCBs



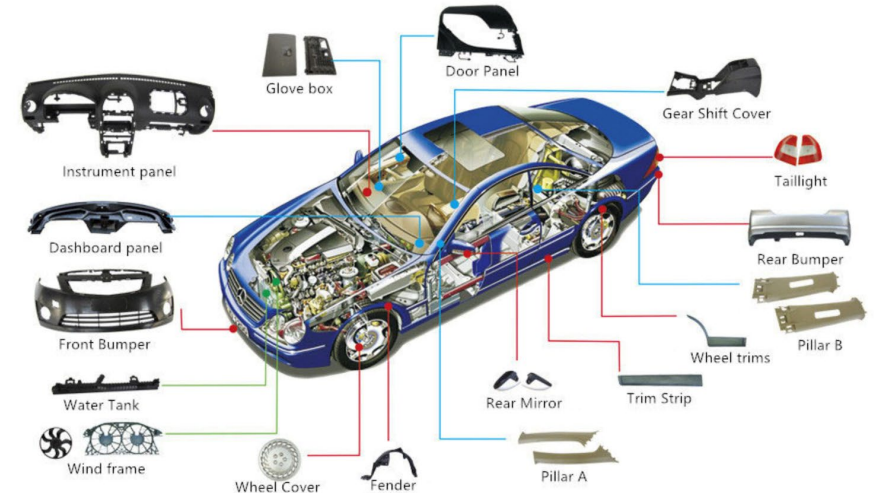
<https://scorpiomfg.com/project/injection-molding-plastic-enclosure>

Electronics Plastic Enclosures and Covers



<https://app-nh.com/markets-electronics/>

Automobile Parts

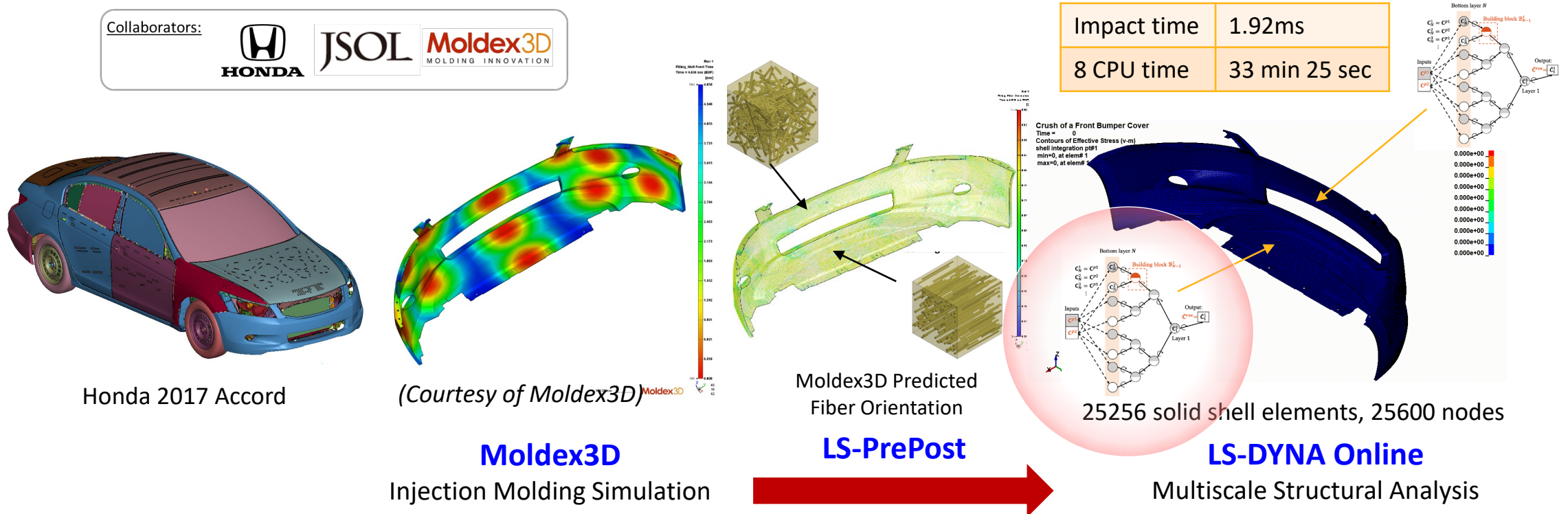


<https://www.hollyplasticparts.com/solution/automotive-plastic-injection-molding/>

DMN for Modeling Short Fiber Composites

- Deep Material Network (DMN)^{1,2,3} developed by LS-DYNA is a Machine Learning method.
- First version was released in 2022.
- DMN recognizes heterogeneous microstructure patterns in data to make efficient prediction of nonlinear material behavior in macroscale.

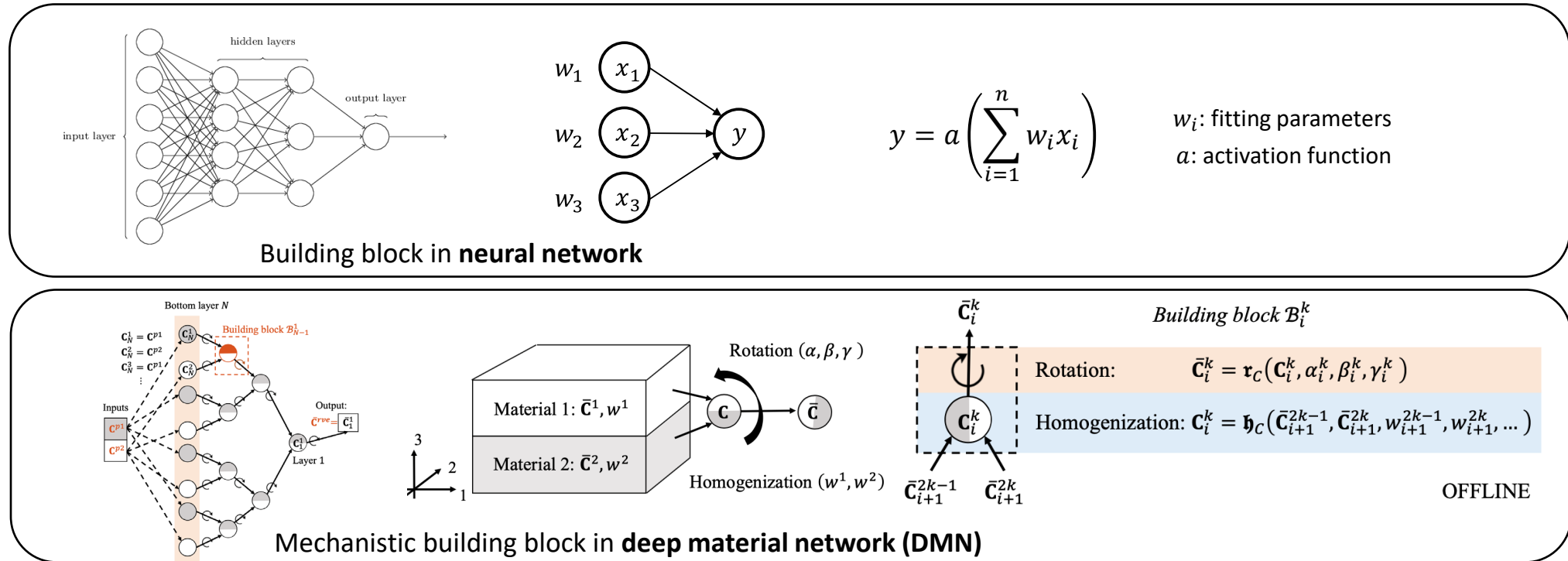
Ex. Multiscale Structural Analysis of Injection Molded Short Fiber Reinforced Bumper Cover by 2022 R14



¹. CMAME, 345, 1138-1168, 2019; ². J. Mech. Phys. Solids, 127, 20-46, 2019; ³. Comp. Mech., 64(3), 625-644, 2020

Difference between Deep Material Network (DMN) and Neural Network

- **Artificial neural networks generally have the issues of loss of physics.** It leads to the problems in modeling material history dependency, keeping physical invariance and preserving conservation law.
- The Deep Material Network (DMN)¹ introduces a collection of connected **building blocks** with **analytical homogenization solutions** to resolve the issues.
- Targeted applications include arbitrary morphology, material nonlinearity (plasticity, damage, de-bonding), geometric nonlinearities (large deformations).



¹ A deep material network for multiscale topological learning and nonlinear modeling of heterogeneous materials, CMAME, 345, 1138-1168, 2019.

Computational Procedure in Deep Material Network (DMN)¹

Offline Training

3D RVE morphology



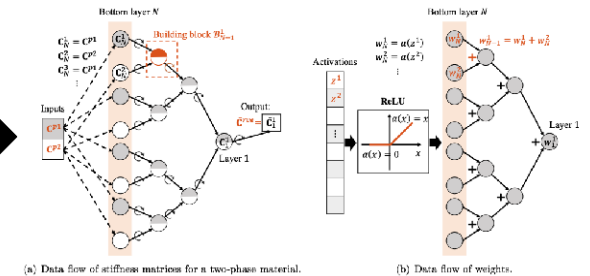
Data generation

High-fidelity DNS or FFT
Generating orthotropic elastic samples

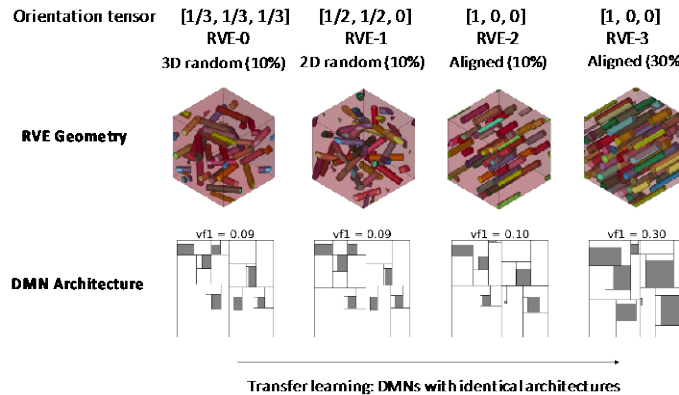
$$\bar{\mathbf{C}}^{rve} = \mathbf{f}_2 \left(\underbrace{\mathbf{C}^{p1}, \mathbf{C}^{p2}}_{\text{Inputs}}, \underbrace{z^j=1,2,\dots,2^{N-1}, \alpha^k=1,2,\dots,2^{i-1}, \beta^k=1,2,\dots,2^{i-1}, \gamma^k=1,2,\dots,2^{i-1}}_{\text{Fitting parameters}} \right)$$

$$Re'(z_N^j) = \begin{cases} 1 & \text{if } z_N^j > 0 \\ 0 & \text{otherwise} \end{cases}$$

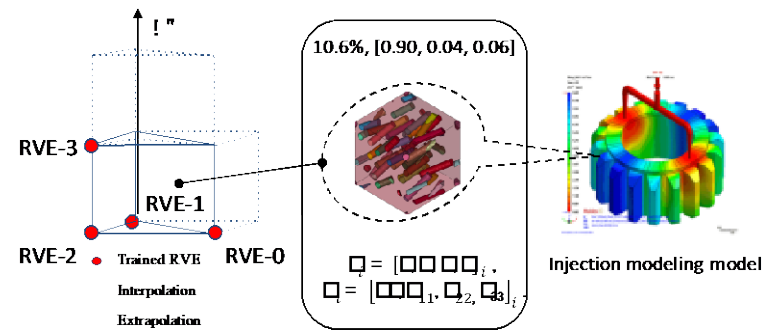
Network training



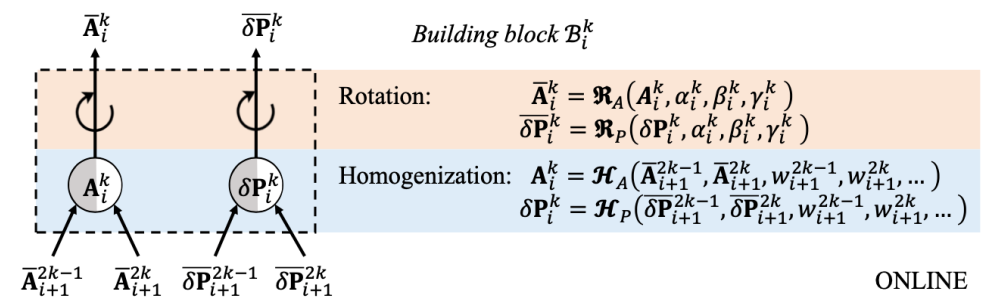
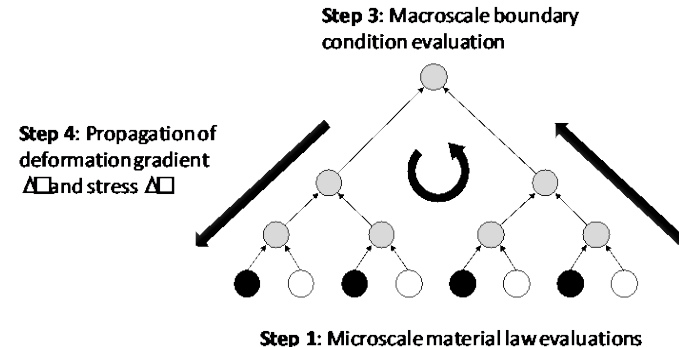
Transfer Learning for Short-Fiber Reinforced Composites



Design space



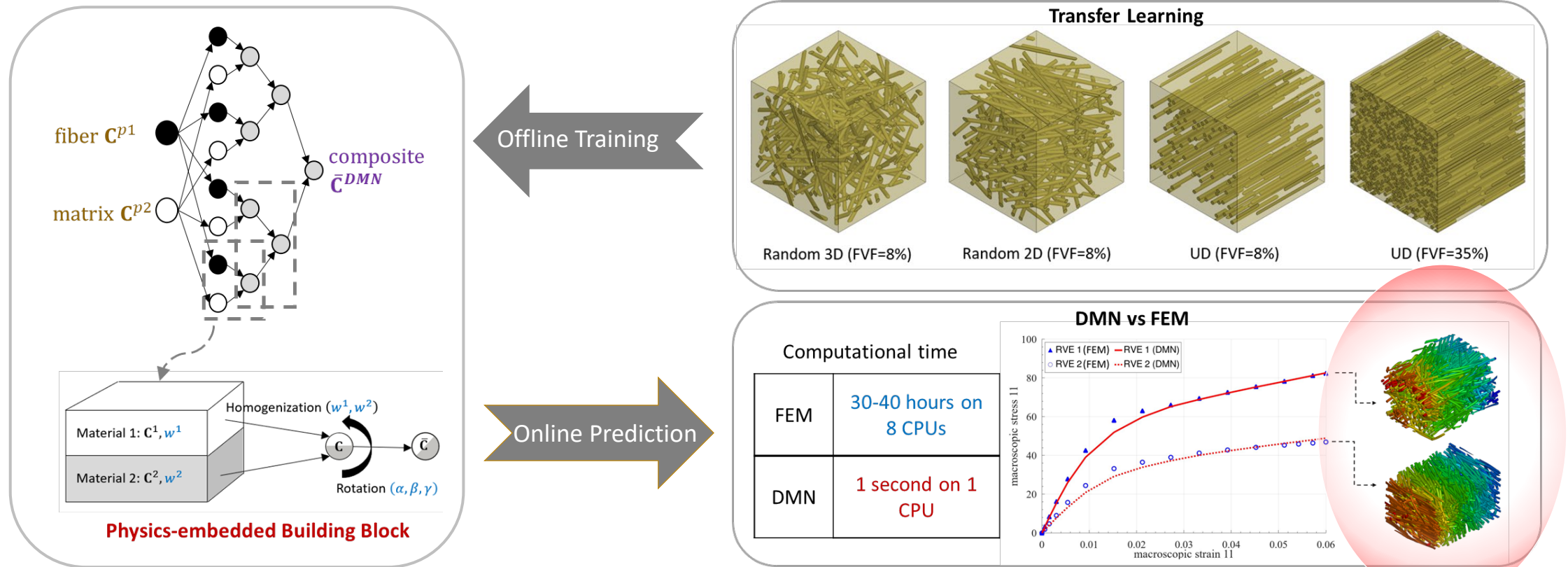
Online Extrapolation Material Nonlinearity in the Network



¹ Exploring the 3D architectures of deep material network in data-driven multiscale mechanics, J. Mech. Phys. Solids, 127, 20-46, 2019.

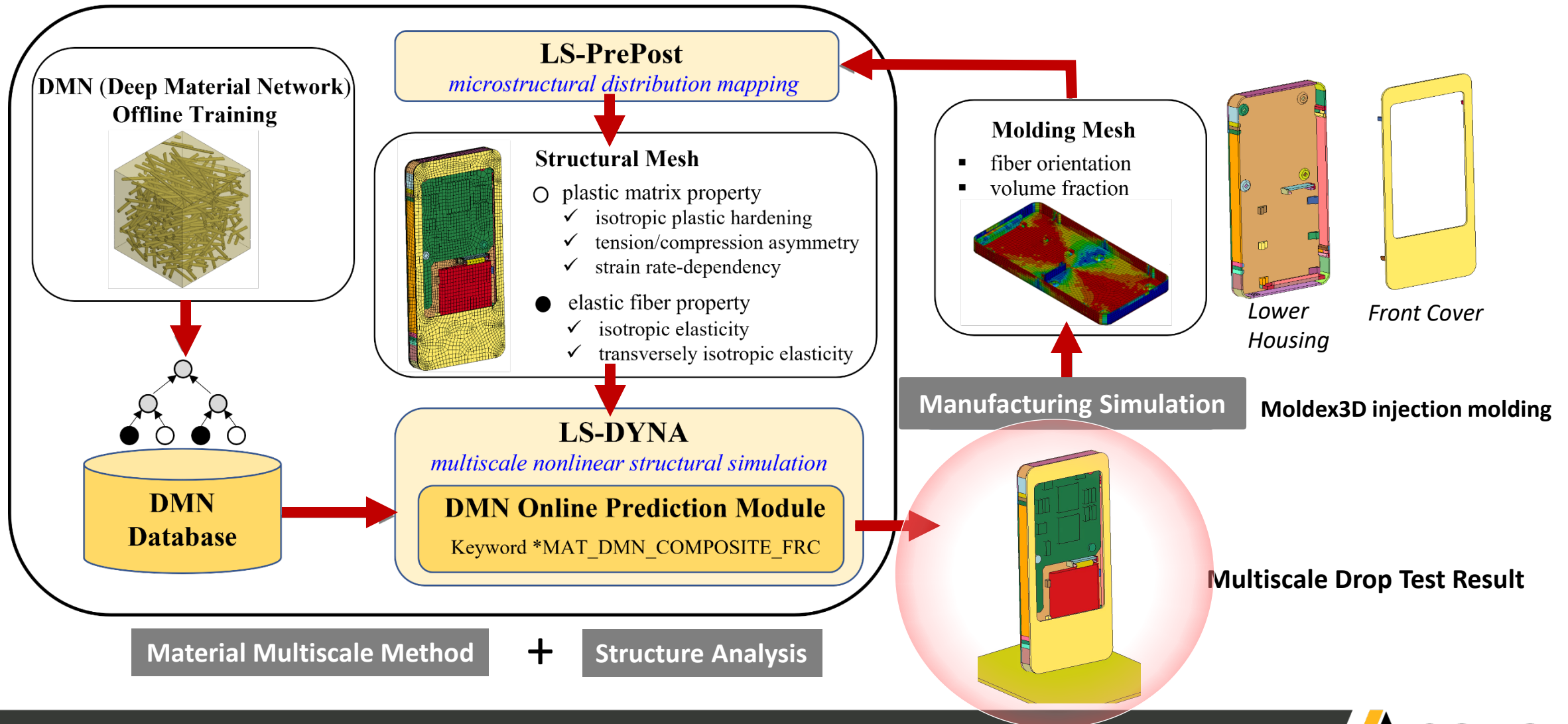
LS-DYNA DMN Performance

- $10^3 \sim 10^5$ times faster than model-based (RVE) concurrent multiscale methods in explicit dynamic analysis.
- Compared to Mori-Tanaka method, DMN can predict the complex micro-morphology and material nonlinearity.
- Six hidden layers for optimal efficiency and accuracy.



2023 R15 Deep Material Network Workflow in LS-DYNA

Workflow for LS-DYNA DMN Multiscale Analysis of Injection Molded Short Fiber Composites¹



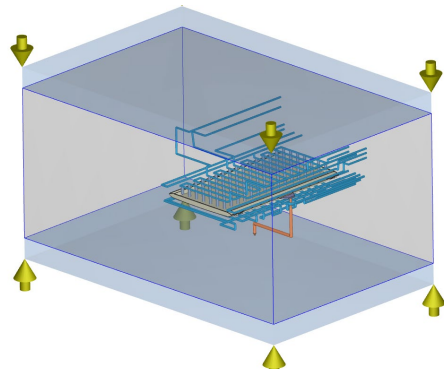
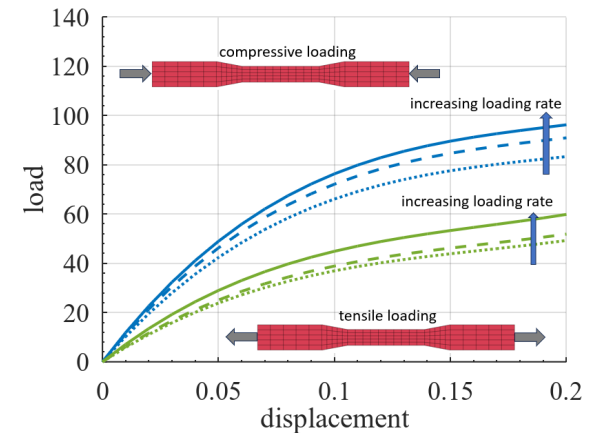
¹ LS-DYNA machine learning-based multiscale method for nonlinear modeling of short-fiber-reinforced composites, J. Eng. Mech., 149(3), 04023003, 2023.

2023 R15 New Release – Strain Rate-dependence and Residual Stress

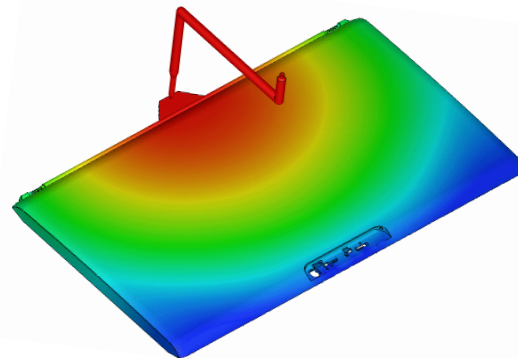
- ✓ Strain rate-dependency of the plastic matrix (resin)
- ✓ Tension/compression asymmetric properties of the plastic matrix
- ✓ Residual stress in Deep Neural Network
- ✓ New LS-PrePost interface for Solid-to-Solid/shell mapping, warpage, etc.

Ex: Drop Test of Laptop Plastic Cover

- DMN prediction of heterogeneous microstructures (position-dependent anisotropy)
- Plastic cover is a shock absorber to protect the solder balls inside chips



- Injection molding set-up

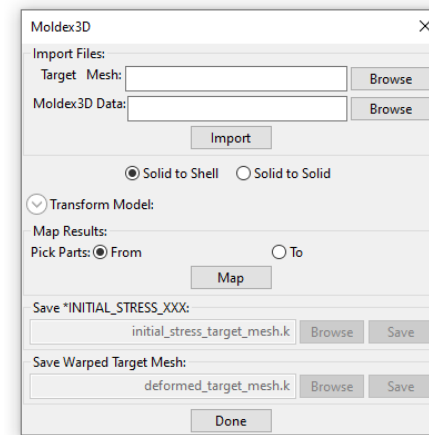


(Courtesy of Moldex3D)

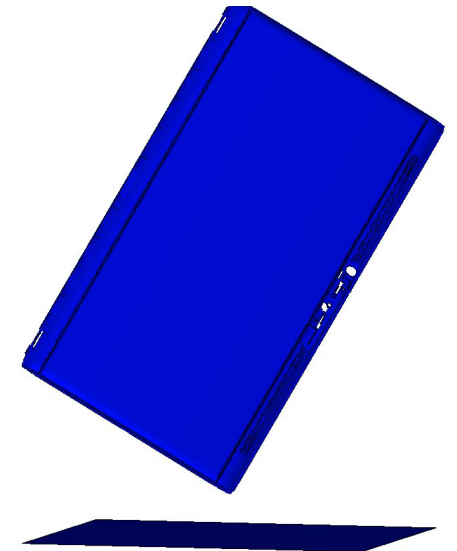
- Fluid flow in the molding process

Moldex3D

Injection Molding Simulation



LS-PrePost



LS-DYNA

Multiscale Drop Test

R15 Application - Structure Strength in Auto Composites Parts

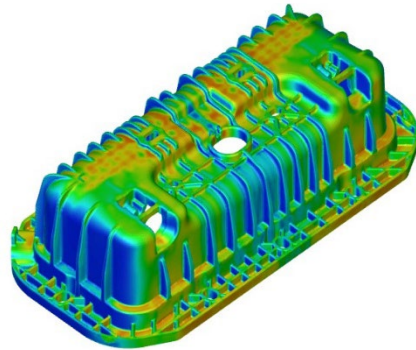
Ex. Multi-scale analysis of airbag housing

- Next goal: Anisotropic material failure of composites at different temperatures
- Airbag deployment by Control Volume
- Airbag housing modeled DMN



<https://www.autoliv.com>

- **Simulation results are validated** *under various strain rates and temperatures*
- **Critical regions are identified** *for better product design that saves lives and reduces injuries*



Moldex3D Predicted Fiber Orientation of Airbag Housing

Moldex3D

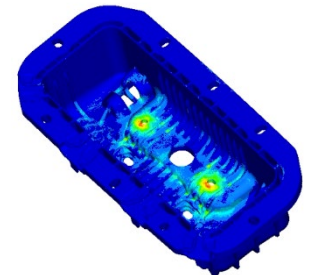
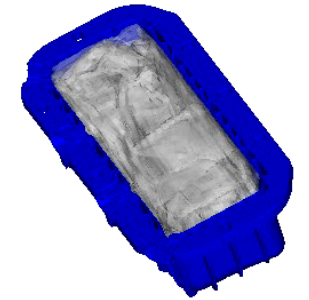
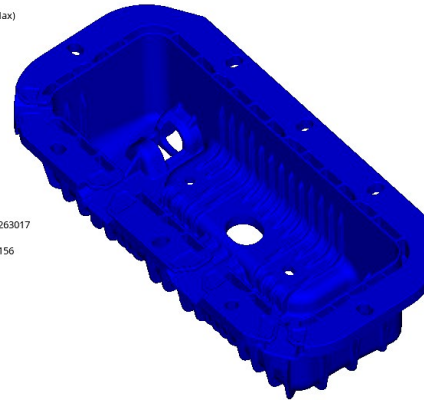
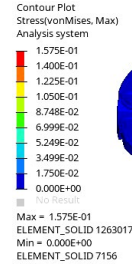
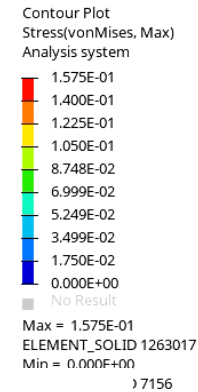
Injection Molding Simulation

LS-PrePost



LS-DYNA

Structure Simulation

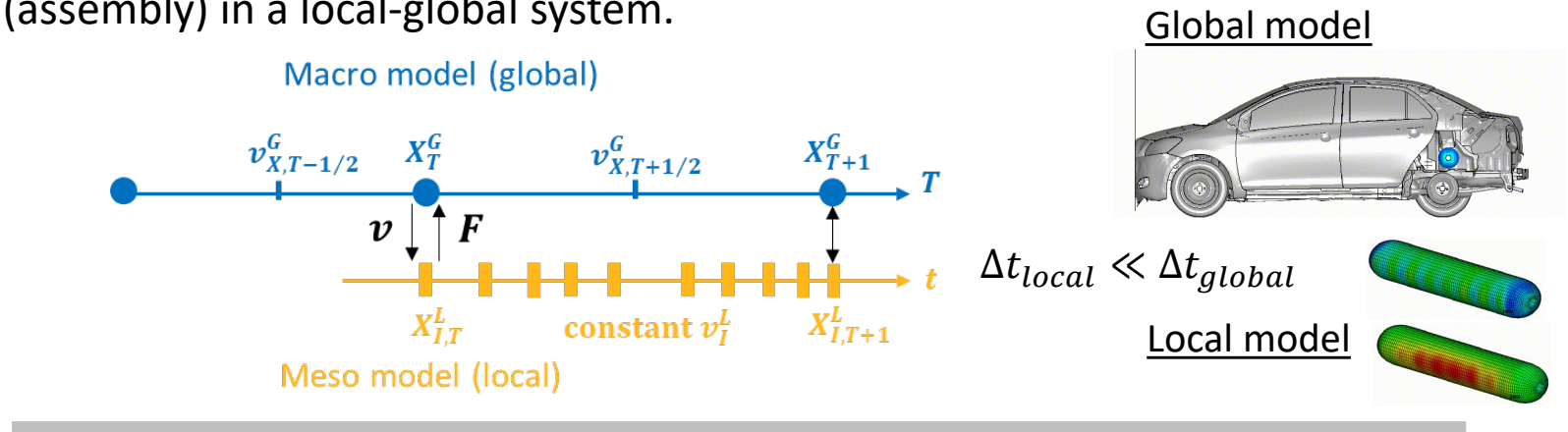


Stress Prediction

(Courtesy of Autoliv)

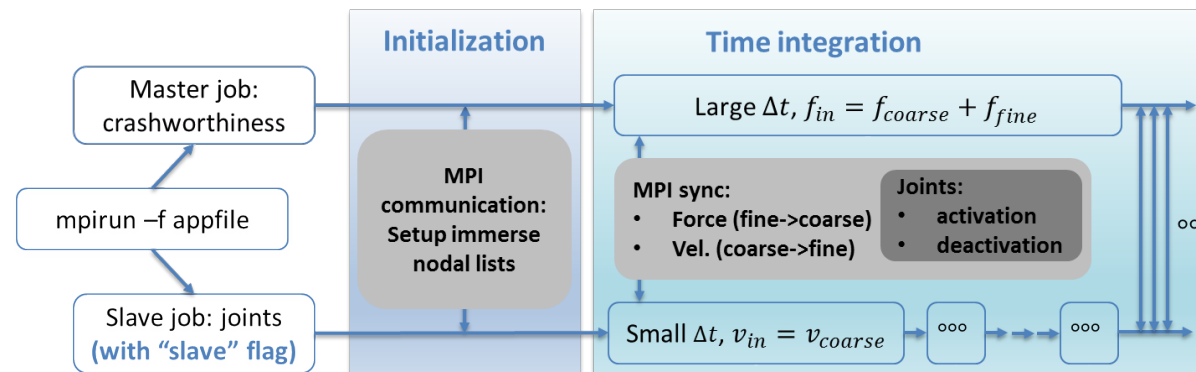
Two-scale Co-simulation¹

- Assemble the components to the system for structural analysis.
- Two-scale Co-simulation is a joint simulation of two coupled standalone solvers for component analysis.
- It improves the efficiency of explicit dynamic analysis when local-scale mesh size (component) is much smaller than global-scale mesh size (assembly) in a local-global system.



- Synchronized time steps

- MPI communication
Tie contact, immersion, etc.

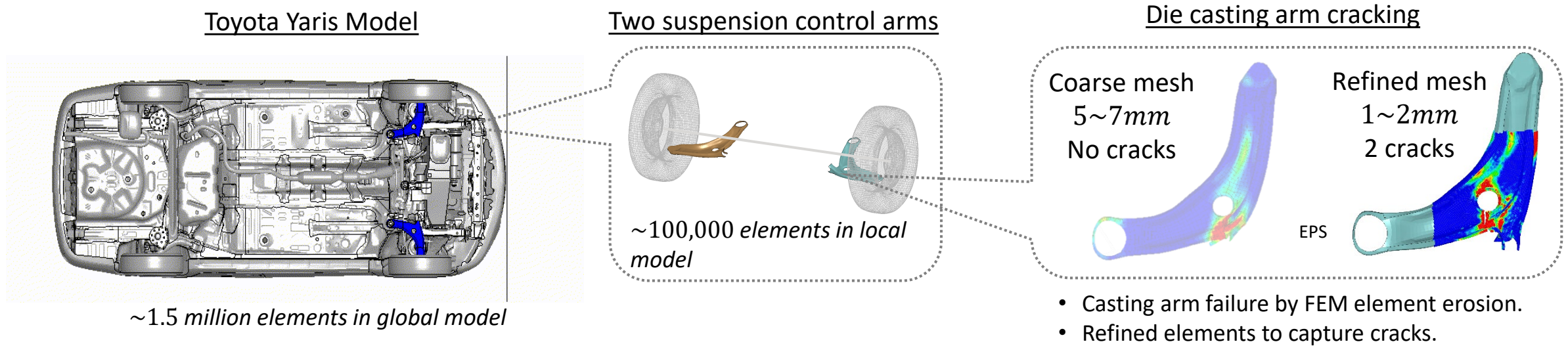


¹ Int. J. Multiscale Comp. Engrg., 18 (4), 455-476, 2020.

2023 R15 New Release – Two-way Co-simulation

- ✓ Main feature in R15 release: **a two-way co-simulation (*INCLUDE_COSIM)** based on tie constraint
- ✓ Easy setup two-scale co-simulation using **new command line flag *nmsp*** (number of MPI processes for local model)

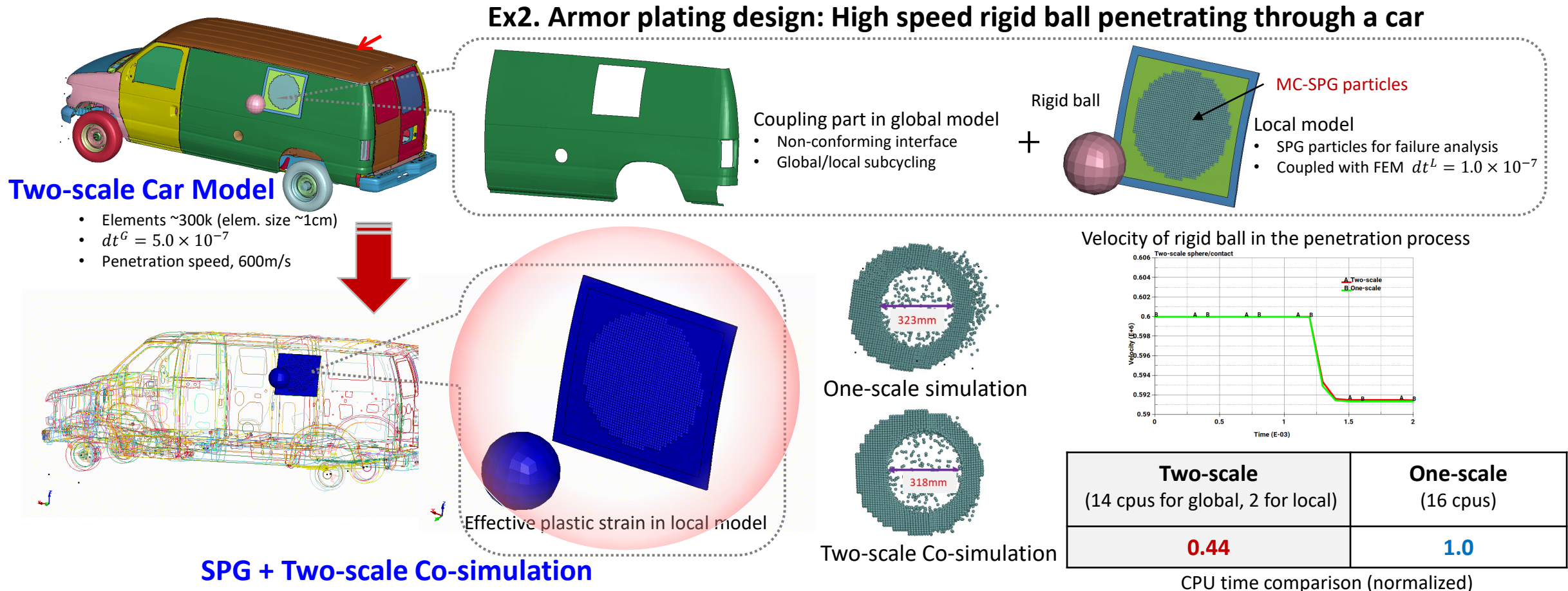
Ex1. Simulate failure of two local casting parts in a global car crash model



A full car with two coarsen casting parts	A full car with two refined casting parts	A full car in global with two refined casting parts in local
$dt = 1.0 \times 10^{-6}$	$dt = 1.0 \times 10^{-7}$ (mass scaling)	$dt^G = 1.0 \times 10^{-6}$; $dt^L = 1.0 \times 10^{-7}$ (mass scaling)
2.3 hours (24 CPUs) Single scale simulation	26 hours (24 CPUs) Single scale simulation	4 hours (global 24 CPUs dt^G + local 8 CPUs dt^L) Two-scale Co-simulation

Application – Armor plating analysis

- ✓ A **solid-in-shell immersion technique** was implemented for easy component modeling in an assembled system.
- ✓ Ex2: Component study – failure of metal armor plating (modeled by SPG with $\Delta t = 1 \times 10^{-7}$) in a full-car model (with $\Delta t = 5 \times 10^{-7}$).



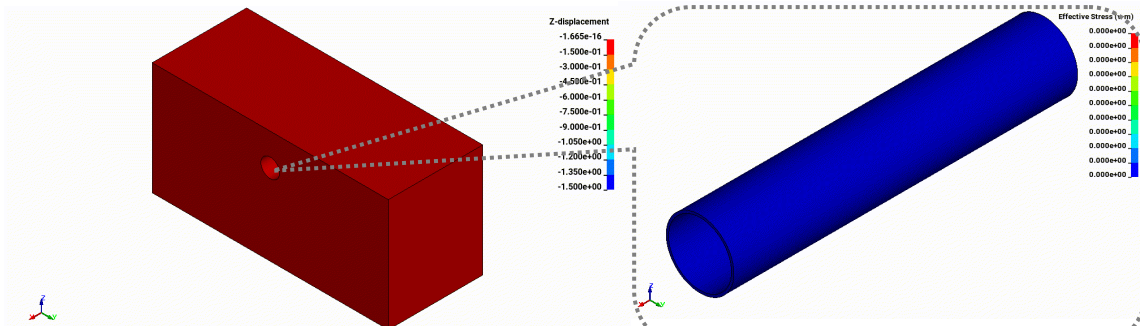
Application – Soil-Tunnel Interaction

- ✓ Soil-tunnel interaction under gravity
- ✓ Applied to Sewer, Metro, Rail/Road tunnels



<https://www.robbinstbm.com/>

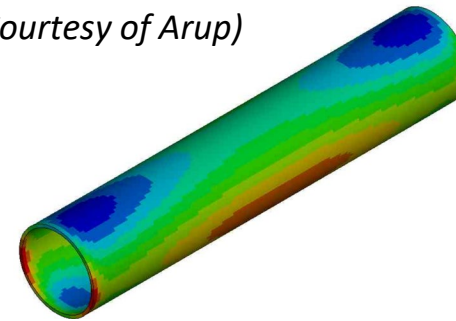
- Time step ratio 1:16 for local and global model



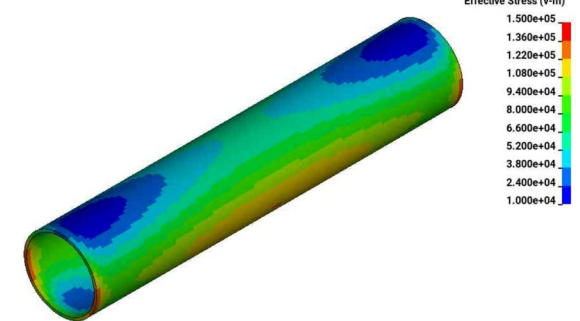
Displacement in global model
(~ 2M elements)

Von-Mises stress in local model
(~ 10k elements)

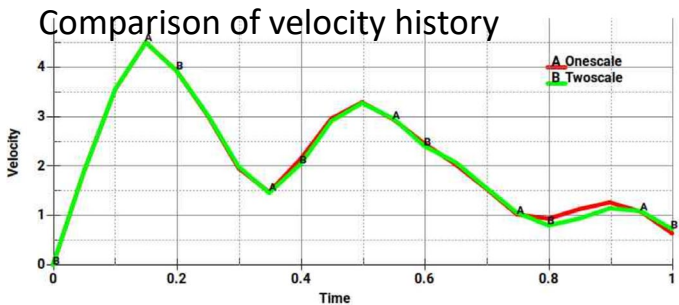
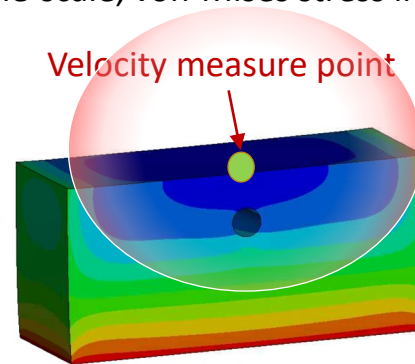
(Courtesy of Arup)



One-scale, von-Mises stress in tunnel



Two-scale, von-mises stress in tunnel



Two-scale (14 cpus for global, 2 for local)	One-scale (16 cpus)
Normalized 0.1 (39 mins)	1.0 (6 hrs 23 mins)



1. Methods for Manufacturing Simulation

1.1 **Incompressible Smoothed Particle Galerkin (ISPG) Method** for Adhesive Fluid Mechanics Analysis

1.2 **Smoothed Particle Galerkin (SPG) Method** for Solid Mechanics Analysis

2. Methods for Multiscale Simulation

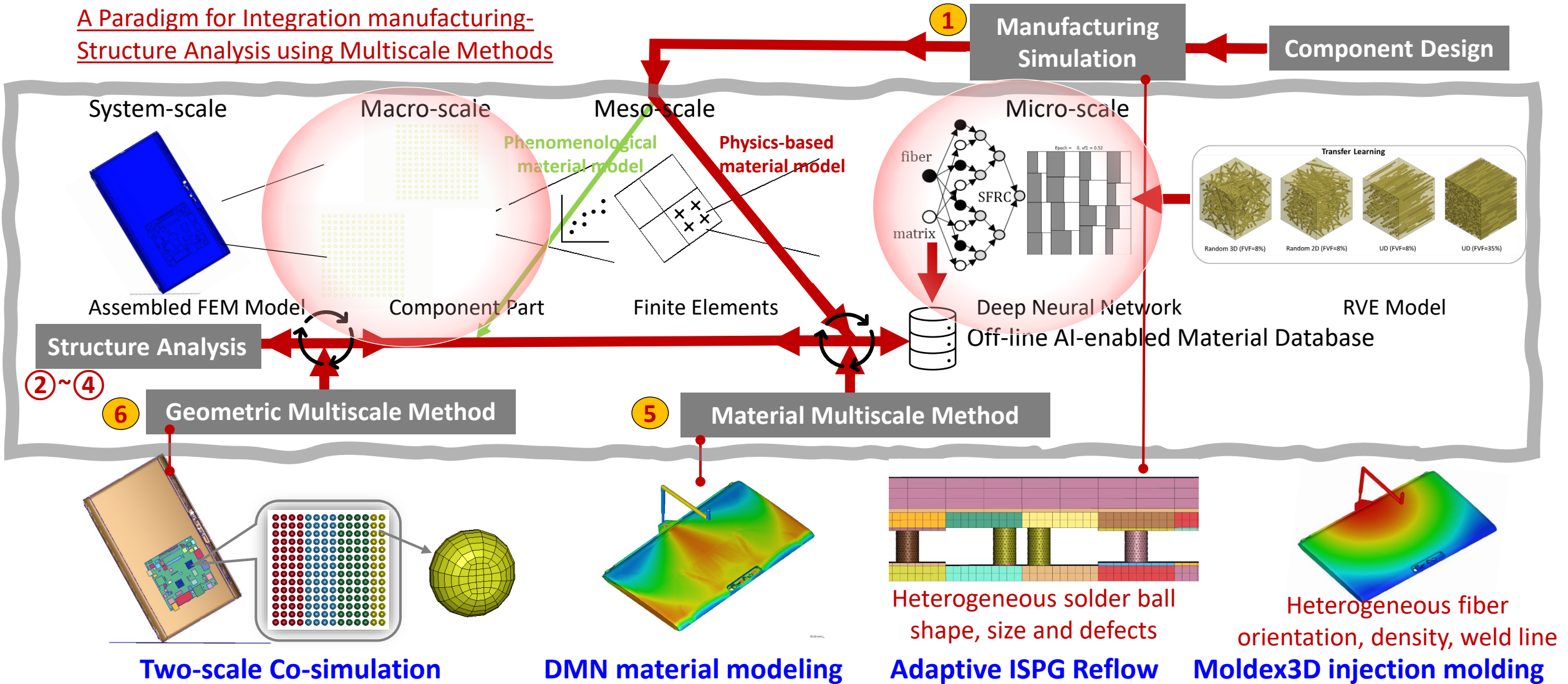
2.1 **Deep Material Network (DMN)** for Component Material Characterization

2.2 **Two-scale Co-simulation** for Assembly Structural Analysis

3. A Paradigm Integrating Structural Analysis with Manufacturing Information Using Multiscale Methods

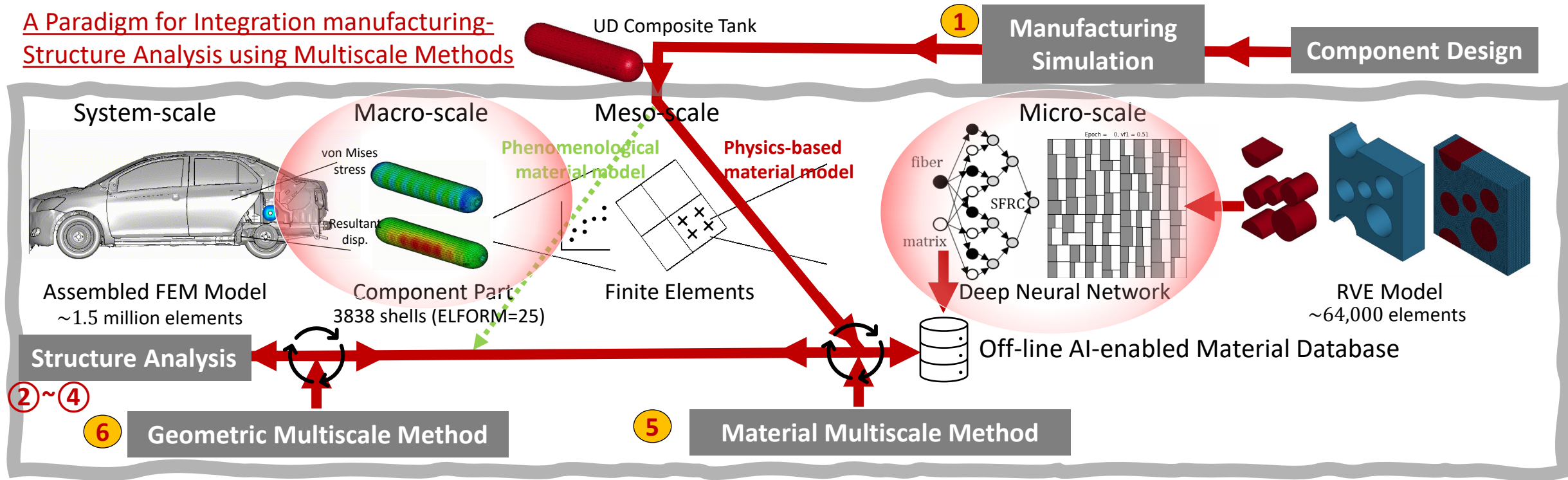
Ex. 1 – Solder balls reliability in a laptop drop test simulation using LS-DYNA R15

A Paradigm for Integration manufacturing-
Structure Analysis using Multiscale Methods



Ex. 2 - A composite component analysis in a full-vehicle crash test using LS-DYNA R15

A Paradigm for Integration manufacturing-Structure Analysis using Multiscale Methods



CPU time (single precision explicit dynamics MPP)

*Original crash model

2.3 hours (24 CPUs) ($dt = 1.0 \times 10^{-6}$)

*Concurrent for RVE-composite tank

~1.5 years (24 CPUs)

*AI for RVE-composite tank

~10 hours (24 CPUs) ($dt = 3.3 \times 10^{-7}$)

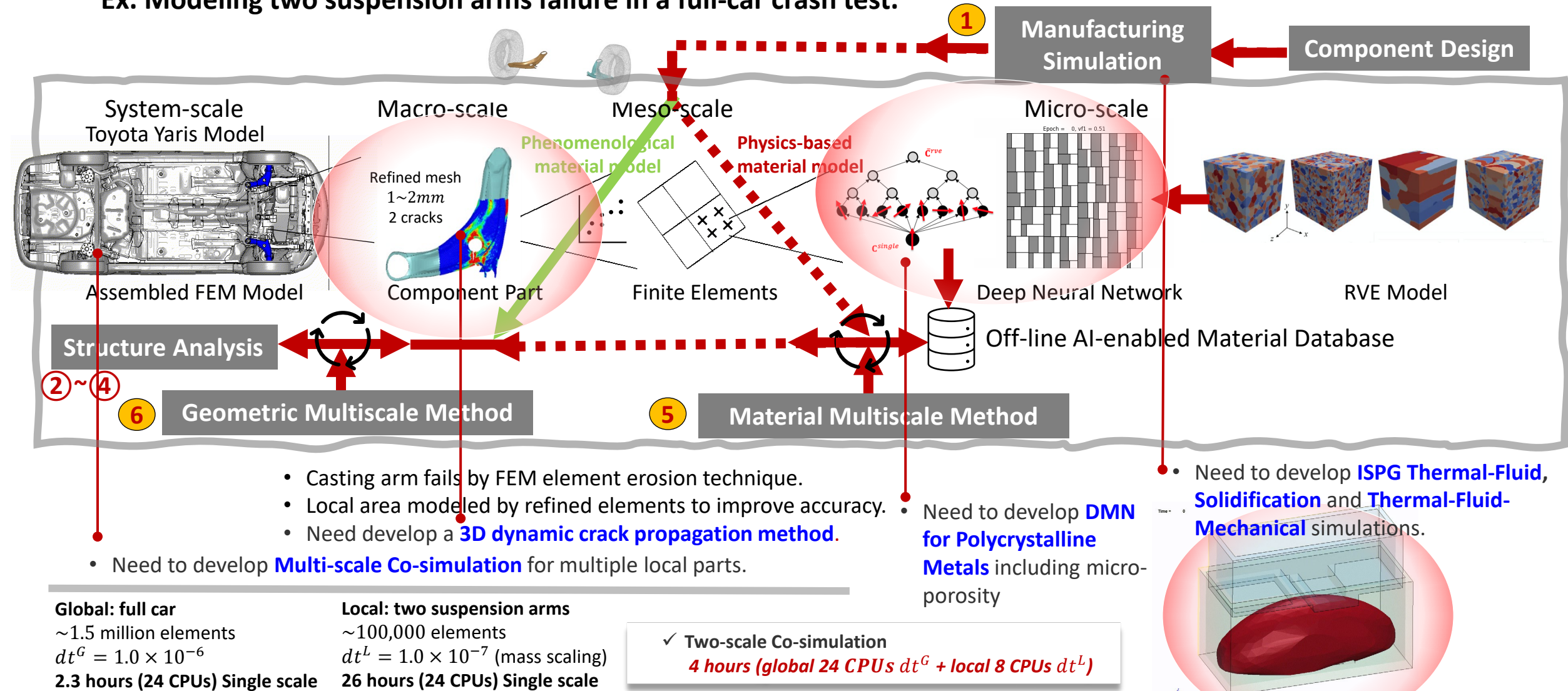
*AI + Two-scale Co-simulation

($dt^G = 1.0 \times 10^{-6}$)
3.4 hours (global 24 + local 8 CPUs) ($dt^L = 3.3 \times 10^{-7}$)

Goal: 2.6 hours (global 24 + local 8 CPUs)

On-going Development for Polycrystalline Metals

Ex. Modeling two suspension arms failure in a full-car crash test.



Conclusion

1. 2023 LS-DYNA developments of several manufacturing simulation methods and multiscale methods were updated.
2. We demonstrated how to predict manufacturing, assembly, and system performance using those methods.
3. The ultimate goal is to accelerate structure design and analysis driving product innovation and digitization for your industry.

Thank you!